Reconstruction and recognition for realistic augmented reality

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The ACVT

- Australia's largest Computer Vision research group
- Working in
 - Machine Learning
 - 5 CVPR'11 papers, 2 ICCV'11, JMLR, ...
 - □ Parameter Estimation
 - CVPR'10 Best Paper Prize, CVPR'11, ICCV'11, PAMI...
 - □ Video Surveillance
 - ICCV'11, 2 start-ups, ...
 - □ Structure from X
 - PAMI, JMIV, Siggraph'07, ToG, ...





There is Demand for 3D



Even kids want 3D



UCC made the Web

- Blogs, Wikis, Social networking sites, Advertising, Fanfiction, News Sites, Trip planners, Mobile Photos & Videos, Customer review sites, Forums, Experience and photo sharing sites, Audio, Video games, Maps and location systems and such, but more
- Associated Content, Atom.com, BatchBuzz.com, Brickfish, CreateDebate, Dailymotion, Deviant Art, Demotix, Digg, eBay, Eventful, Fark, Epinions, Facebook, Filemobile, Flickr, Forelinksters, Friends Reunited, GiantBomb, Helium.com, HubPages, InfoBarrel, iStockphoto, Justin.tv, JayCut, Mahalo, Metacafe, Mouthshut.com, MySpace, Newgrounds, Orkut, OpenStreetMap, Picasa, Photobucket, PhoneZoo, Revver, Scribd, Second Life, Shutterstock, Shvoong, Skyrock, Squidoo, TripAdvisor, The Politicus, TypePad, Twitter, Urban Dictionary, Veoh, Vimeo, Widgetbox, Wigix, Wikia, WikiMapia, Wikinvest, Wikipedia, Wix.com, WordPress, Yelp, YouTube, YoYoGames, Zooppa

Where is the 3D AR?



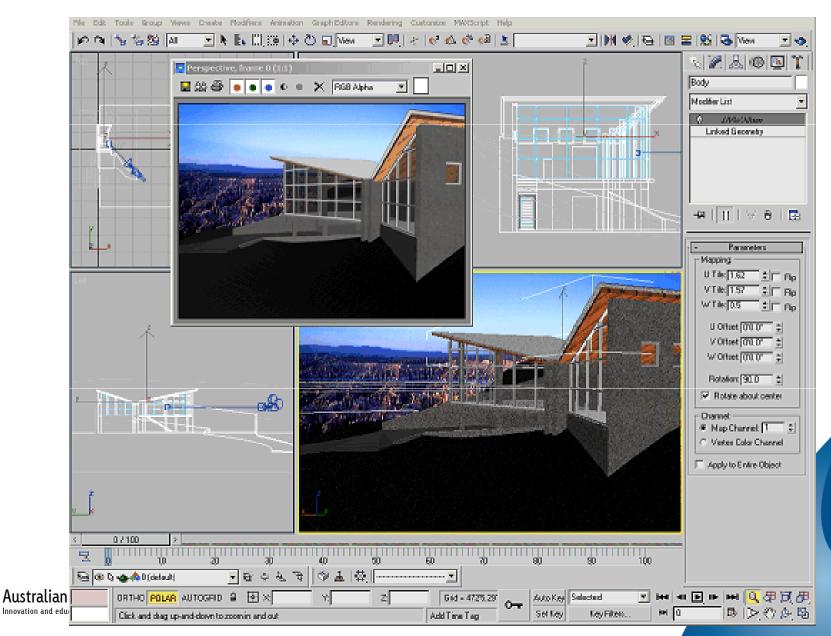


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The Problem



3D Modelling is Hard





The Solution

- Images are everywhere
 - □ A good source of 3D information
 - Easily accessible
 - □ They're typically captured anyway
 - Almost everything has a camera attached
 - Humans are very good at interpreting them

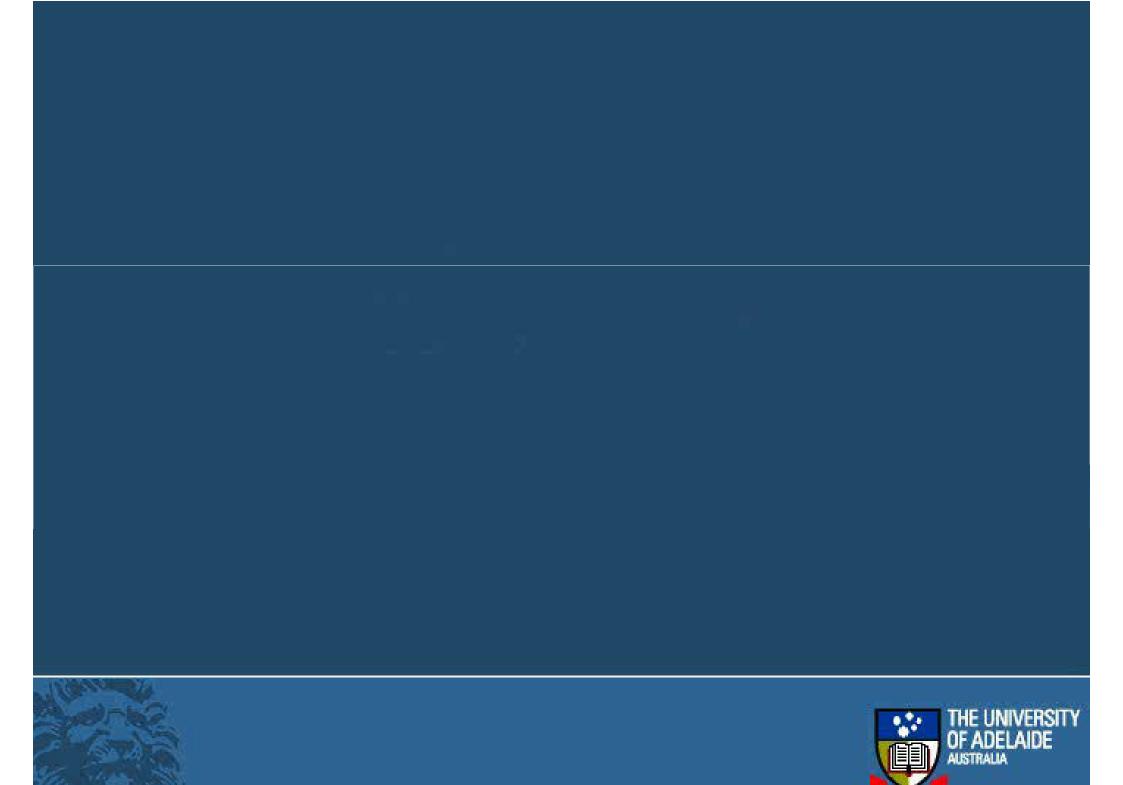




Image-based 3D UCC

- The image is the interface
 - □ People can't help but see images in 3D
 - Most image sets embody 3D
- Powerful way to model real objects
 - □ Varying levels of interaction
 - □ Varying types of models
- Helps even in modelling imaginary objects



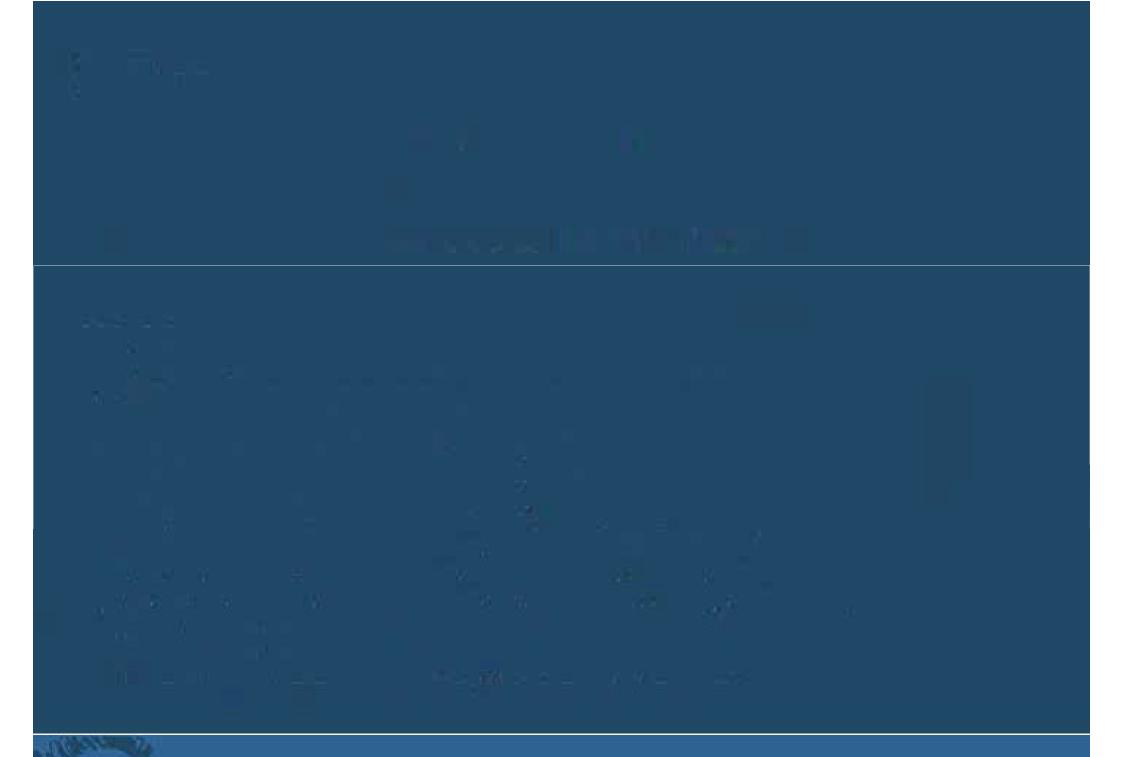


A Point Cloud is not Shape

- Point clouds are not a useful model of scene shape
 - □ Too much information
 - More than 3 points to a plane
 - □ Too little information

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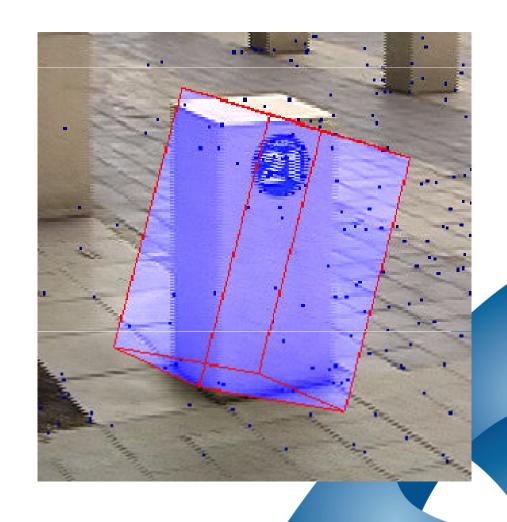
- No object parameters, boundaries, relationships, textures, ...
- □ But they do contain critical shape information
- We want to exploit the point cloud and the image set to get exactly the shape information we require





Relationships

- Specify constraints on object parameters
 - Allow use of sparser point clouds
- Inform interactions
 - Otherwise higher dimensional actions can be reduced to 2D
 - □ Increase modelling power
- Adjacent is the key relationship



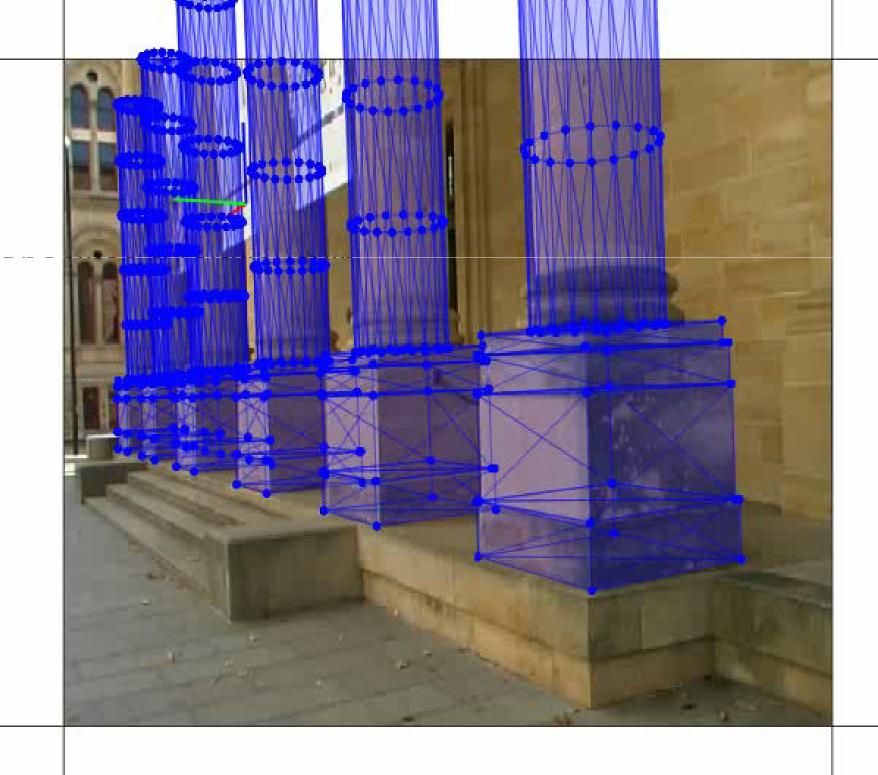


Optimisation

- Graph-based
 - □ One node per object
 - One observation per object node
 - □ Three likelihoods
 - 2D, 3D and User
 - One node per relationship
 - Links between relationship node and nodes of objects related







Optimisation

- Three likelihoods per object node
 - □3D likelihood is robust
 - □ 2D likelihood is fragile, but locally accurate
 - User likelihood is globally robust, but locally inaccurate
- One likelihood per relationship node
 - Reflects degree to which relationship fulfilled
- No loops in the graph



Optimisation

2D likelihood

$$\mathcal{J}_2(\{I_k\}, \mathbf{C}) = f_2 \sum_k \sum_{\mu} \arg \max_{\nu} \exp(-\frac{\nu^2}{s}) I'_k(n_{\mu\nu})^2$$

3D likelihood

$$\mathcal{J}_3(\{\mathbf{P}_i\},\mathbf{C}) = f_3 \sum_i d(\mathbf{P}_i,\mathbf{C})^2$$

User likelihood

$$\mathcal{J}_U(\mathbf{a}, \mathbf{C}) = f_U \sum_{\mathbf{a}_{\gamma, k} \in \mathbf{a}} d_U(\mathbf{a}_{\gamma, k}, \mathbf{A}_k \mathbf{V}_{\gamma}(\mathbf{C}))^2$$





Primitive Modelling

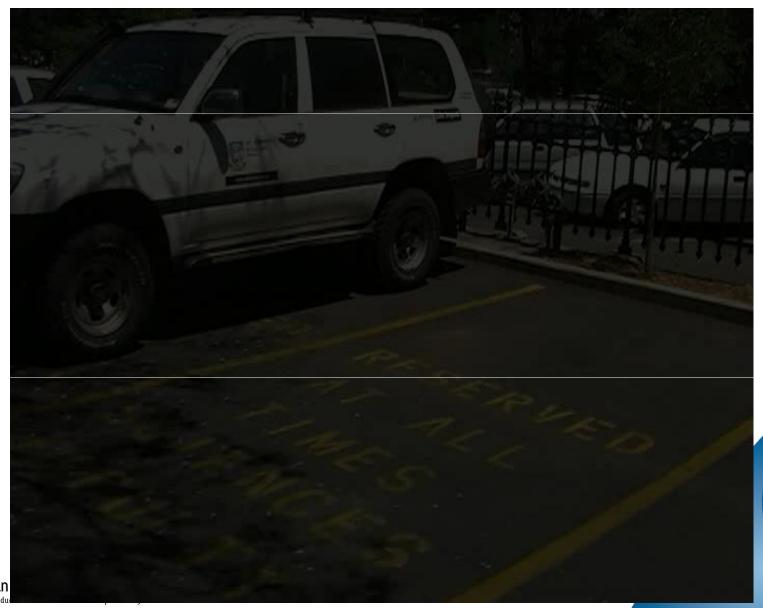
- There's not all that much of the world that can be modelled as a set of cubes
- Medium-level primitives
 - □ Planes, NURBS surfaces
 - Simple enough to be flexible
 - High-level enough to be useful
 - The kinds of primitives that modelling packages use



Sketch-based interface?



Input



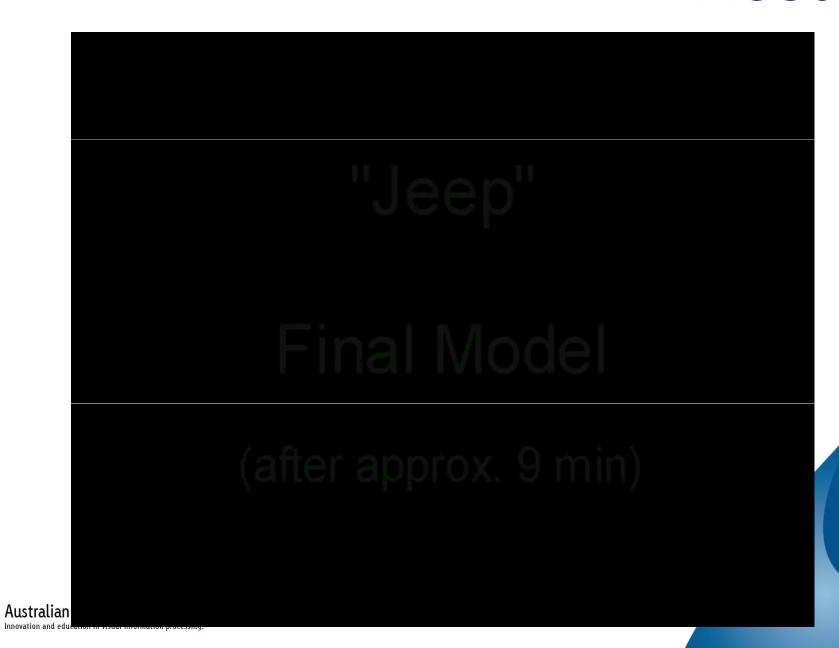


Modelling

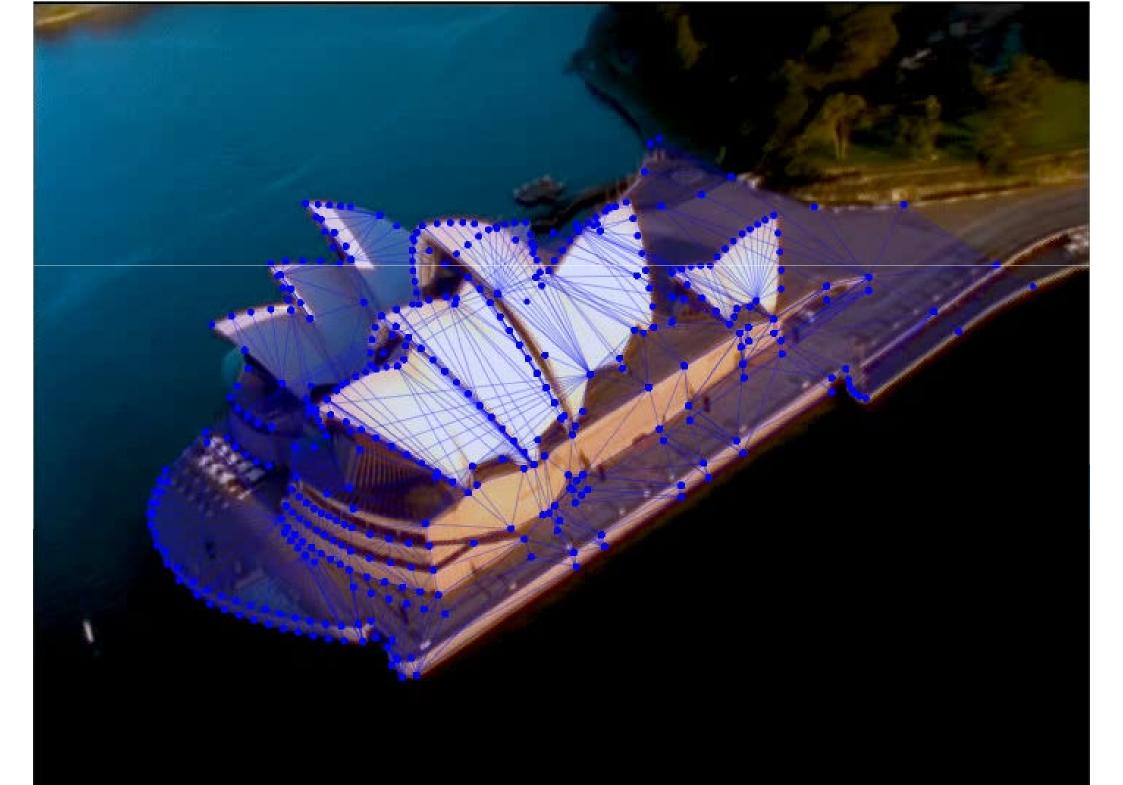




Results









Put your truck into a game

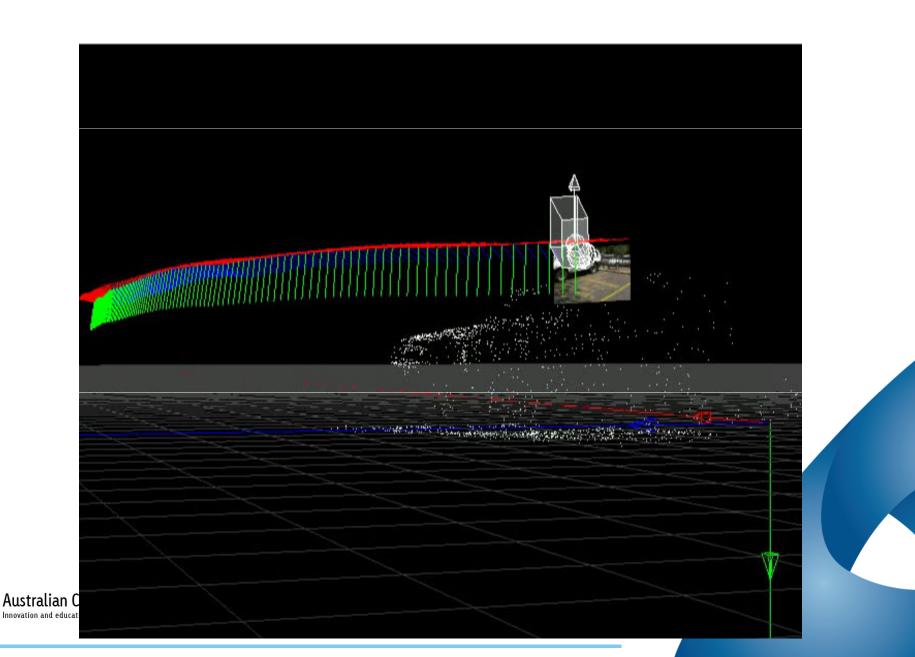




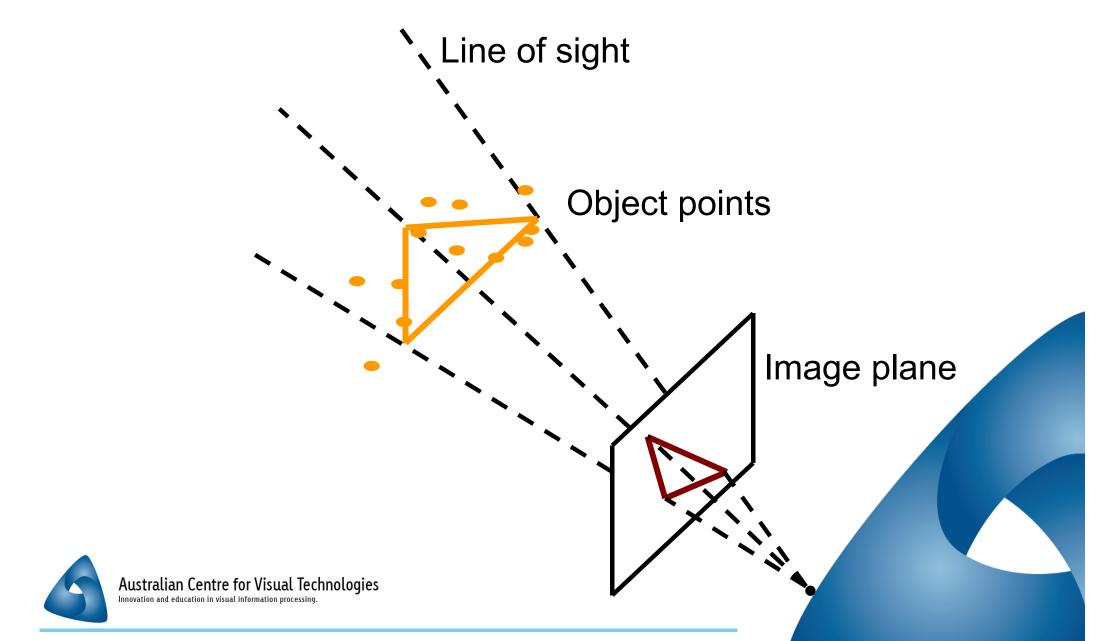
Modelling architecture



Structure from motion



Fitting planar faces



Hierarchical RANSAC

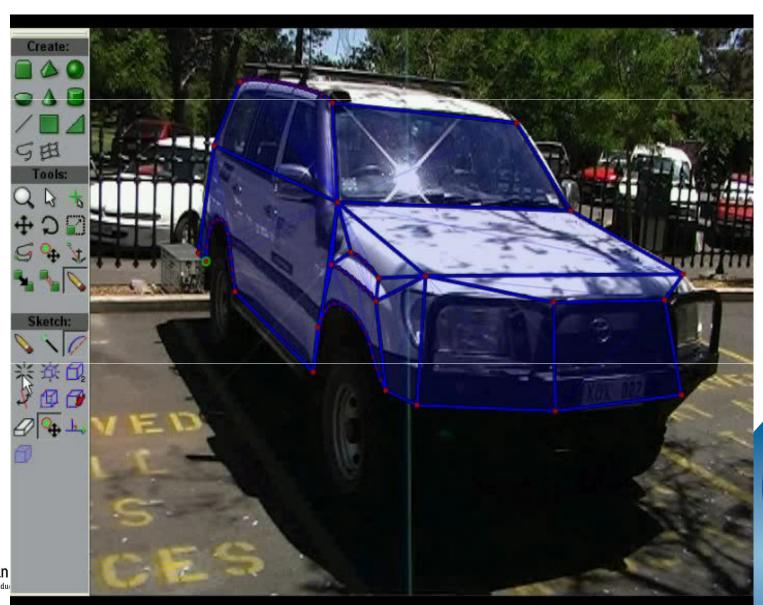
- Generate bounded plane hypotheses
- Tests
 - Support from point cloud
 - □ Reprojects within new image boundaries
 - Constraints on relative edge length and face size
 - □ Colour histogram matching on faces
 - Colour matching on edge projections
 - □ Reprojection is not self-occluding



Extrusion

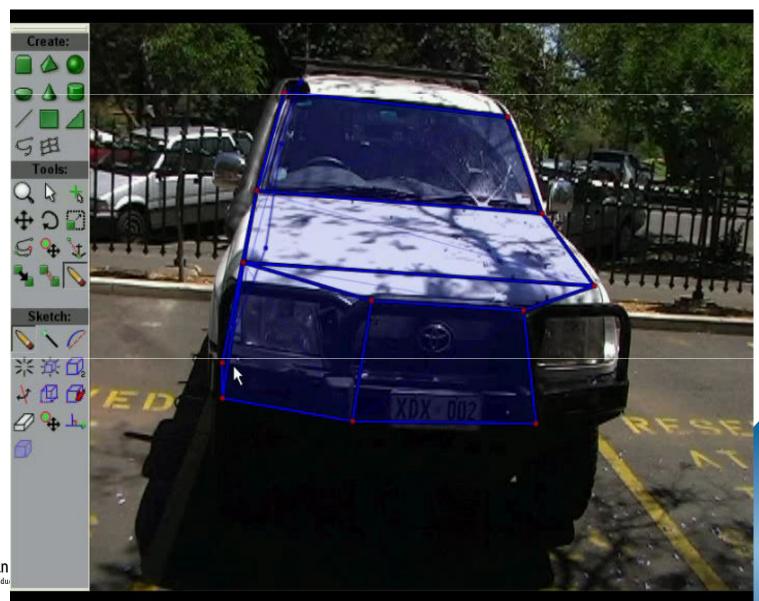


Mirroring





2D Curves



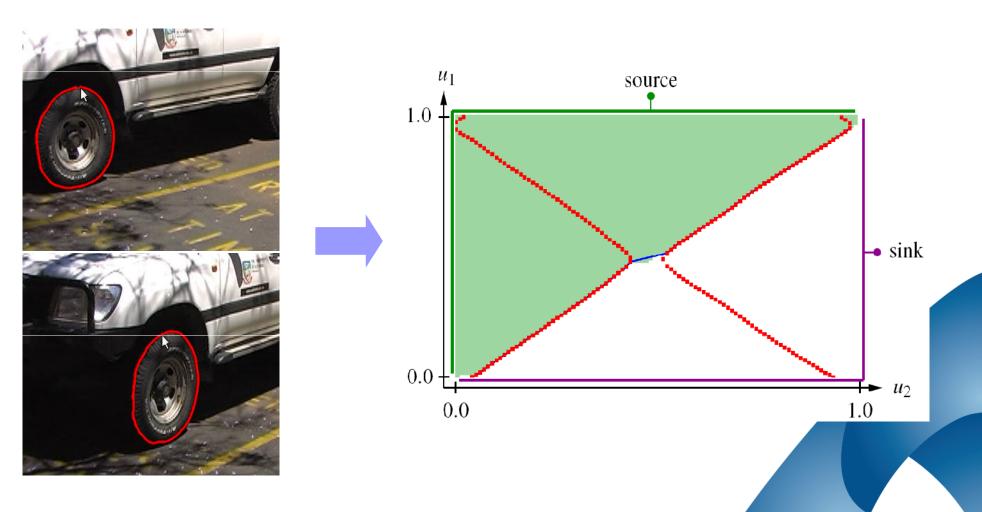


3D Curves

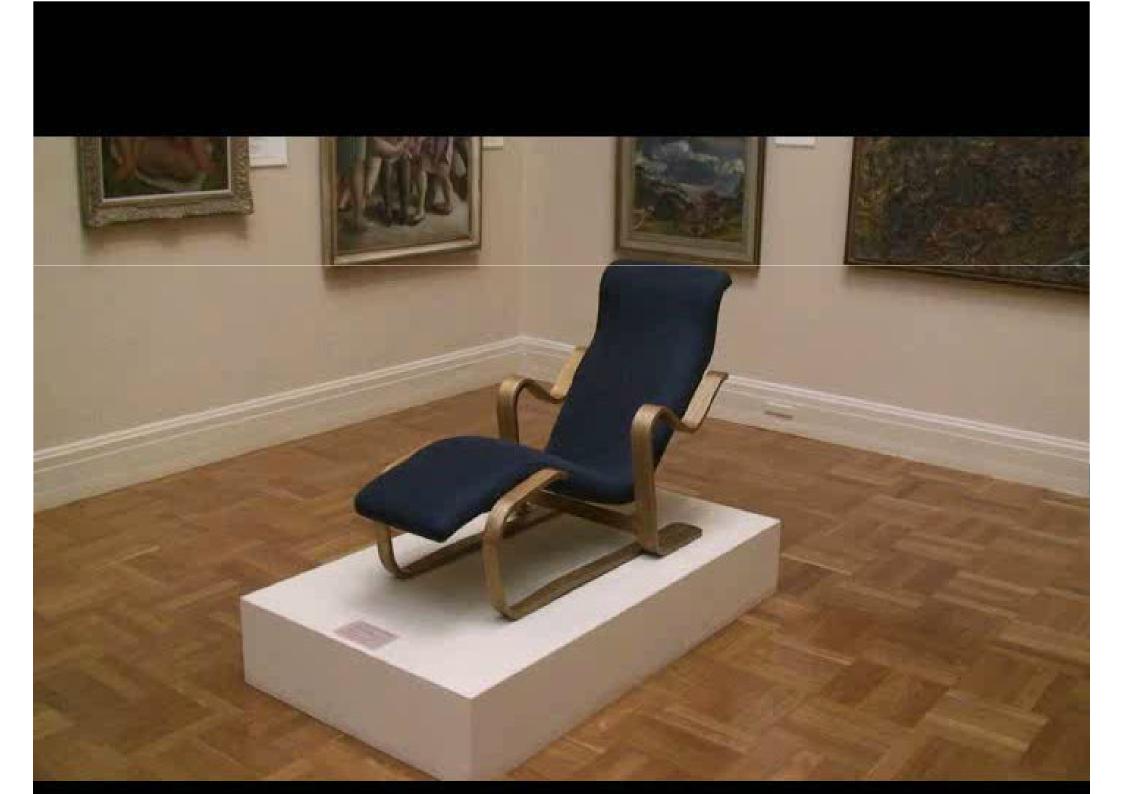


- Match 2 hand-drawn curves in 2 images
 - Curves generally not drawn accurately
 - May not match image features
 - Many-to-many matching
 - Generally different start and end points
- Interactive
 - □ Speed
 - Editing





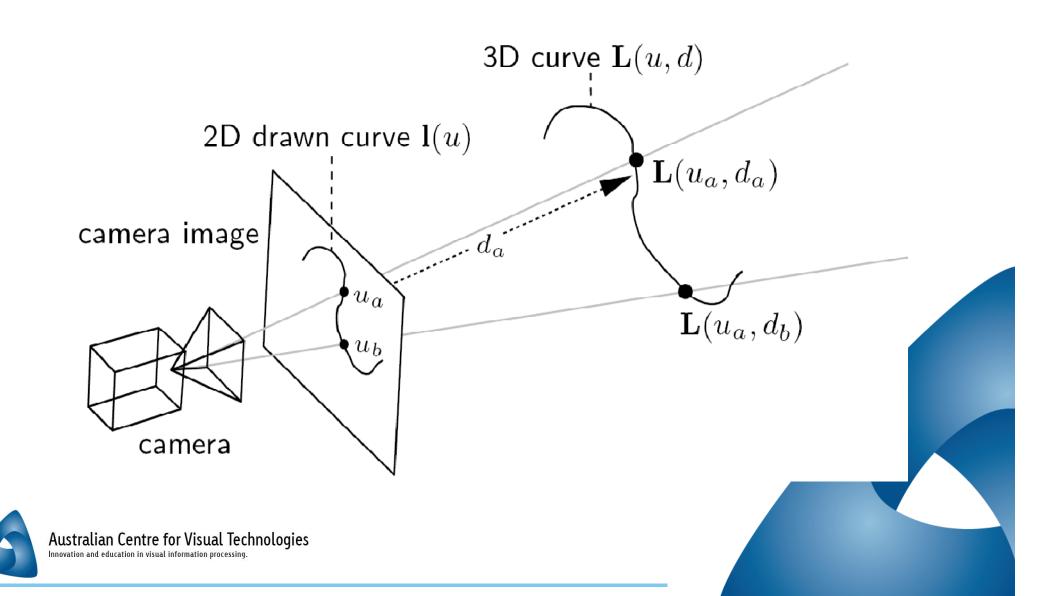


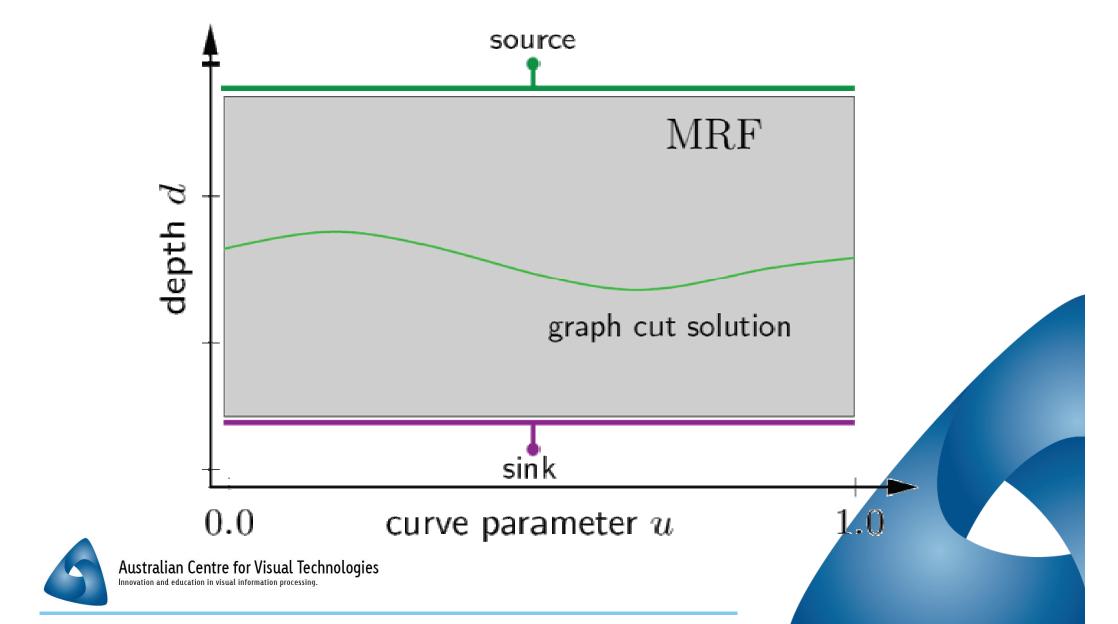


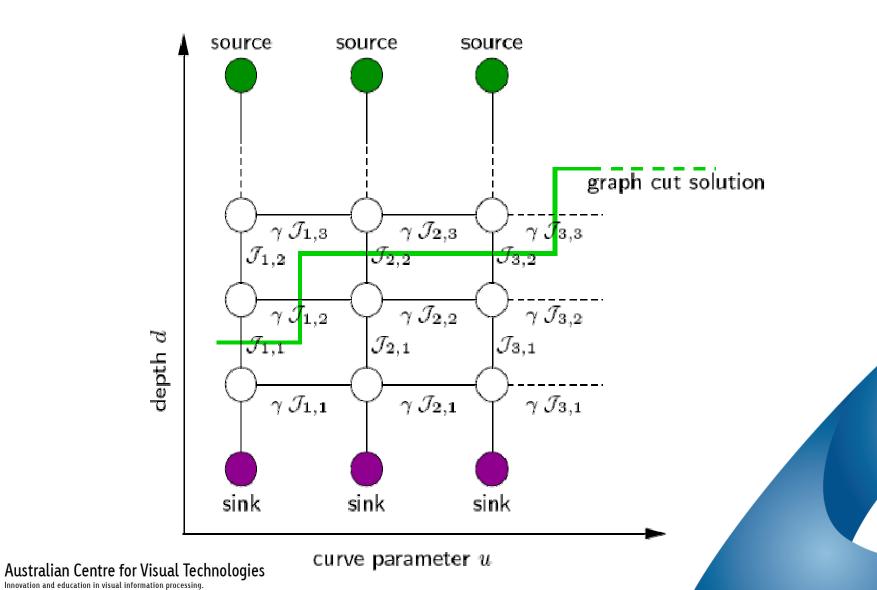


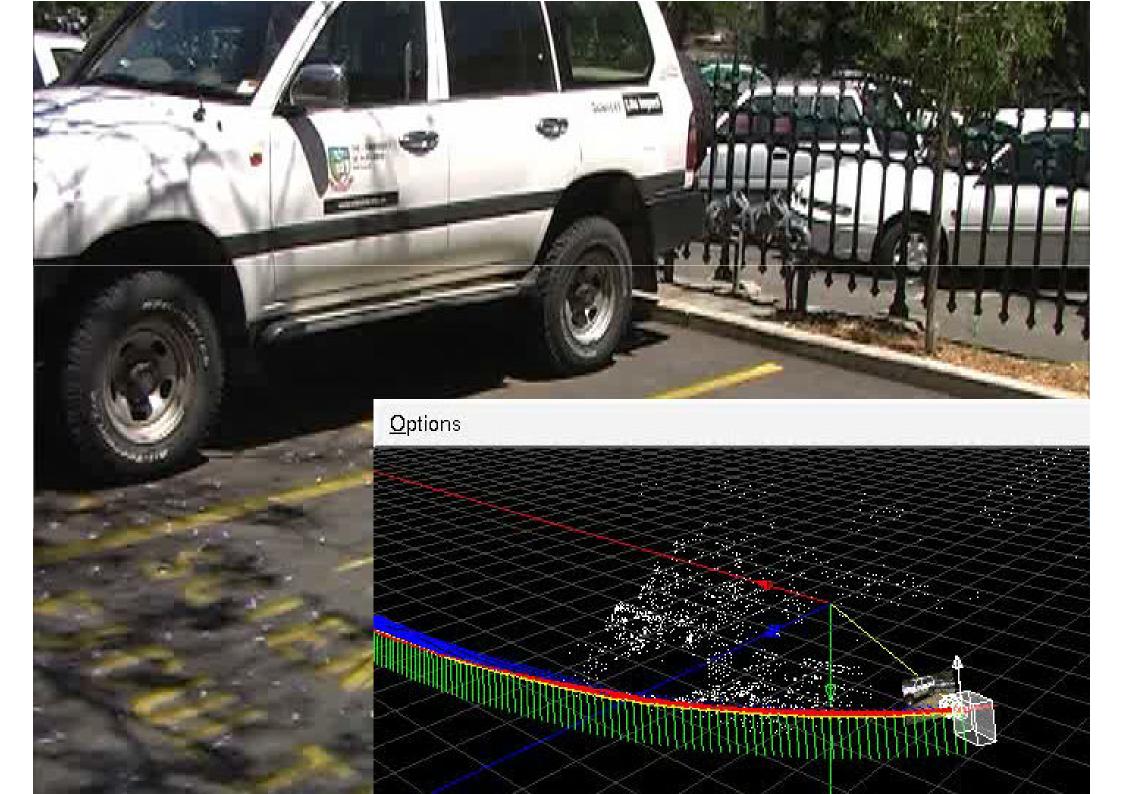
- Seek the 3D (scene) curve which best matches a curve drawn over one image from the set
 - □ Drawn curve specifies a set of possible 3D curves
 - Image set used to select from amongst that set
- Uses an MRF and graph cuts
 - Much like dense matching using graph cuts







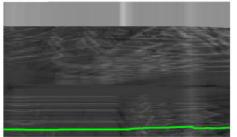


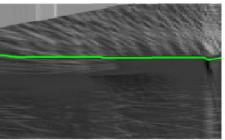


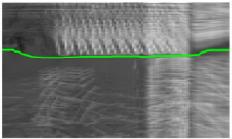


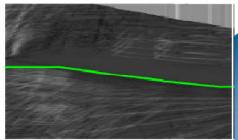


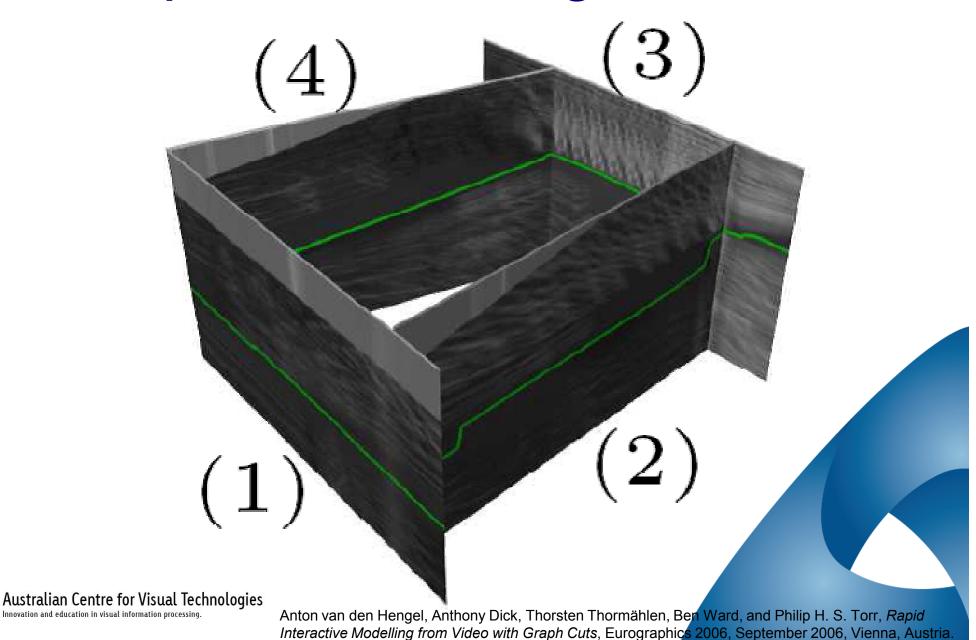
- Can't estimate intersecting curves independently
 - Curves don't necessarily intersect at end points











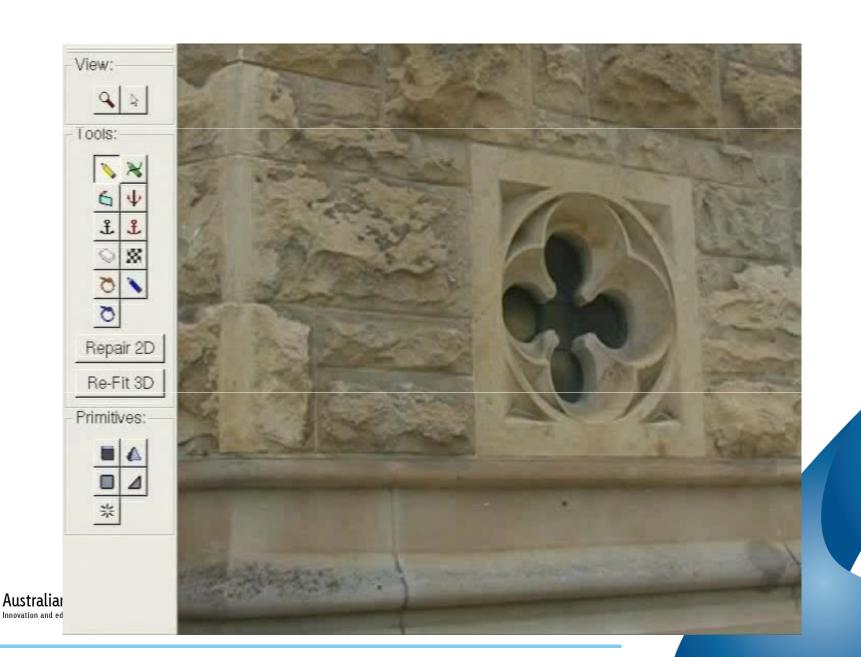








Dense surface reconstruction







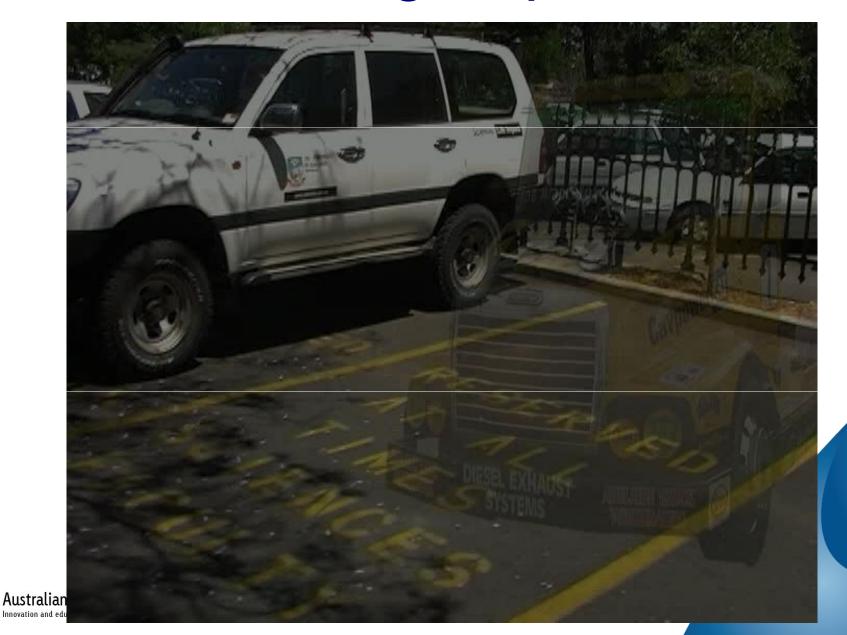
Video editing requires 3D

- We have Photoshop, but where is Videoshop?
- What is missing is the 3D





Video editing requires models



Video editing requires models



Lighting is 3D, as are materials

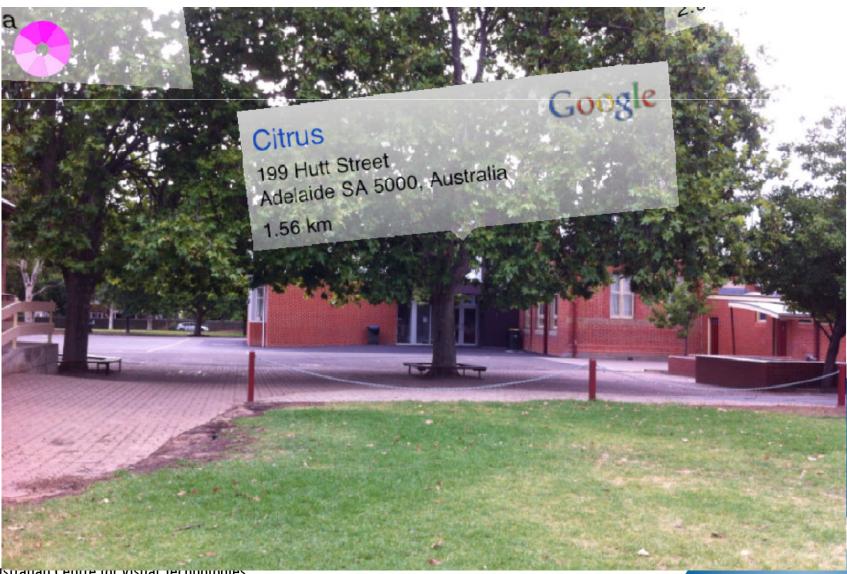
SecondSkin

An interactive method for appearance transfer





The Problem





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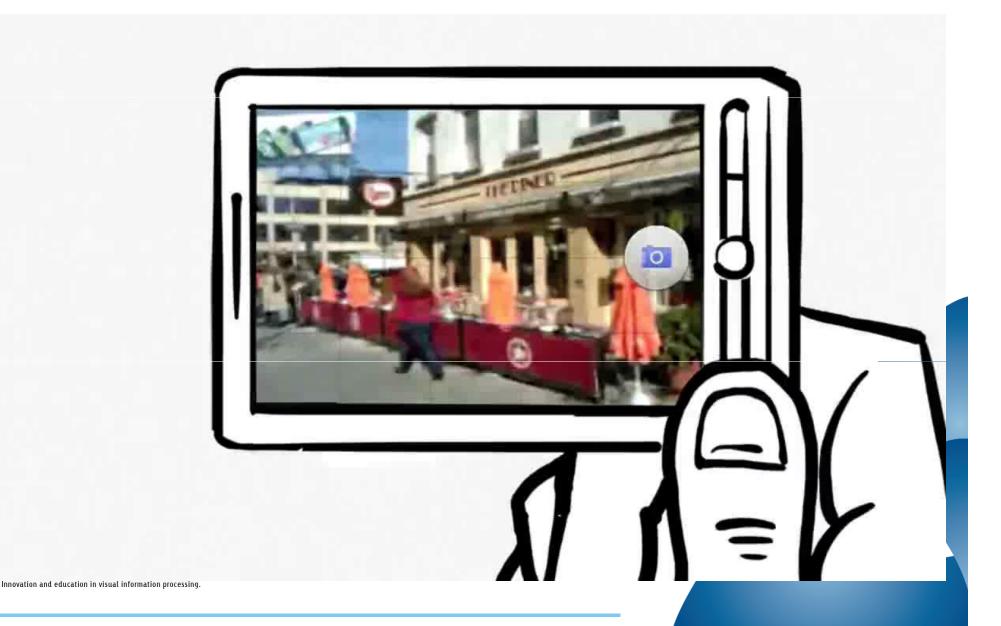
User-created 2D content for AR





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Google-created content for AR



Live modelling

- Most geometry cannot be modelled beforehand
 - ☐ You can't tell where it will be
 - Modelling the whole world won't work
- Need to generate models in-situ
 - While you're there



Videotrace - Live









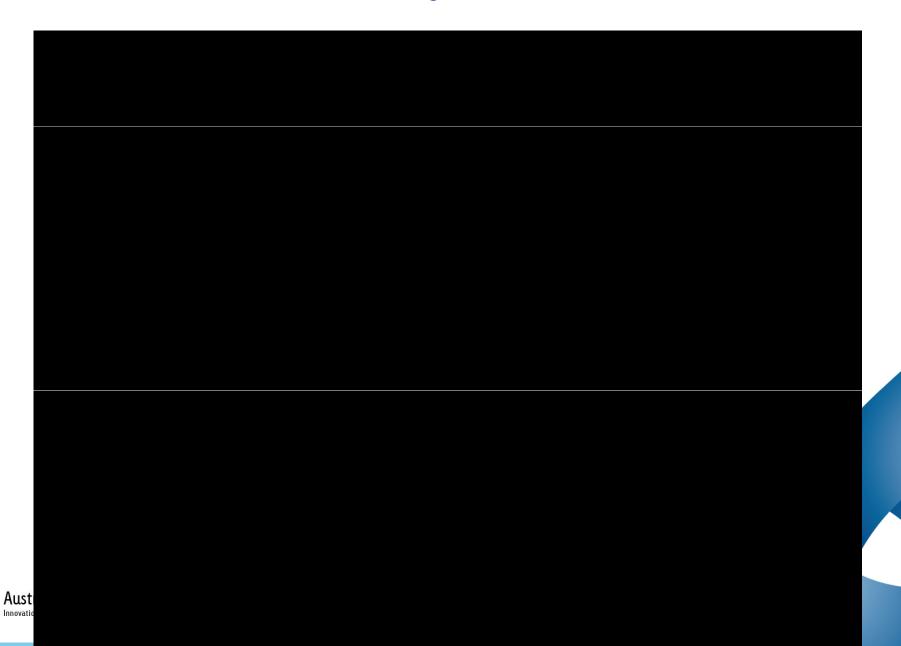
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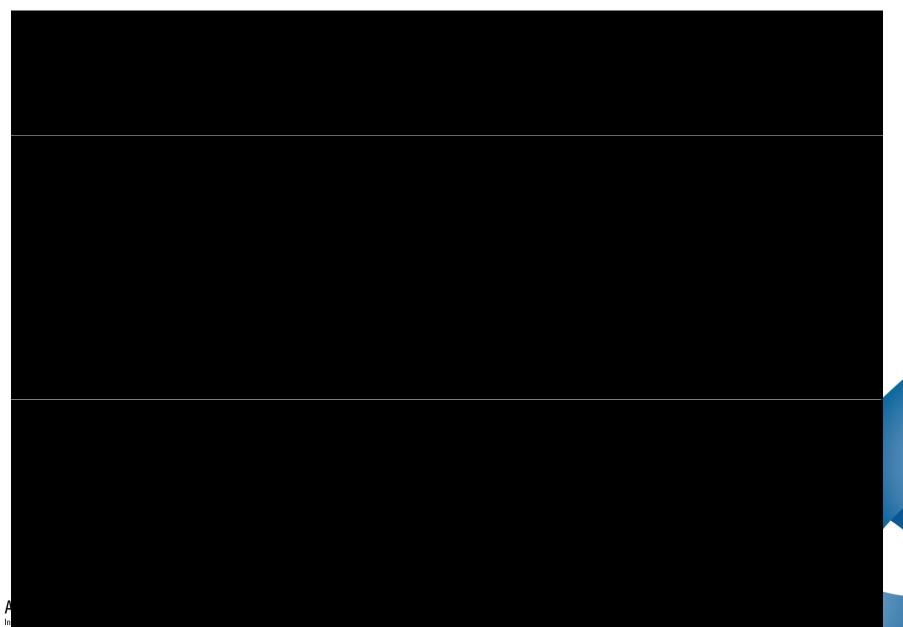


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Physical Interaction

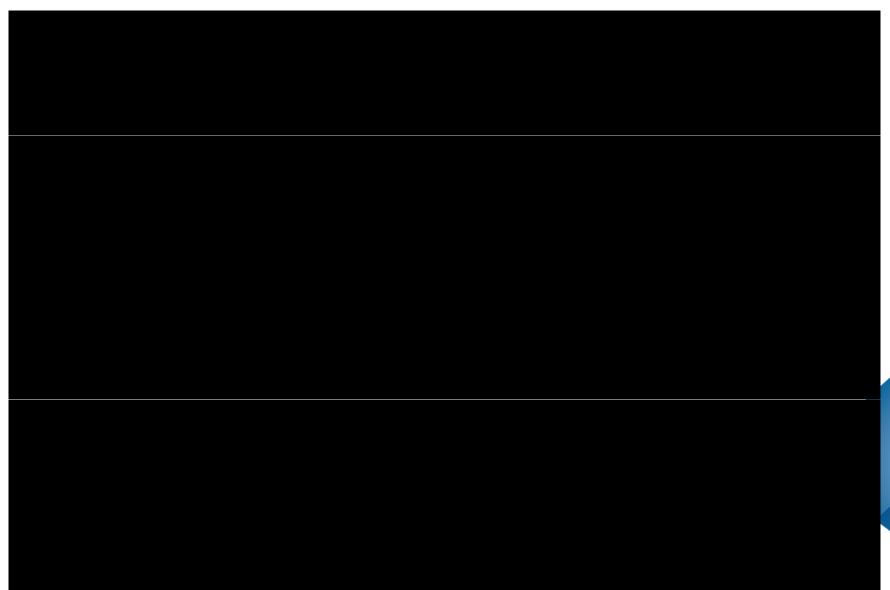


Occlusion





Fun



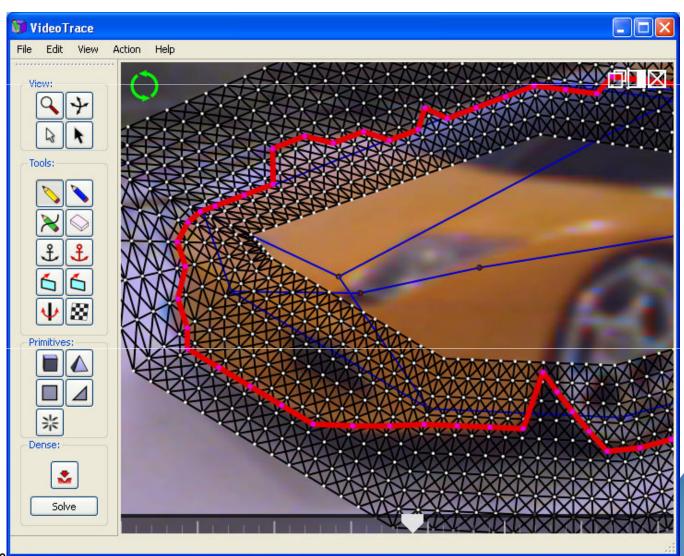


Getting Occlusion Right

- Occlusion is a key depth cue
 - But there is always some misalignment between model and reality
- Solve using a live segmentation of the real object from the video



Occlusion boundary refinement

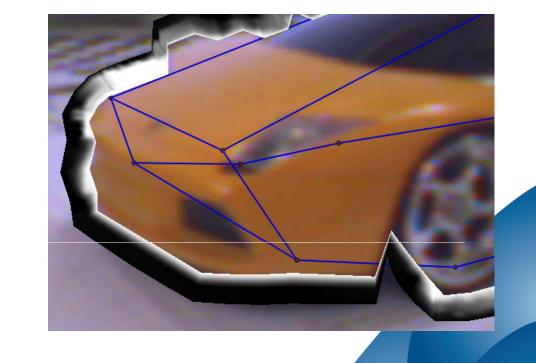




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Occlusion boundary refinement

- Graph cut gives a hard segmentation
- Fix with an alpha matte
- Blends between foreground and synthetic object
- Fixes some holes in the cut





Live modelling for AR

Live modelling and fast occlusion boundary refinement for augmented reality



AR modelling for other purposes



AR modelling for other purposes





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In-camera special effects

- A lot of video goes straight from the camera to distribution
 - ☐ Youtube, news, facebook, MMS, ...
- There are a lot of video cameras sitting in cupboards
- There is a lot of video that's not worth watching

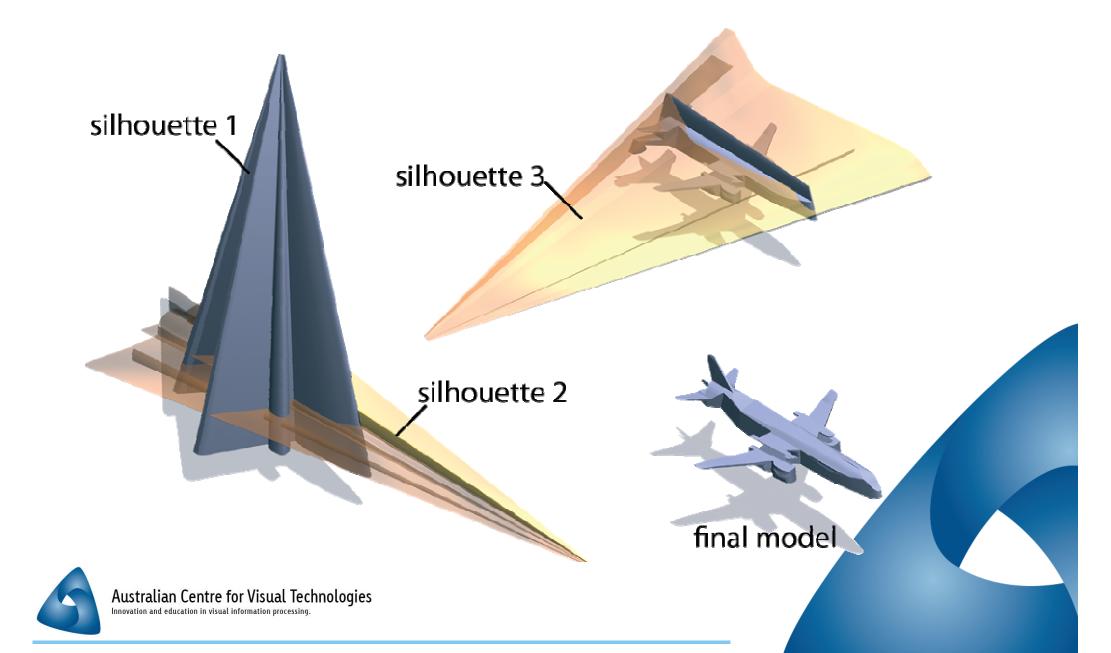


Minimal interaction modelling

- Use the camera as the modelling tool
 - □ The user only specifies the object, the rest is done with the camera
- Projective texturing
 - Some compensation for Visual Hull



Silhouette modelling



Minimal interaction modelling

Real-Time Modelling for AR Applications



SLAM is Fragile

- SLAM is
 - Designed for robot navigation
 - Dependent on continuous tracks
 - ☐ Solitary (rather than collaborative)
 - □ Inflexible
 - Dependant on geometry estimation
 - □ Overkill

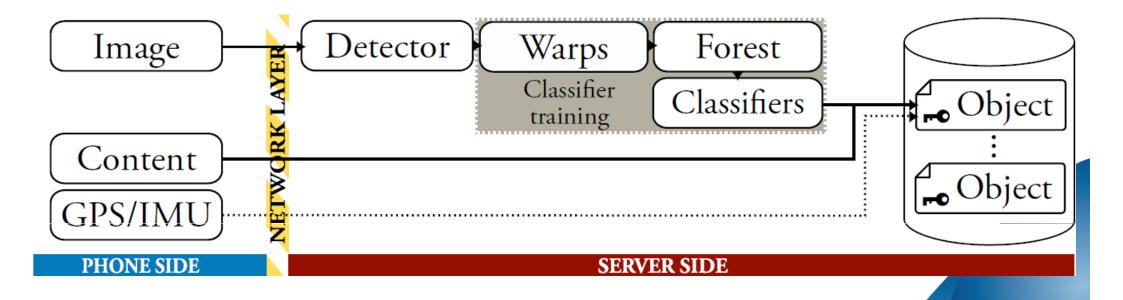


STAR

Simultaneous Tracking and Recognition

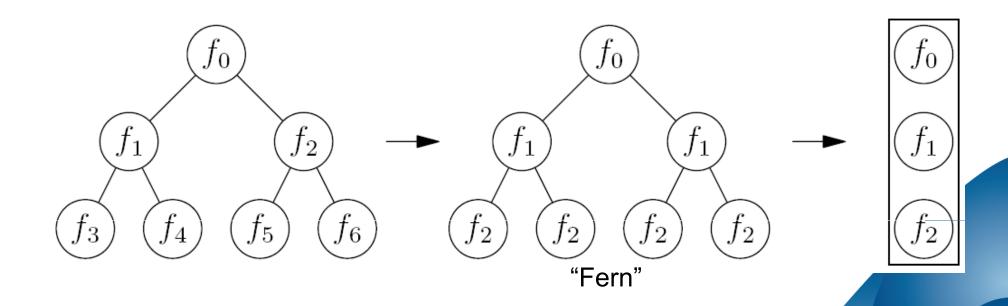


Training



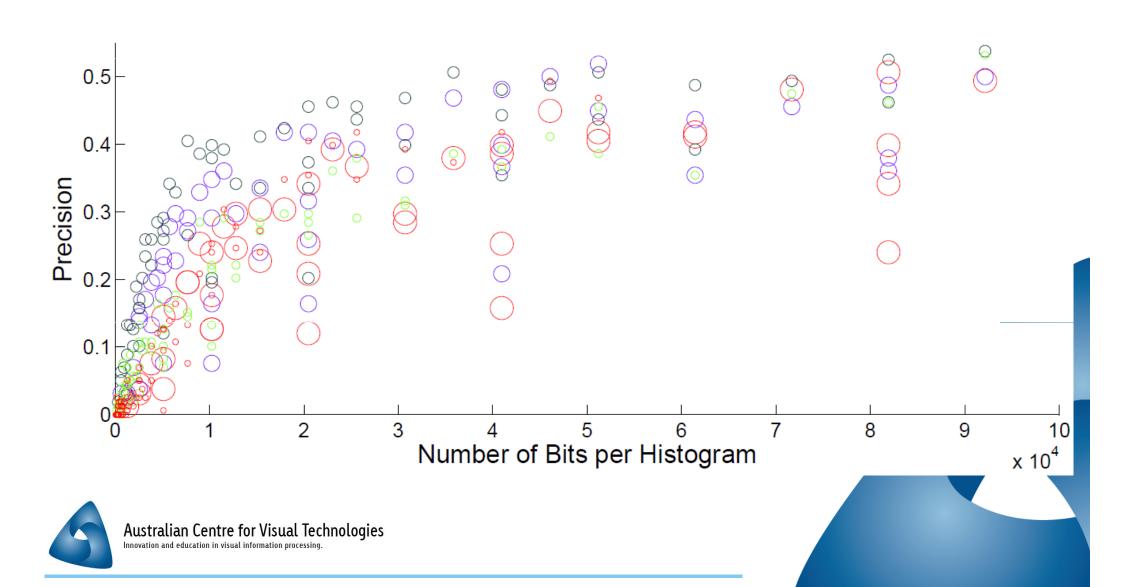


A Forest of Ferns





Classifier Efficiency



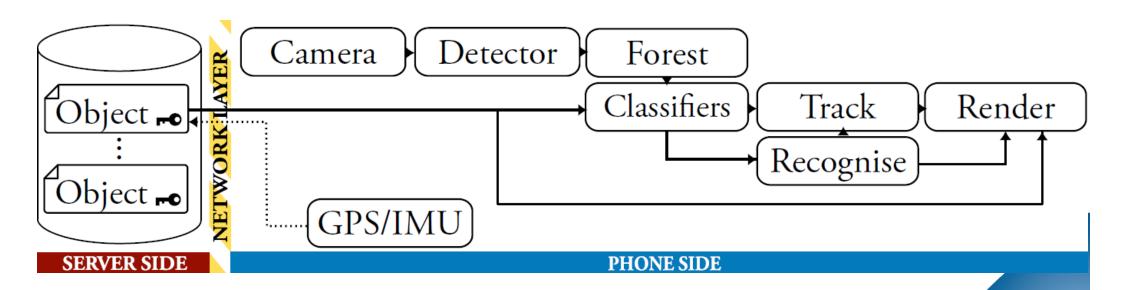
Classifiers as Feature Transforms

- 1. Train a set of N classifiers
- 2. Apply each to the image patch
- 3. Each element of the feature vector is the output of one classifier

This means we can use the same classifiers for Recognition and Tracking



Sharing





Shared Tracking and Recognition for Content Placement in AR

What's next?

- New interactions, applications and data sources
- Interactive SFM
- Videoshop





How to get Videotrace

- It's available on free beta test
 - ☐ Just register at www.punchcard.com.au
 - ☐ They will email you a link
 - □ It's a real beta
- Hopefully the final version will be free too

