

Seeing Through Augmented Reality

Steven Feiner



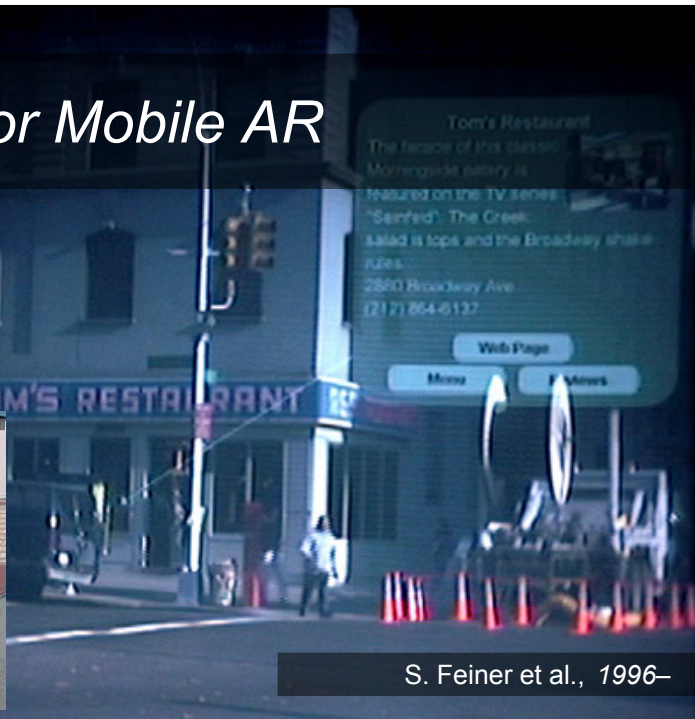
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New York, NY 10027

Supported in part by NSF, ONR, Raytheon, USMC, and gifts from Microsoft, Nokia, VTT, Vuzix, Canon

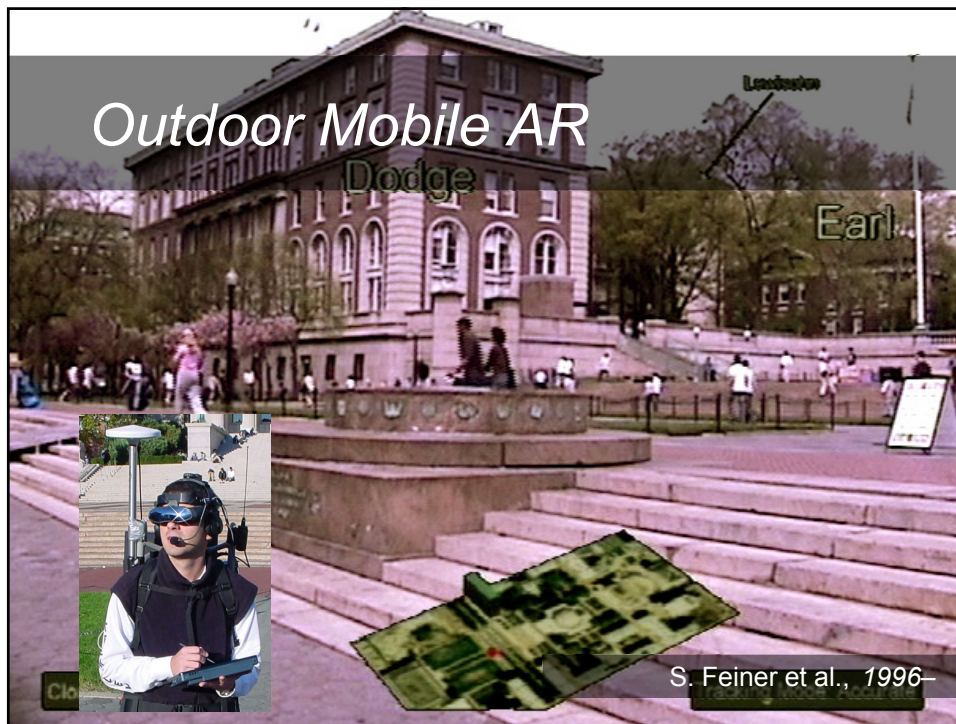
Qualcomm Augmented Reality Lecture Series
TU Wien, Vienna, Austria, August 22, 2013

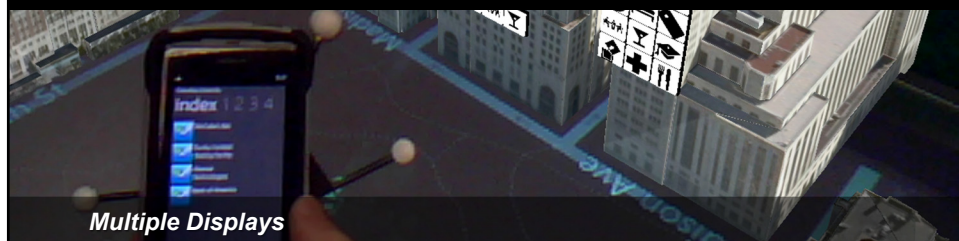


Outdoor Mobile AR

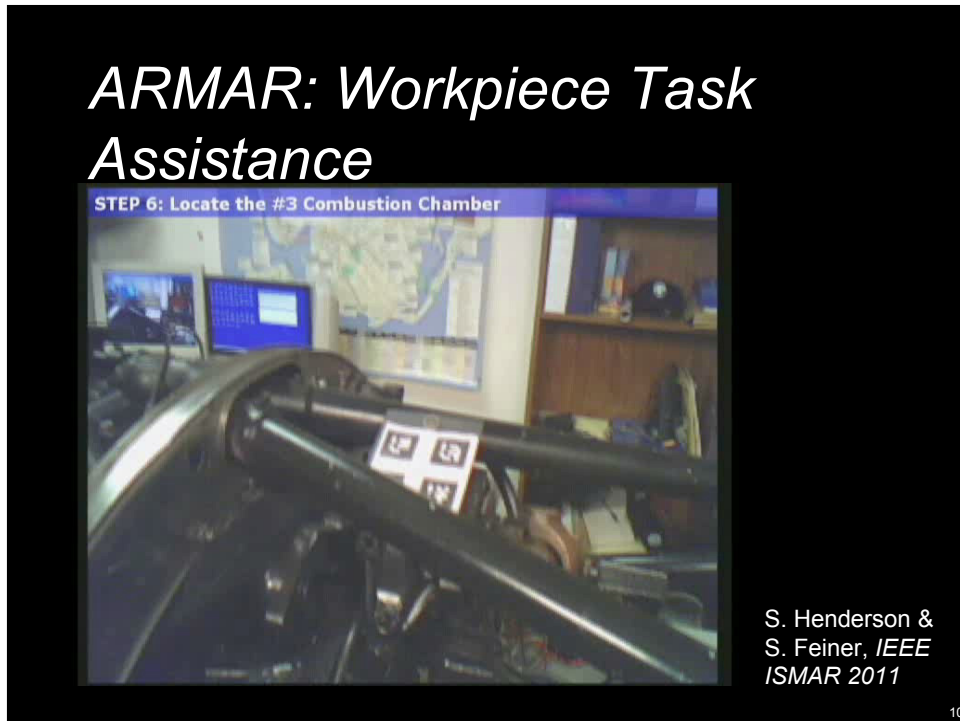


S. Feiner et al., 1996–

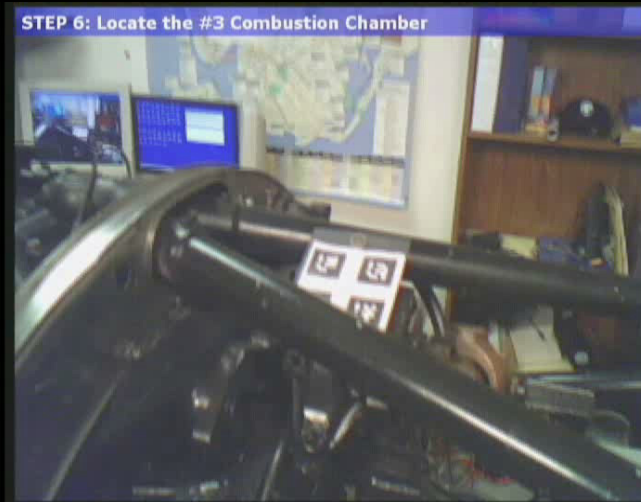








ARMAR: Workpiece Task Assistance



S. Henderson &
S. Feiner, *IEEE*
ISMAR 2011

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ARMAR: Workpiece Task Assistance Study

- Is AR better than conventional (computer) documentation?
 - Assemble aircraft engine combustion chamber
 - Select bottom and top, align correctly, pin



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ARMAR: Workpiece Task Assistance Study

- Within-subject
- Counterbalanced start condition: AR, LCD
- Randomized chamber bottom/top, pairs of holes



AR Condition



LCD Condition

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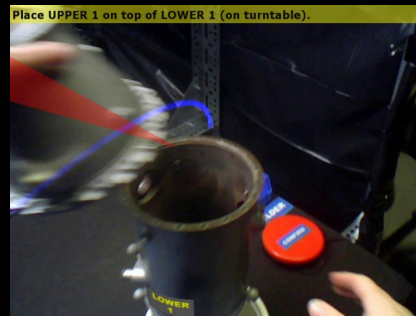
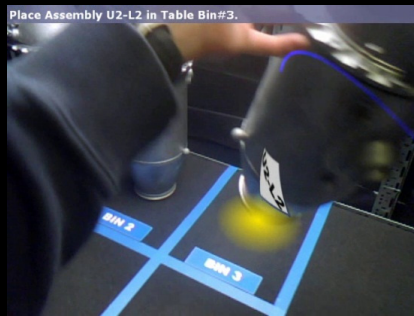
ARMAR: Workpiece Task Assistance Study: AR Condition



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ARMAR: Workpiece Task Assistance Study: AR Condition

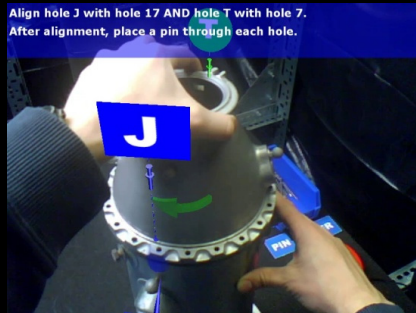
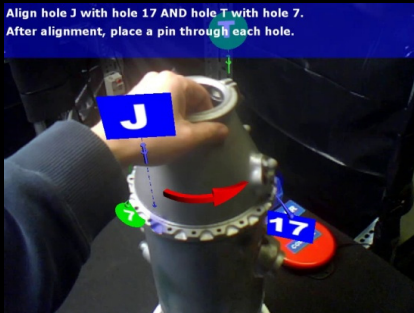
- Source/destination bin highlights
- Motion paths



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ARMAR: Workpiece Task Assistance Study: AR Condition

- Prescriptive 3D arrows
- Billboarded labels



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ARMAR: Workpiece Task Assistance Study: AR Condition

- Alignment highlights



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ARMAR: Workpiece Task Assistance Study: AR Condition



Optical
See-Through
HWD

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ARMAR: Workpiece Task Assistance Study: LCD Condition



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ARMAR: Workpiece Task Assistance Study: Experiment Design

- Formal study
(22 participants, 6 female, ages 18–44 [avg 26.3], CU affiliates)
- Introduction + stereo vision test + 2 conditions × (instructional video + practice block + 14 trials) + post hoc questionnaire



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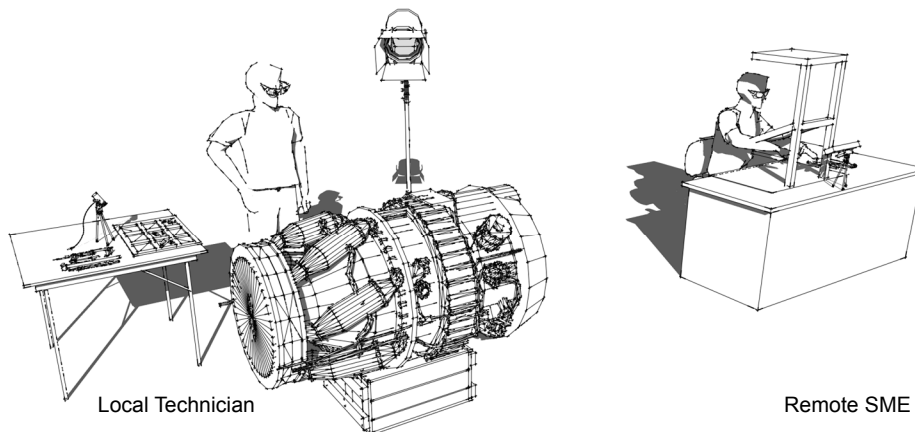
ARMAR: Workpiece Task Assistance Study: Results ($\alpha = .05$)

- H1: AR faster for alignment/pinning (24.2s vs. 45.5s)
- H2: AR more accurate [aligned within .5 hole width] (95% vs. 62%)
- H3: AR preferred [ranked higher in questionnaire] (20 of 22)
- H4: AR more intuitive [ranked higher in questionnaire] (19 of 22)



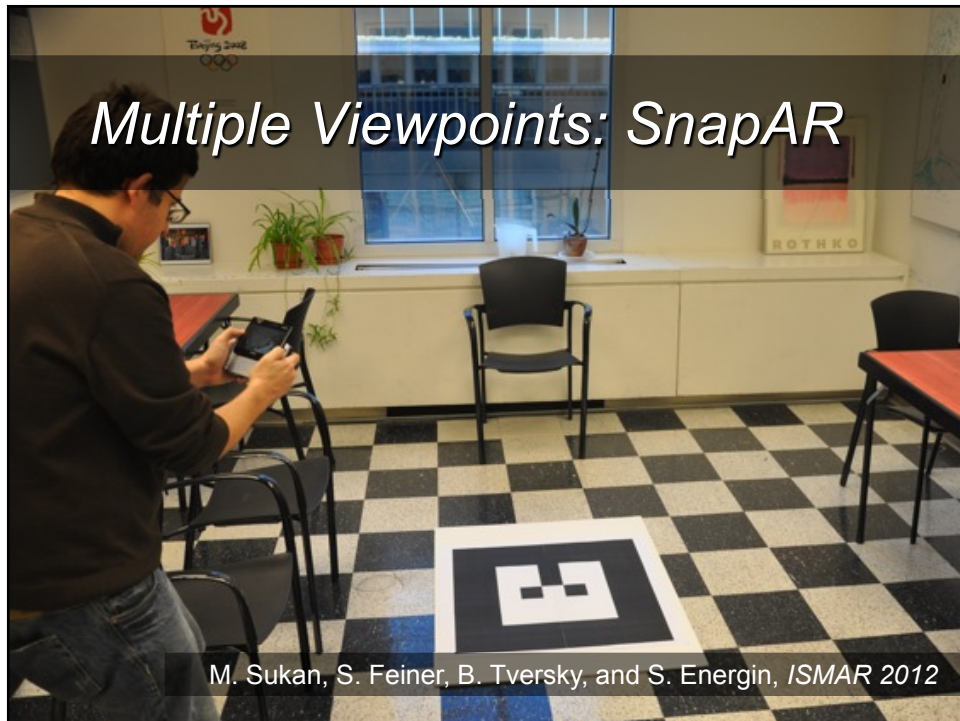
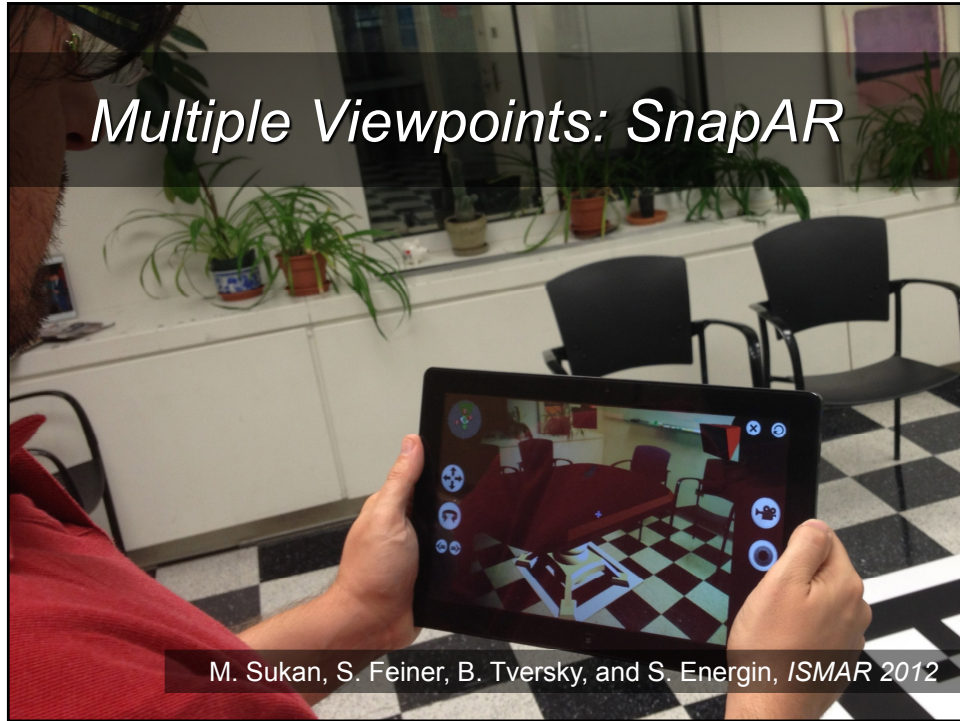
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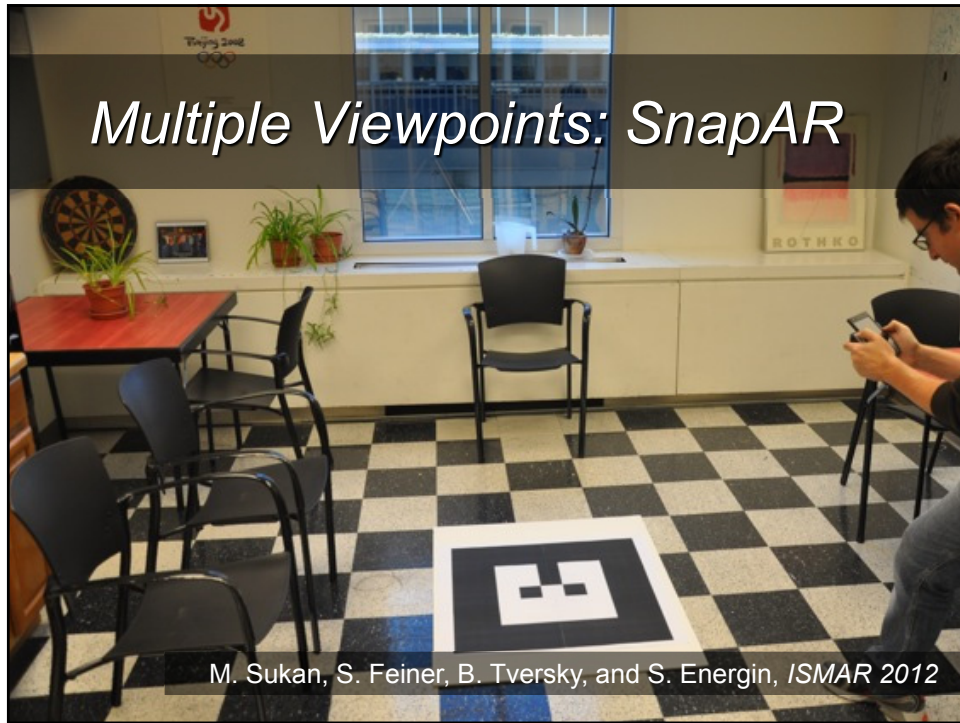
Remote Localization and Referencing in Collaborative AR

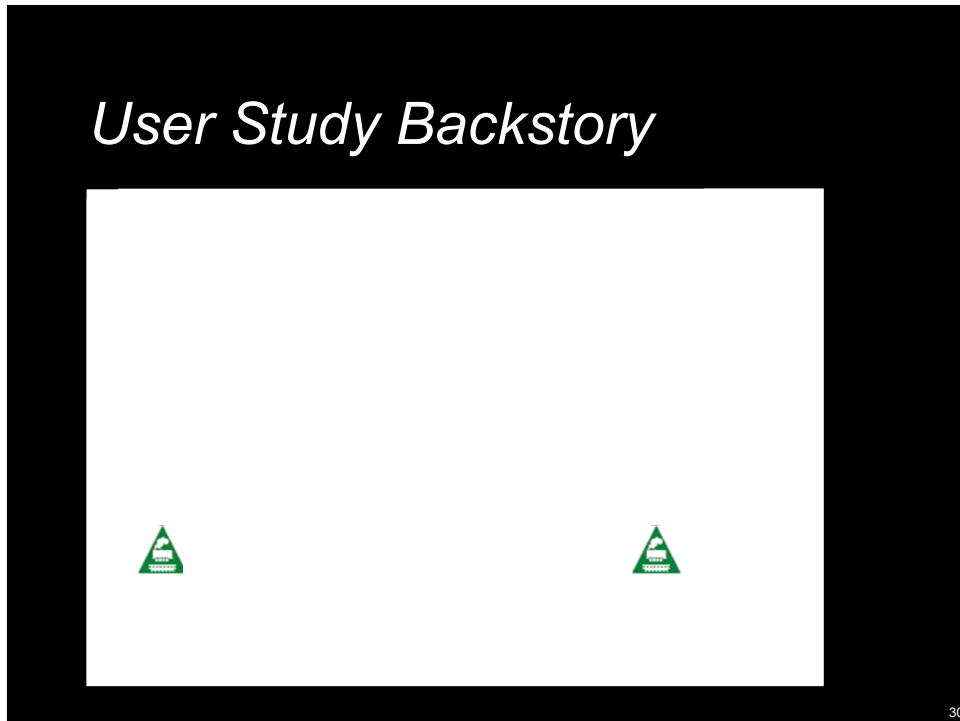
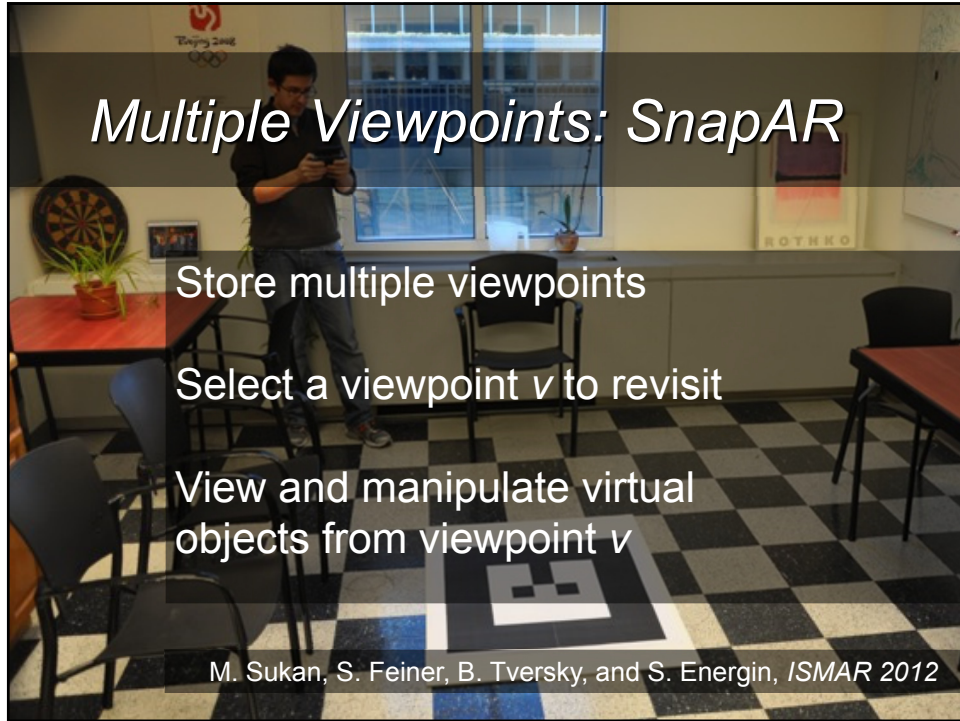


O. Oda, M. Sukan, S. Feiner, and B. Tversky, *3DUI 2013*







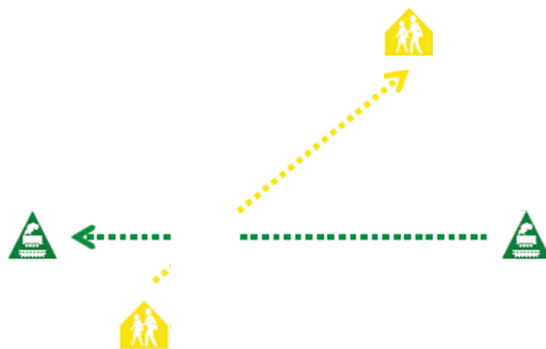


User Study Backstory



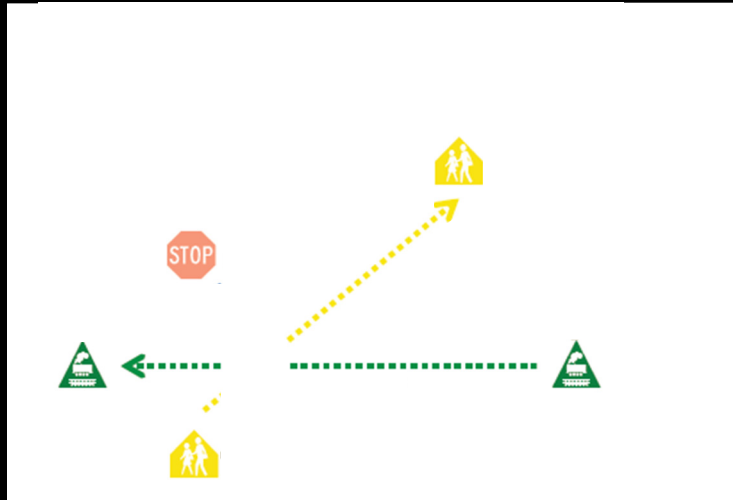
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User Study Backstory



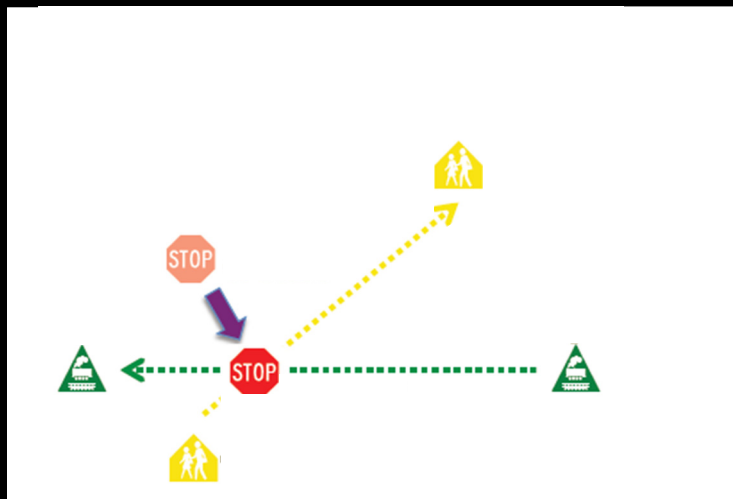
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User Study Backstory



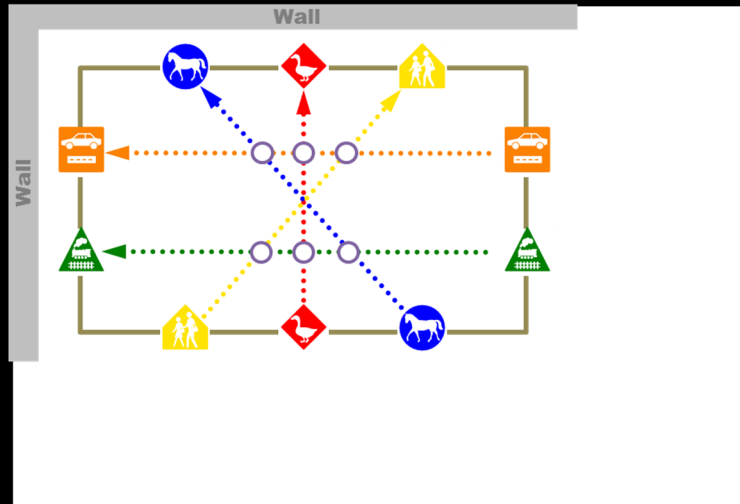
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User Study Backstory



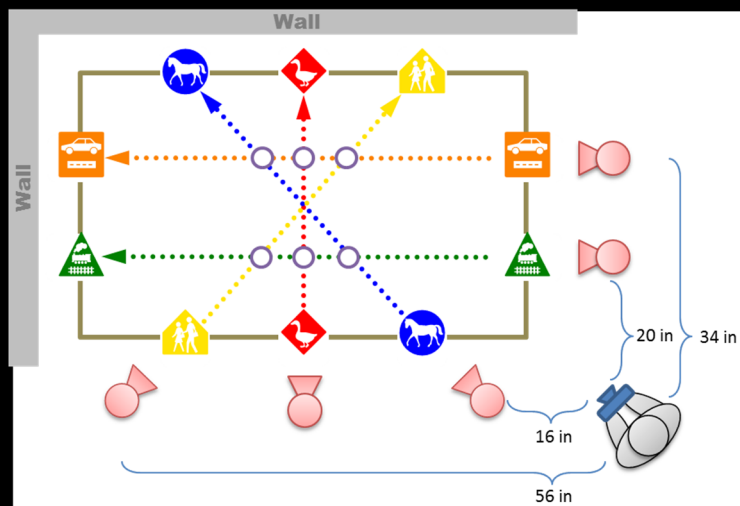
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User Study Setup

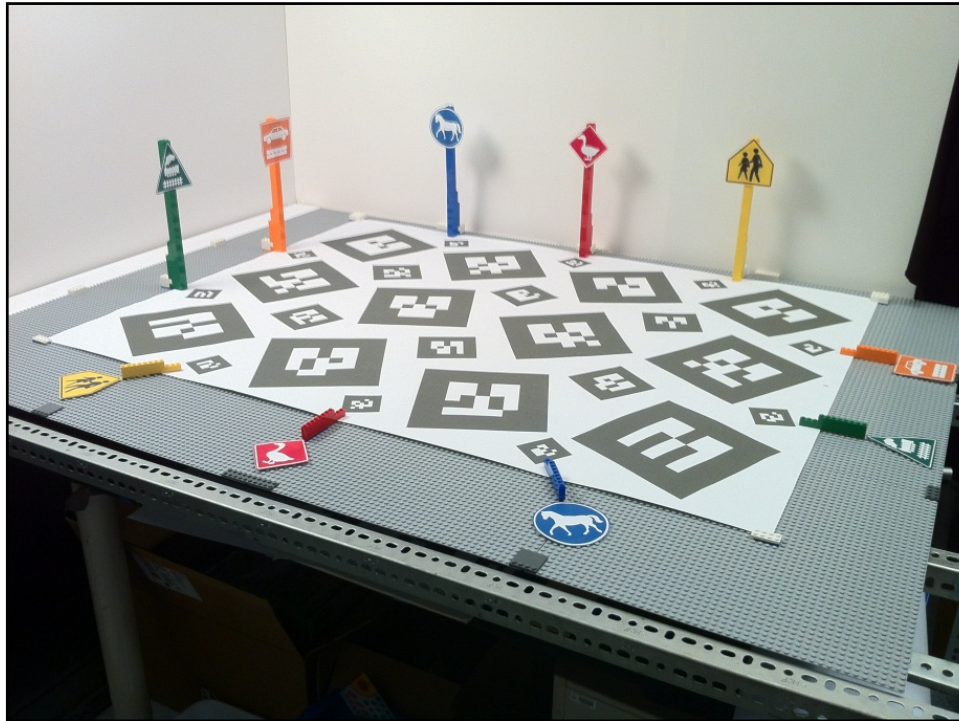


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User Study Setup



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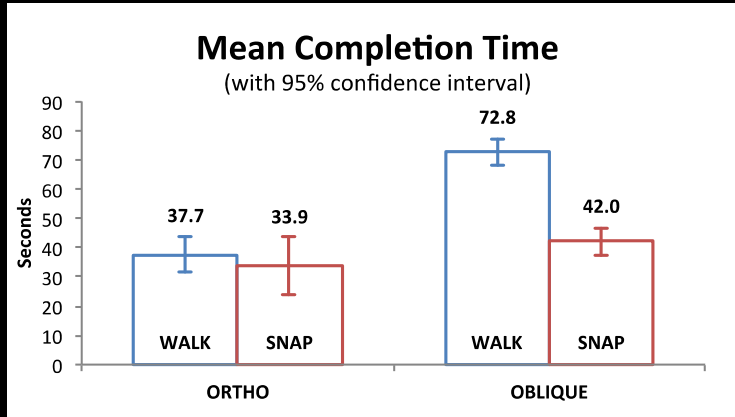


User Study Design

- Travel condition: SNAP, WALK
- Task difficulty: ORTHO, OBLIQUE
- 21 participants (CU affiliates, 8 female, age 19–40, $\bar{X} = 23.6$)
- Within-subject

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User Study Results



- SNAP significantly faster overall, esp. for OBLIQUE (# revisits higher)

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User Study Results

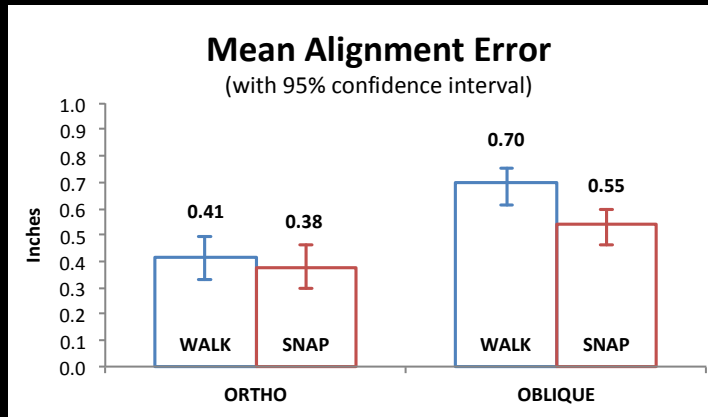
$$t_{\text{Capture}} < \underbrace{(t_{\text{Walk}} - t_{\text{Switch}})}_{\text{Saved time}} \times n_{\text{revisits}}$$

$$n_{\text{revisits}} > \frac{t_{\text{Capture}}}{t_{\text{Walk}} - t_{\text{Switch}}} \rightarrow \text{Time saved overall}$$

- $t_{\text{Capture}} \approx 54$ secs for 5 snapshots
- $t_{\text{Walk}} - t_{\text{Switch}} \approx 30$ secs for OBLIQUE, so faster after second OBLIQUE trial
- Time savings scale with usage/walking time

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User Study Results



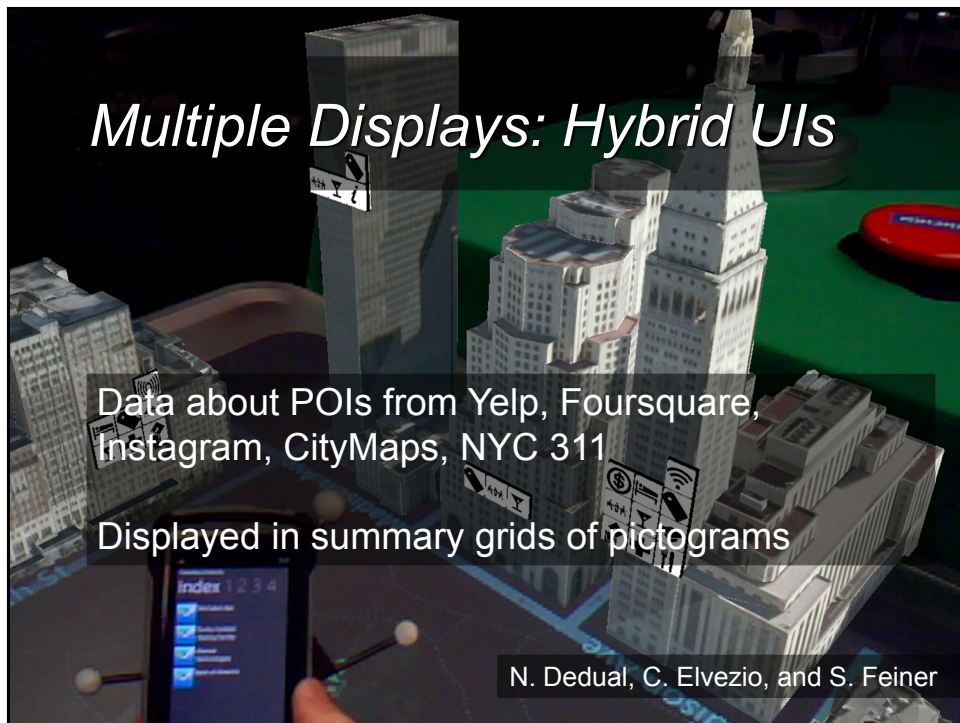
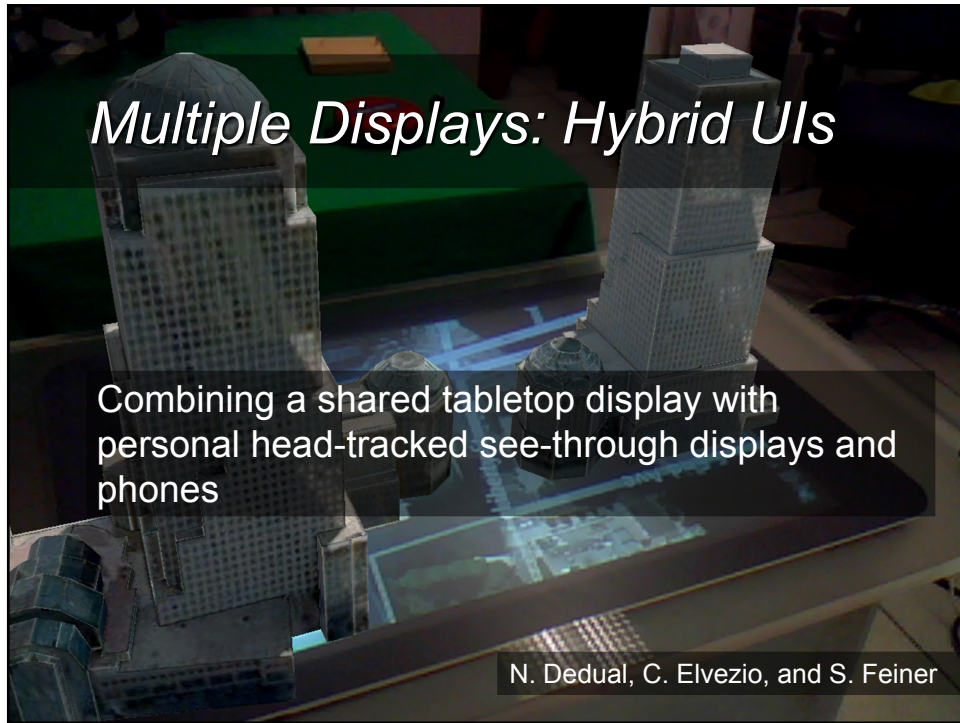
- SNAP significantly more accurate overall, esp. for OBLIQUE (more difficult)

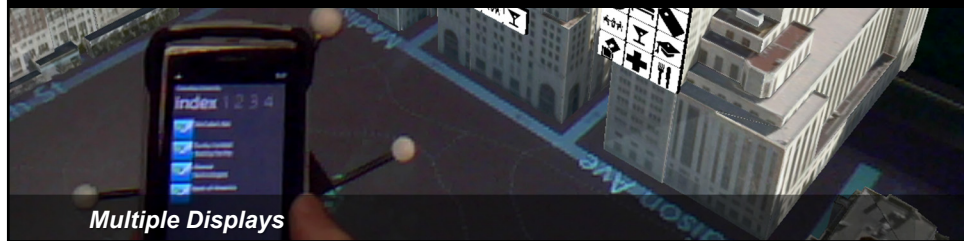
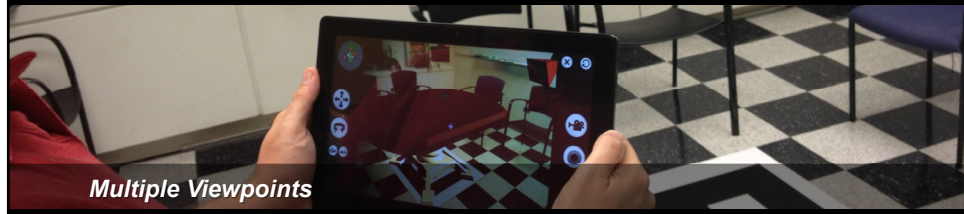
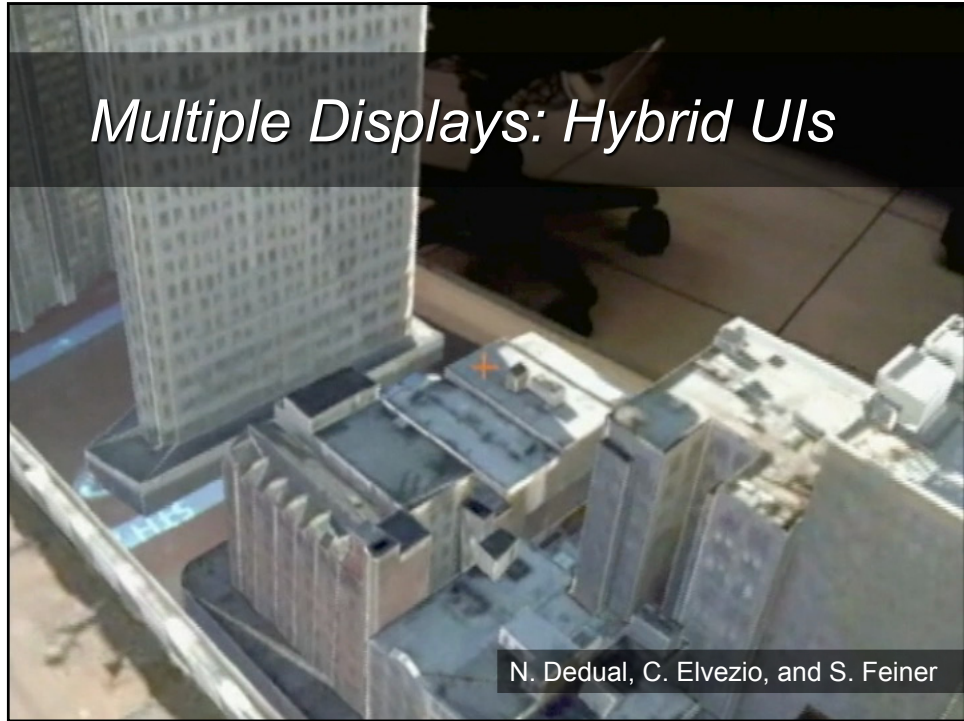
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User Study Results

- Questionnaire
 - 19 of 21 preferred SNAP over WALK
 - 17 of 21 rated SNAP less demanding than WALK

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STEP 2: Loosen #3 Fuel Line Clamp with the screwdriver

Once clamp is loose, disconnect the #3 Combustion Chamber Fuel Line

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Any opinions, findings and conclusions **on text** recommendations expressed in this material are those of the author(s) and do not necessarily reflect the views of the National Science Foundation



See you at *ISMAR 2013*, Oct 1-4, 2013
Adelaide, Australia <http://ismar.vgtc.org>