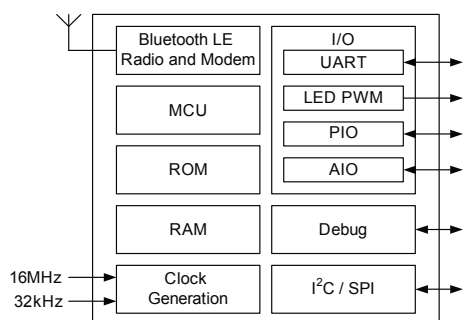


Features

- Bluetooth® v4.1 specification compliant
- Bluetooth Smart
- 128KB memory: 64KB RAM and 64KB ROM
- Support for Bluetooth v4.1 specification host stack including ATT, GATT, SMP, L2CAP, GAP
- RSSI monitoring for proximity applications
- <900nA current consumption in dormant mode
- 32kHz and 16MHz crystal or system clock
- Switch-mode power supply
- Programmable general purpose PIO controller
- 10-bit ADC and a DAC
- 12 digital PIOs
- 1 analogue AIO
- UART
- I²C / SPI for EEPROM / flash memory ICs and peripherals
- Debug SPI
- 4 PWM modules
- Wake-up interrupt and watchdog timer
- UT-WLCSP 34-bump, 2.43 x 2.56 x 0.35 mm, 0.4 mm pitch

General Description

CSR1013 WLCSP is a CSR µEnergy platform device. CSR µEnergy are CSR's single-mode Bluetooth low energy products for the Bluetooth Smart market. CSR1013 WLCSP increases application code and data space for greater application development flexibility. CSR µEnergy enables ultra low-power connectivity and basic data transfer for applications previously limited by the power consumption, size constraints and complexity of other wireless standards. CSR1013 WLCSP provides everything required to create a Bluetooth low energy product with RF, baseband, MCU, qualified Bluetooth v4.1 specification stack and customer application running on a single IC.



CSR µEnergy® CSR1013 WLCSP

Bluetooth Smart IC

Production Information

CSR1013A05

Issue 3



Applications

- Building an ecosystem using Bluetooth low energy
CSR is the industry leader for Bluetooth low energy, also known as Bluetooth Smart. Bluetooth Smart enables connectivity and data transfer to leading smartphone, tablet and personal computing devices including Apple iPhone, iPad, iPod and Mac products and leading Android devices.

Bluetooth low energy takes less time to make a connection than conventional Bluetooth wireless technology and can consume approximately 1/20th of the power of Bluetooth Basic Rate. CSR1013 WLCSP supports profiles for health and fitness sensors, watches, keyboards, mice and remote controls.

Typical Bluetooth Smart applications:

- HID: keyboards, mice, touchpads, remote controls
- Sports and fitness sensors: heart rate, runner speed and cadence, cycle speed and cadence
- Health sensors: blood pressure, thermometer and glucose meters
- Mobile accessories: watches, proximity tags, alert tags and camera controls
- Smart home: heating control and lighting control



Ordering Information

Device	Package			Order Number
	Type	Size	Shipment Method	
CSR1013 WLCSP	UT-WLCSP-34-bump (Pb free)	2.43 x 2.56 x 0.35 mm 0.4 mm pitch	Tape and reel	CSR1013A05-IUUM-R

Note:

Minimum order quantity is 4kpcs taped and reeled.

Supply chain: CSR's manufacturing policy is to multisource volume products. For further details, contact your local sales account manager or representative.

CSR1013 WLCSP Development Kit Ordering Information

Description	Order Number
Starter Development Kit and CSR1013 WLCSP Module Design	See www.csrsupport.com

Contacts

General information

www.csr.com

Information on this product

sales@csr.com

Customer support for this product

www.csrsupport.com

Details of compliance and standards

product.compliance@csr.com

Help with this document

comments@csr.com

Device Details

Bluetooth Radio

- On-chip balun (50Ω impedance in TX and RX modes)
- No external trimming is required in production
- Bluetooth v4.1 specification compliant

Bluetooth Transmitter

- 9.0dBm RF transmit power with level control from integrated 6-bit DAC over a dynamic range >25dB
- No external power amplifier or TX/RX switch required

Bluetooth Receiver

- -91.5dBm sensitivity
- Integrated channel filters
- Digital demodulator for improved sensitivity and co-channel rejection
- Fast AGC for enhanced dynamic range

Bluetooth Stack

CSR's protocol stack runs on the integrated MCU:

- Support for Bluetooth v4.1 specification features:
 - Master and slave operation
 - Including encryption
- Software stack in firmware includes:
 - GAP
 - L2CAP
 - Security manager
 - Attribute protocol
 - Attribute profile
 - Bluetooth low energy profile support

Synthesiser

- Fully integrated synthesiser requires no external VCO varactor diode, resonator or loop filter

Baseband and Software

- Hardware MAC for all packet types enables packet handling without the need to involve the MCU

Physical Interfaces

- SPI master interface
- SPI programming and debug interface
- I²C
- 12 digital PIOs
- 1 analogue AIO
- UART

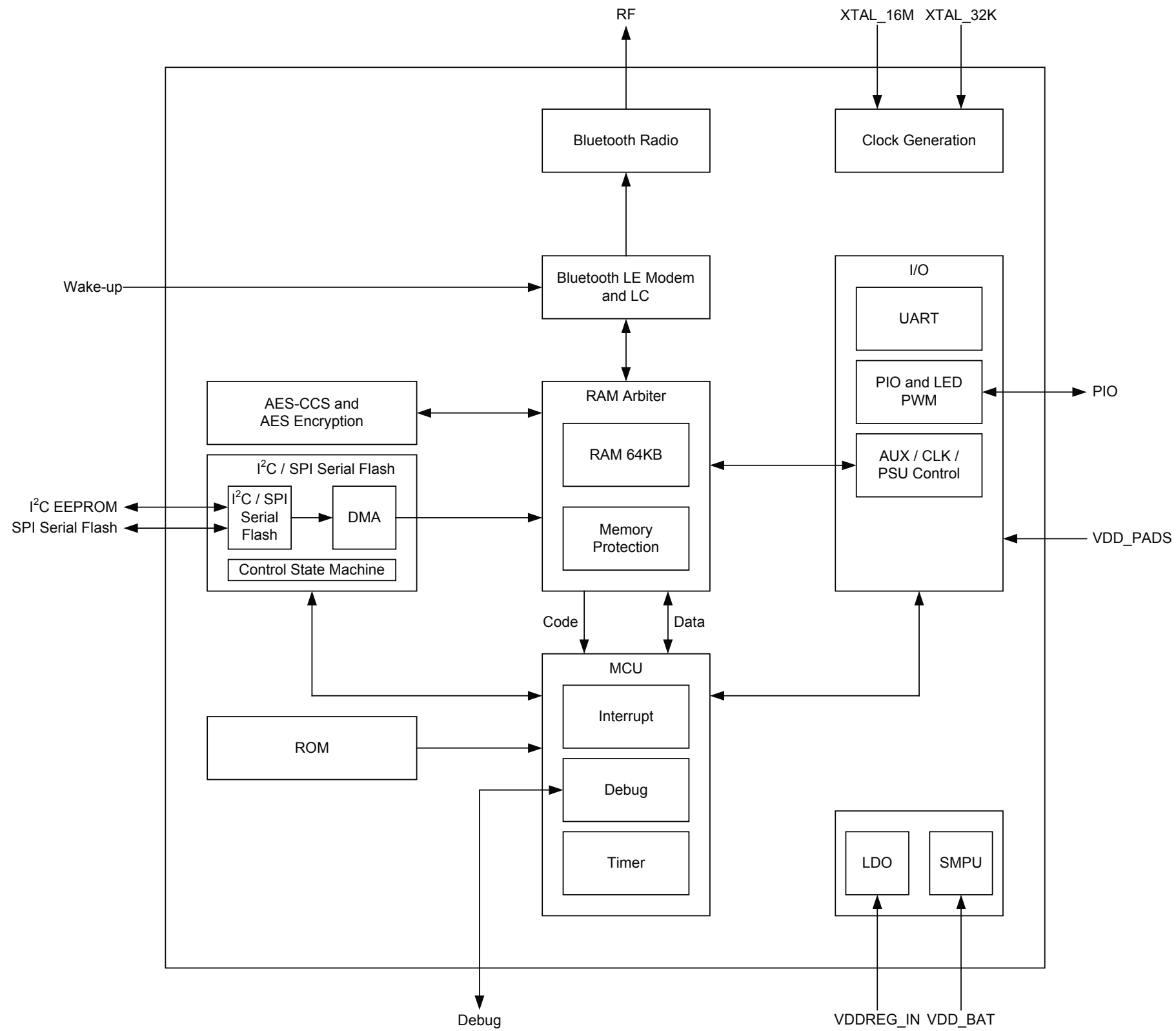
Auxiliary Features

- Battery monitor
- Power management features include software shutdown and hardware wake-up
- CSR1013 WLCSP can run in low power modes from an external 32.768kHz clock signal
- Integrated switch-mode power supply
- Linear regulator (internal use only)
- Power-on-reset cell detects low supply voltage

Package

- 34-bump 2.43 x 2.56 x 0.35 mm, 0.4 mm pitch UT-WLCSP

Functional Block Diagram



Document History

Revision	Date	Change Reason
1	14 JAN 15	Original publication of this document.
2	15 JAN 15	Updated Ordering Information.
3	19 JUN 15	Updated to Production Information.

Status Information

The status of this Data Sheet is **Production Information**. CSR Product Data Sheets progress according to the following format:

- **Advance Information:**
 - Information for designers concerning CSR product in development. All values specified are the target values of the design. Minimum and maximum values specified are only given as guidance to the final specification limits and must not be considered as the final values.
- **Engineering Sample:**
 - Information about initial devices. Devices are untested or partially tested prototypes, their status is described in an Engineering Sample Release Note. All values specified are the target values of the design. Minimum and maximum values specified are only given as guidance to the final specification limits and must not be considered as the final values.
 - All detailed specifications including pinouts and electrical specifications may be changed by CSR without notice.
- **Pre-production Information:**
 - Pinout and mechanical dimension specifications finalised. All values specified are the target values of the design. Minimum and maximum values specified are only given as guidance to the final specification limits and must not be considered as the final values.
 - All electrical specifications may be changed by CSR without notice.
- **Production Information:**
 - Final Data Sheet including the guaranteed minimum and maximum limits for the electrical specifications.
 - Production Data Sheets supersede all previous document versions.

Device Implementation

Important Note:

As the feature-set of the CSR1013 WLCSP is firmware build-specific, see the relevant software release note for the exact implementation of features on the CSR1013 WLCSP.

Life Support Policy and Use in Safety-critical Applications

CSR's products are not authorised for use in life-support or safety-critical applications. Use in such applications is done at the sole discretion of the customer. CSR will not warrant the use of its devices in such applications.

CSR Green Semiconductor Products and RoHS Compliance

CSR1013 WLCSP devices meet the requirements of Directive 2011/65/EU of the European Parliament and of the Council on the Restriction of Hazardous Substance (RoHS). CSR1013 WLCSP devices are free from halogenated or antimony trioxide-based flame retardants and other hazardous chemicals. For more information, see CSR's *Environmental Compliance Statement for CSR Green Semiconductor Products*.

Confidentiality Status

This document is non-confidential. The right to use, copy and disclose this document may be subject to license restrictions in accordance with the terms of the agreement entered into by CSR plc and the party that CSR plc delivered this document to.

Trademarks, Patents and Licences

Unless otherwise stated, words and logos marked with [™] or [®] are trademarks registered or owned by CSR plc or its affiliates. Bluetooth [®] and the Bluetooth [®] logos are trademarks owned by Bluetooth [®] SIG, Inc. and licensed to CSR. Other products, services and names used in this document may have been trademarked by their respective owners.

The publication of this information does not imply that any license is granted under any patent or other rights owned by CSR plc and/or its affiliates.

CSR reserves the right to make technical changes to its products as part of its development programme.

While every care has been taken to ensure the accuracy of the contents of this document, CSR cannot accept responsibility for any errors.

Refer to www.csrsupport.com for compliance and conformance to standards information.

Contents

	Ordering Information	2
	CSR1013 WLCSP Development Kit Ordering Information	2
	Contacts	2
	Device Details	3
	Functional Block Diagram	4
1	Package Information	10
	1.1 Pinout Diagram	10
	1.2 Device Terminal Functions	11
	1.3 Package Dimensions	14
	1.4 PCB Design and Assembly Considerations	15
	1.5 Typical Solder Reflow Profile	15
2	Bluetooth Modem	16
	2.1 RF Ports	16
	2.2 RF Receiver	16
	2.2.1 Low Noise Amplifier	16
	2.2.2 RSSI Analogue to Digital Converter	16
	2.3 RF Transmitter	16
	2.3.1 IQ Modulator	16
	2.3.2 Power Amplifier	16
	2.4 Bluetooth Radio Synthesiser	16
	2.5 Baseband	16
	2.5.1 Physical Layer Hardware Engine	16
3	Clock Generation	17
	3.1 Clock Architecture	17
	3.2 Crystal Oscillator: XTAL_16M_IN and XTAL_16M_OUT	17
	3.2.1 Crystal Specification	17
	3.2.2 Frequency Trim	18
	3.3 Sleep Clock	18
	3.3.1 Crystal Specification	18
4	Operating Modes	20
	4.1 Run Mode	20
	4.2 Idle Mode	20
	4.3 Deep Sleep Mode	20
	4.4 Hibernate Mode	20
	4.5 Dormant Mode	20
5	Microcontroller, Memory and Baseband Logic	21
	5.1 System RAM	21
	5.2 Internal ROM	21
	5.3 Microcontroller	21
	5.4 Programmable I/O Ports, PIO and AIO	21
	5.5 LED Flasher / PWM Module	22
	5.6 Temperature Sensor	23
	5.7 Battery Monitor	24
6	Serial Interfaces	25
	6.1 Application Interface	25
	6.1.1 UART Interface	25
	6.2 I ² C Interface	25
	6.3 SPI Master Interface	27
	6.4 Programming and Debug Interface	29

6.4.1	Instruction Cycle	29
6.4.2	Multi-slave Operation	30
7	Power Control and Regulation	31
7.1	Switch-mode Regulator	31
7.2	Low-voltage VDD_CORE Linear Regulator	31
7.3	Reset	31
7.3.1	Digital Pin States on Reset	31
7.3.2	Power-on Reset	32
8	Example Application Schematic	33
9	Electrical Characteristics	34
9.1	Absolute Maximum Ratings	34
9.2	Recommended Operating Conditions	34
9.3	Input/Output Terminal Characteristics	35
9.3.1	Switch-mode Regulator	35
9.3.2	Low-voltage Linear Regulator	35
9.3.3	Digital Terminals	35
9.3.4	AIO	36
9.4	Junction Temperature	38
9.5	ESD Protection	38
10	Current Consumption	39
11	CSR Green Semiconductor Products and RoHS Compliance	40
12	CSR1013 WLCSP Software Stack	41
13	Tape and Reel Information	42
13.1	Tape Orientation	42
13.2	Tape Dimensions	43
13.3	Reel Information	44
13.4	Moisture Sensitivity Level	44
14	Document References	45
	Terms and Definitions	46

List of Figures

Figure 1.1	Pinout Diagram	10
Figure 3.1	Clock Architecture	17
Figure 3.2	Crystal Driver Circuit	17
Figure 3.3	Sleep Clock Crystal Driver Circuit	18
Figure 5.1	Baseband Digits Block Diagram	21
Figure 5.2	Typical PWM Signal on a PIO	23
Figure 6.1	Example of an I ² C Interface EEPROM Connection	26
Figure 6.2	I ² C Standard Mode 100 kHz Timing Diagram (Top Line: SCL, Bottom Line: SDA)	26
Figure 6.3	I ² C Fast Mode 400 kHz Timing Diagram (Top Line: SCL, Bottom Line: SDA)	27
Figure 6.4	SPI Timing Diagram	28
Figure 6.5	Memory Boot-up Sequence	29
Figure 7.1	Voltage Regulator Configuration	31
Figure 12.1	Software Architecture	41
Figure 13.1	Tape Orientation	42
Figure 13.2	Tape Dimensions	43
Figure 13.3	Reel Dimensions	44

List of Tables

Table 3.1	Crystal Specification	18
Table 3.2	Sleep Clock Specification	19
Table 5.1	Wake Options for Sleep Modes	22
Table 5.2	Alternative PIO Functions	22
Table 5.3	PWM Operating Range	23
Table 6.1	Possible UART Settings	25
Table 6.2	I ² C Standard Mode 100 kHz Timing Definition	26
Table 6.3	I ² C Fast Mode 400 kHz Timing Definition	27
Table 6.4	SPI Master Serial Flash Memory Interface	28
Table 6.5	Instruction Cycle for a SPI Transaction	30
Table 7.1	Pin States on Reset	32
Table 7.2	Power-on Reset	32
Table 9.1	Junction Temperature within Recommended Operating Conditions	38
Table 9.2	ESD Handling Ratings	38
Table 10.1	Current Consumption	39

1 Package Information

1.1 Pinout Diagram

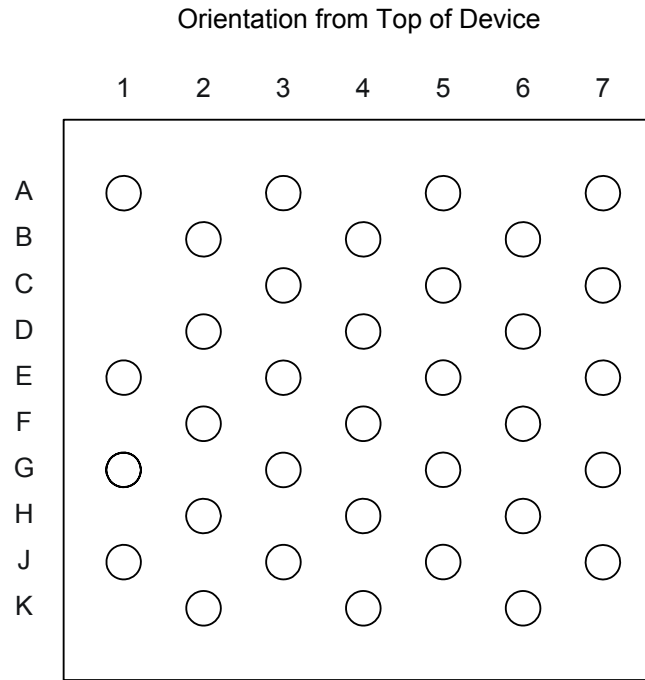


Figure 1.1: Pinout Diagram

G-TW-0014374.2.2

1.2 Device Terminal Functions

Radio	Bump	Pad Type	Supply Domain	Description
RF	D2	RF	VDD_REG_IN	Bluetooth transmitter / receiver.

Synthesiser and Oscillator	Bump	Pad Type	Supply Domain	Description
XTAL_32K_OUT	H2	Analogue	VDD_BAT	Drive for sleep clock crystal.
XTAL_32K_IN	J1	Analogue	VDD_BAT	32.768kHz sleep clock input.
XTAL_16M_OUT	B2	Analogue	VDD_XTAL	Drive for crystal.
XTAL_16M_IN	A3	Analogue	VDD_XTAL	Reference clock input.

I ² C Interface	Bump	Pad Type	Supply Domain	Description
I2C_SDA	J5	Bidirectional, tristate, with weak internal pull-up	VDD_PADS	I ² C data input / output or SPI serial flash data output (SF_DOUT). If connecting to SPI serial flash, connect this pin to SO on the serial flash.
I2C_SCL	G5	Input with weak internal pull-up	VDD_PADS	I ² C clock or SPI serial flash clock output (SF_CLK).

PIO Port	Bump	Pad Type	Supply Domain	Description
PIO[11]	E3	Bidirectional with programmable strength internal pull-up/down	VDD_PADS	Programmable I/O line.
PIO[10]	D4			
PIO[9]	J7			
PIO[8] / DEBUG_MISO	F6	Bidirectional with programmable strength internal pull-up/down	VDD_PADS	Programmable I/O line or debug SPI MISO selected by SPI_PIO#.
PIO[7] / DEBUG_MOSI	E7			Programmable I/O line or debug SPI MOSI selected by SPI_PIO#.
PIO[6] / DEBUG_CS#	C7			Programmable I/O line or debug SPI chip select (CS#) selected by SPI_PIO#.
PIO[5] / DEBUG_CLK	D6			Programmable I/O line or debug SPI CLK selected by SPI_PIO#.

PIO Port	Bump	Pad Type	Supply Domain	Description
PIO[4] / SF_CS#	A7	Bidirectional with programmable strength internal pull-up/down	VDD_PADS	Programmable I/O line or SPI serial flash chip select (SF_CS#).
PIO[3] / SF_DIN	B6			Programmable I/O line or SPI serial flash data (SF_DIN) input. If connecting to SPI serial flash, this pin connects to SI on the serial flash.
PIO[2]	H6	Bidirectional with programmable strength internal pull-up/down	VDD_PADS	Programmable I/O line or I ² C power.
PIO[1] / UART_RX	C5	Bidirectional with programmable strength internal pull-up/down	VDD_PADS	Programmable I/O line or UART RX.
PIO[0] / UART_TX	A5			Programmable I/O line or UART TX.
AIO[0]	B4	Bidirectional analogue	VDD_XTAL	Analogue programmable I/O line.

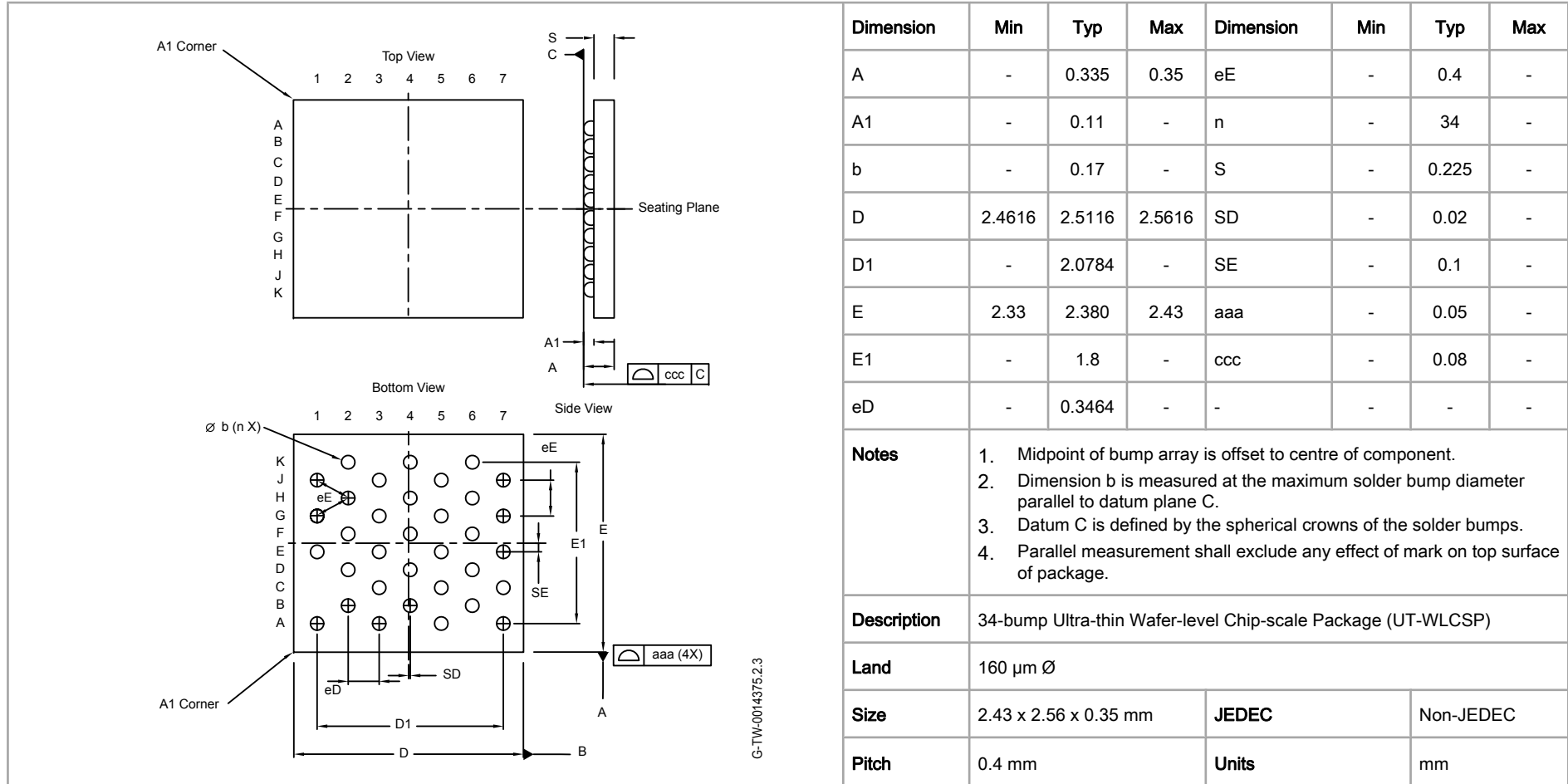
Test and Debug	Bump	Pad Type	Supply Domain	Description
SPI_PIO#	K6	Input with strong internal pull-down	VDD_PADS	Selects SPI debug on PIO[8:5].

Wake-up	Bump	Pad Type	Supply Domain	Description
WAKE	F2	Input has no internal pull-up or pull-down, use external pull-down.	VDD_BAT	Input to wake CSR1013 WLCSP from hibernate or dormant.

Power Supplies and Control	Bump	Description
VDD_BAT	G3	Battery input and regulator enable (active high).
VDD_BAT_SMPS	J3	Input to high-voltage switch-mode regulator.
SMPS_LX	K2	High-voltage switch-mode regulator output.
VDD_CORE	K4	Positive supply for digital domain.
VDD_PADS	G7	Positive supply for all digital I/O ports PIO[11:0].

Power Supplies and Control	Bump	Description
VDD_REG_IN	G1	Positive supply for Bluetooth radio and digital linear regulator.
VDD_XTAL	A1	Decouple with 470nF capacitor to ground.
VSS_AUX_LO	C3	Ground for AUX and LO.
VSS_DIG	E5, F4	Digital ground.
VSS_RADIO	E1	RF ground.
VSS_VBAT_SMPS	H4	Switcher ground.

1.3 Package Dimensions



1.4 PCB Design and Assembly Considerations

This section lists recommendations to achieve maximum board-level reliability of the 2.43 x 2.56 x 0.35 mm UT-WLCSP 34-bump package:

- NSMD lands (that is, lands smaller than the solder mask aperture) are preferred because of the greater accuracy of the metal definition process compared to the solder mask process. With solder mask defined pads, the overlap of the solder mask on the land creates a step in the solder at the land interface, which can cause stress concentration and act as a point for crack initiation.
- Ideally, via-in-pad technology should be used to achieve truly NSMD lands. Where this is not possible, a maximum of one trace connected to each land is preferred. This trace should be as thin as possible, taking into consideration its current carrying and the RF requirements.
- CSR recommends 35µm thick (1oz) copper lands rather than 17µm thick (0.5oz). This results in a greater standoff which has been proven to provide greater reliability during thermal cycling.
- Land diameter should be 160 µm ±10µm to achieve optimum reliability.
- UT-WLCSP parts have nominal bump geometries of 100µm (height) and 160µm (diameter). To maintain the lowest profile solution, CSR recommends a flux-only assembly process.
- UT-WLCSP can be mounted using a solder paste assembly process. However because additional solder material is introduced, the final bump height will be higher. An increase in the final volume of solder in the joint generally increases reliability.
- Differences in CTE ratings between UT-WLCSP (silicon) and application substrate should be carefully considered.
- Reliability may be enhanced by the introduction of a suitable underfill material.
- Where possible, the solder lands should be finished with OSP.
- Where a nickel gold plating finish is used, the gold thickness should be kept below 0.5µm to prevent brittle gold/tin intermetallics forming in the solder.
- The UT-WLCSP is designed so that bump lands do not lie on top of sensitive areas of the active silicon.
- UT-WLCSP components often have the bump array mid-point offset to the centre of the component outline. This requires careful consideration during component footprint design.

UT-WLCSP devices have proven to be reliable. However, by their nature they are more susceptible to handling damage than plastic packaged devices. Care should be taken to optimise placement equipment settings for UT-WLCSPs, and care should be taken when handling PCBs with UT-WLCSPs attached.

1.5 Typical Solder Reflow Profile

For information, see *Typical Solder Reflow Profile for Lead-free Devices Information Note*.

2 Bluetooth Modem

2.1 RF Ports

CSR1013 WLCSP contains an integrated balun which provides a single-ended RF TX / RX port pin. No matching components are needed as the receive mode impedance is 50Ω and the transmitter has been optimised to deliver power in to a 50Ω load.

2.2 RF Receiver

The receiver features a near-zero IF architecture that allows the channel filters to be integrated onto the die. Sufficient out-of-band blocking specification at the LNA input allows the receiver to be used in close proximity to GSM and W-CDMA cellular phone transmitters without being significantly desensitised.

An ADC digitises the IF received signal.

2.2.1 Low Noise Amplifier

The LNA operates in differential mode and takes its input from the balanced port of the integrated balun.

2.2.2 RSSI Analogue to Digital Converter

The ADC samples the RSSI voltage on a packet-by-packet basis and implements a fast AGC. The front-end LNA gain is changed according to the measured RSSI value, keeping the first mixer input signal within a limited range. This improves the dynamic range of the receiver, improving performance in interference-limited environments.

2.3 RF Transmitter

2.3.1 IQ Modulator

The transmitter features a direct IQ modulator to minimise frequency drift during a transmit packet, which results in a controlled modulation index. Digital baseband transmit circuitry provides the required spectral shaping.

2.3.2 Power Amplifier

The internal PA has a maximum 9.0dBm output power without needing an external RF PA.

2.4 Bluetooth Radio Synthesiser

The Bluetooth radio synthesiser is fully integrated onto the die with no requirement for an external VCO screening can, varactor tuning diodes, LC resonators or loop filter. The synthesiser is guaranteed to lock in sufficient time across the guaranteed temperature range to meet the Bluetooth v4.1 specification.

2.5 Baseband

2.5.1 Physical Layer Hardware Engine

Dedicated logic performs:

- Cyclic redundancy check
- Encryption
- Data whitening
- Access code correlation

The hardware supports all optional and mandatory features of Bluetooth v4.1 specification.

3 Clock Generation

The Bluetooth reference clock for the system is generated from an external 16MHz clock source, see Figure 3.1. All the CSR1013 WLCSP internal digital clocks are generated using a phase locked loop, which is locked to the frequency of either the external reference clock source or a sleep clock frequency of 32.768kHz, see Figure 3.1.

3.1 Clock Architecture

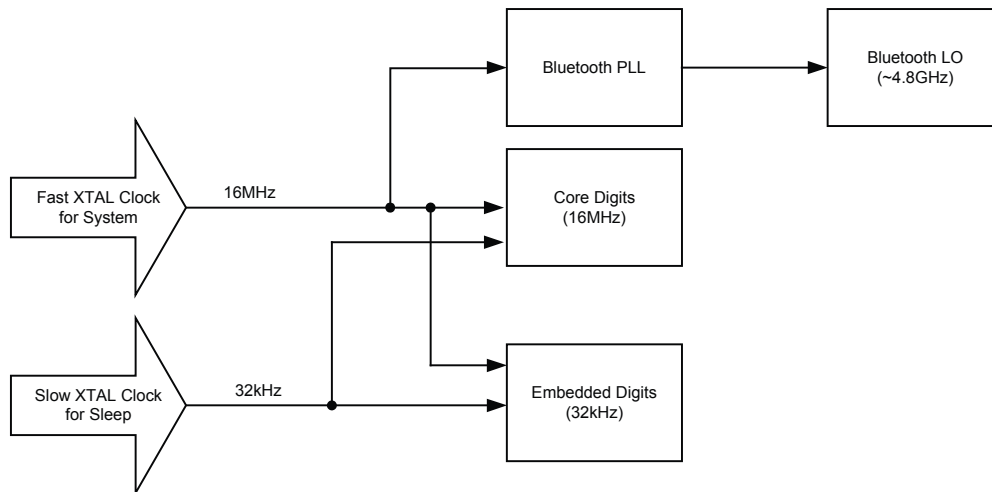


Figure 3.1: Clock Architecture

3.2 Crystal Oscillator: XTAL_16M_IN and XTAL_16M_OUT

CSR1013 WLCSP contains crystal driver circuits. This operates with an external crystal and capacitors to form a Pierce oscillator. Figure 3.2 shows the external crystal is connected to pins XTAL_16M_IN and XTAL_16M_OUT.

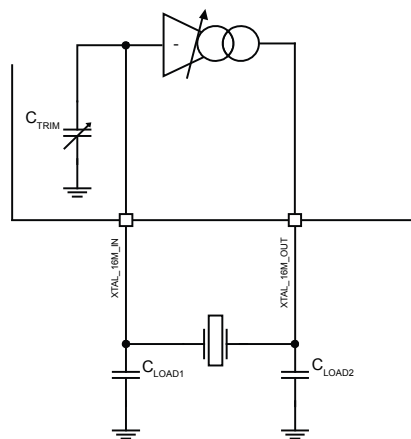


Figure 3.2: Crystal Driver Circuit

Note:

C_{TRIM} is the internal trimmable capacitance in Table 3.1.

C_{LOAD1} and C_{LOAD2} in combination with C_{TRIM} and any parasitic capacitance provide the load capacitance required by the crystal.

3.2.1 Crystal Specification

Table 3.1 shows the specification for an external crystal.

Parameter	Min	Typ	Max	Unit
Frequency	-	16	-	MHz
Frequency tolerance (without trimming) ^(a)	-	-	±25	ppm
Frequency trim range ^(b)	-	±50	-	ppm
Drive level	-	0.4	-	V
Equivalent series resistance	-	-	60	Ω
Load capacitance	-	9	-	pF
Pullability	10	-	-	ppm/pF

Table 3.1: Crystal Specification

^(a) Use integrated load capacitors to trim initial frequency tolerance in production or to trim frequency over temperature, increasing the allowable frequency tolerance.

^(b) Frequency trim range is dependent on crystal load capacitor values and crystal pullability.

3.2.2 Frequency Trim

CSR1013 WLCSP contains variable integrated capacitors to allow for fine-tuning of the crystal resonant frequency. This firmware-programmable feature allows accurate trimming of crystals on a per-device basis on the production line. The resulting trim value is stored in non-volatile memory.

3.3 Sleep Clock

The sleep clock is an externally provided 32.768kHz clock that is used during deep sleep and in other low-power modes. Figure 3.3 shows the sleep clock crystal driver circuit.

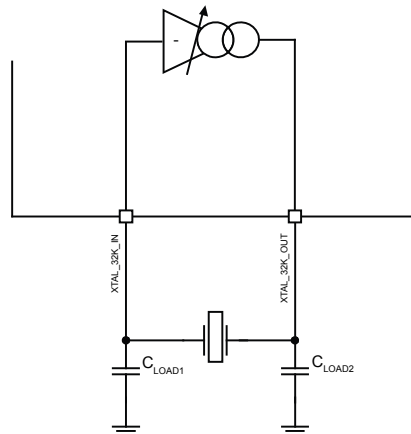


Figure 3.3: Sleep Clock Crystal Driver Circuit

Note:

C_{LOAD1} and C_{LOAD2} in combination with any parasitic capacitance provide the load capacitance required by the crystal.

3.3.1 Crystal Specification

Table 3.2 shows the requirements for the sleep clock.

G-TW-0005349.2.2

Sleep Clock	Min	Typ	Max	Units
Frequency	30	32.768	35	kHz
Frequency tolerance ^(a) ^(b)	-	-	250	±ppm
Frequency trim range	-	50	-	±ppm
Drive level	-	0.4	-	V
Load capacitance	-	-	10	pF
Equivalent series resistance	40	-	65	kΩ
Duty cycle	30:70	50:50	70:30	%

Table 3.2: Sleep Clock Specification

^(a) The frequency of the slow clock is periodically calibrated against the system clock. As a result the rate of change of the frequency is more important than the maximum deviation. To meet the accuracy requirements the frequency should not drift due to temperature or other effects by more than 80ppm in any 5 minute period.

^(b) CSR1013 WLCSP can correct for ±1% by using the fast clock to calibrate the slow clock.

4 Operating Modes

CSR1013 WLCSP has 5 operating modes. 3 of these are sleep modes:

- Running
- Idle
- Sleep modes:
 - Deep Sleep
 - Hibernate
 - Dormant

For current consumption rates in the operating modes, see Section 10.

4.1 Run Mode

In Run mode, all functions are on. RX and/or TX are active.

4.2 Idle Mode

In Idle mode, the VDD_PADS and VDD_BAT domains are powered, the reference clock and the sleep clock are powered, the RAM is powered and the digital circuits are powered. The MCU is idle.

There is a $<1\mu\text{s}$ wake-up time.

4.3 Deep Sleep Mode

In Deep Sleep mode, the VDD_PADS and VDD_BAT domains are powered, the sleep clock is on but the reference clock is off, the RAM is on, the digital circuits are on and the SMPS is on (low-power mode). There is a configurable wake-up time.

CSR1013 WLCSP is woken from Deep Sleep mode by any PIO configured to wake the IC.

4.4 Hibernate Mode

In Hibernate mode, the VDD_PADS and VDD_BAT domains are powered and the sleep clock is on. The reference clock is off.

CSR1013 WLCSP is woken from Hibernate mode by a selected level on the WAKE pin or by the watchdog timer.

4.5 Dormant Mode

In Dormant mode, all functions are off. CSR1013 WLCSP is woken from Dormant mode by a selected level on the WAKE pin.

5 Microcontroller, Memory and Baseband Logic

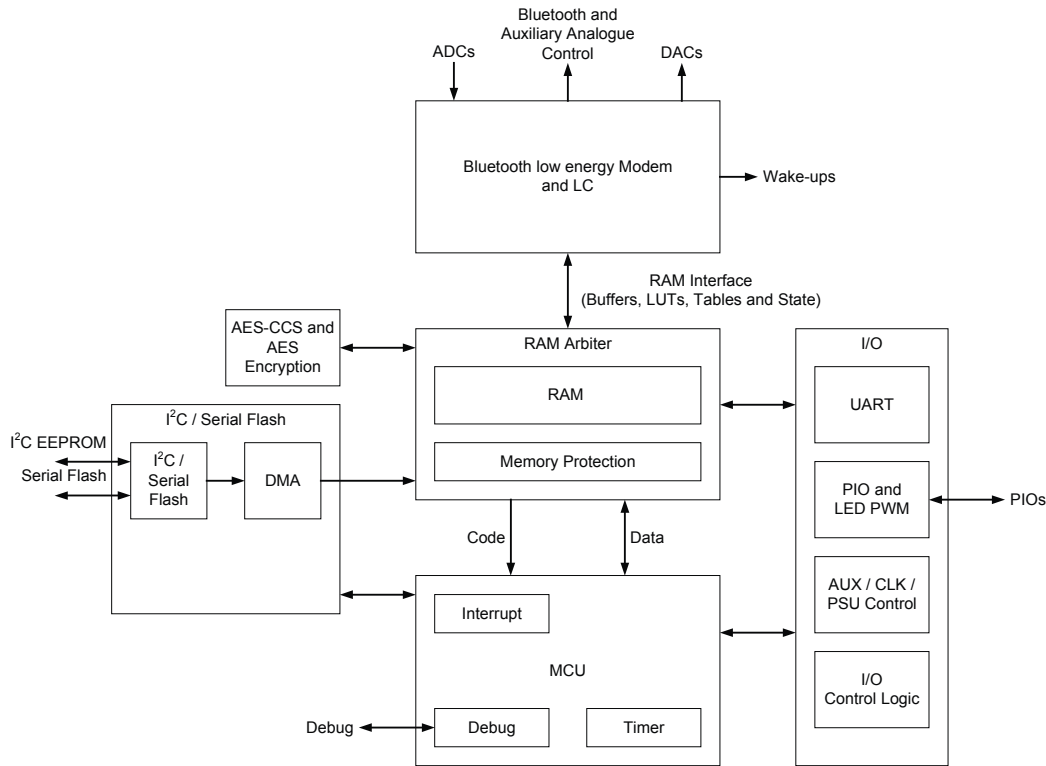


Figure 5.1: Baseband Digits Block Diagram

5.1 System RAM

64KB of integrated RAM supports the RISC MCU and is shared between the ring buffers used to hold data for each active connection, general-purpose memory required by the Bluetooth stack and the user application.

5.2 Internal ROM

CSR1013 WLCSP has 64KB of internal ROM. This memory is provided for system firmware implementation. If the internal ROM holds valid program code, on boot-up, this is copied into the program RAM. Code then executes from ROM and RAM.

5.3 Microcontroller

The MCU, interrupt controller and event timer run the Bluetooth software stack and control the Bluetooth radio and external interfaces. A 16-bit RISC microcontroller is used for low power consumption and efficient use of memory.

5.4 Programmable I/O Ports, PIO and AIO

12 lines of programmable bidirectional I/O are provided. They are all powered from VDD_PADS.

PIO lines are software-configurable as weak pull-up, weak pull-down, strong pull-up or strong pull-down.

Note:

At reset all PIO lines are inputs with weak pull-downs.

Any of the PIO lines can be configured as interrupt request lines or to wake the IC from deep sleep mode. Table 5.1 lists the options for waking the IC from the sleep modes.

Sleep Mode	Wake-up Options
Dormant	Can only be woken by the WAKE pin.
Hibernate	Can be woken by the WAKE pin or by the watchdog timer.
Deep Sleep	Can be woken by any PIO configured to wake the IC.

Table 5.1: Wake Options for Sleep Modes

The CSR1013 WLCSP supports alternative functions on the PIO lines, for example:

- SPI interface, see Section 1.2 and Section 6.4
- UART, see Section 1.2 and Section 6.1.1
- LED flasher / PWM module, see Section 5.5

Table 5.2 shows the alternative functions on the PIO lines.

PIO	Function		
	Debug SPI	SPI Flash	UART
PIO[8]	DEBUG_MISO	-	-
PIO[7]	DEBUG_MOSI	-	-
PIO[6]	DEBUG_CS#	-	-
PIO[5]	DEBUG_CLK	-	-
PIO[4]	-	SF_CS#	-
PIO[3]	-	SF_DIN	-
PIO[2]	-	-	-
PIO[1]	-	-	UART_RX
PIO[0]	-	-	UART_TX

Table 5.2: Alternative PIO Functions

Note:

CSR cannot guarantee that the PIO assignments remain as described. Implementation of the PIO lines is firmware build-specific, for more information see the relevant software release note.

CSR1013 WLCSP has 1 general-purpose analogue interface pins, AIO[0].

5.5 LED Flasher / PWM Module

CSR1013 WLCSP contains an LED flasher / PWM module.

Note:

The LED flasher functions in Deep Sleep and Active modes only.

The PWM functions in all modes except Hibernate and Dormant.

These functions are controlled by the on-chip firmware.

Figure 5.2 shows a typical PWM signal on a PIO. For more information, see *CSR μEnergy Pulse Width Modulation Application Note*.

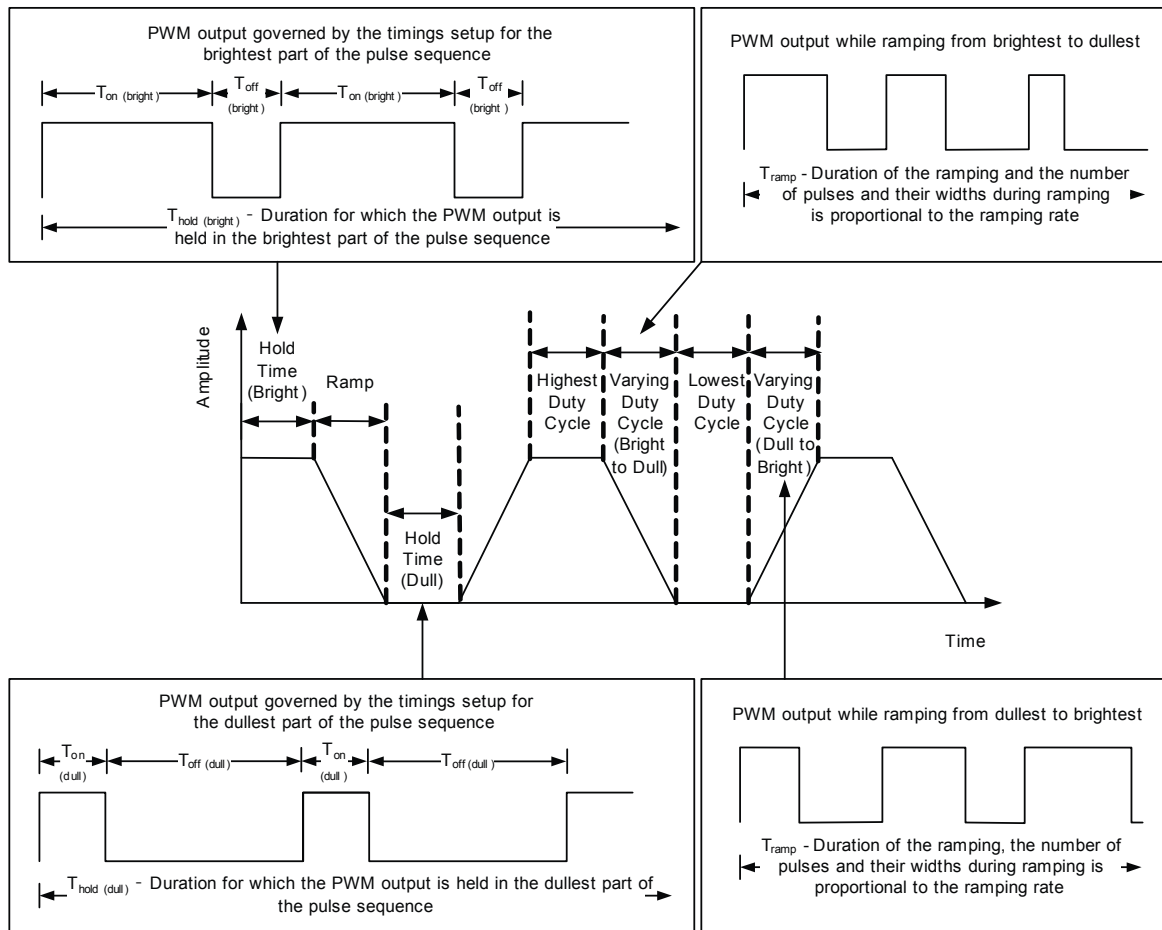


Figure 5.2: Typical PWM Signal on a PIO

Figure 5.2 lists PWM the operating range.

Parameter	Min	Max	Unit
Off Time (T_{off})	30.5	7782	μ s
On Time (T_{on})	30.5	7782	μ s
Hold Time (T_{hold})	16	4080	ms
Duty Cycle = On Time (T_{on}) + Off Time (T_{off})	61	15564	μ s
Frequency = 1 / Duty Cycle	64.3	16320	Hz

Table 5.3: PWM Operating Range

5.6 Temperature Sensor

CSR1013 WLCSP contains a temperature sensor that measures the temperature of the die to an accuracy of ± 1 °C.



5.7 Battery Monitor

CSR1013 WLCSP contains an internal battery monitor that reports the battery voltage to the software.

6 Serial Interfaces

6.1 Application Interface

6.1.1 UART Interface

The CSR1013 WLCSP UART interface provides a simple mechanism for communicating with other serial devices using the RS232 protocol.

2 signals implement the UART function, UART_TX and UART_RX. When CSR1013 WLCSP is connected to another digital device, UART_RX and UART_TX transfer data between the 2 devices.

UART configuration parameters, e.g. baud rate and data format, are set using CSR1013 WLCSP firmware.

When selected in firmware PIO[0] is assigned to a UART_TX output and PIO[1] is assigned to a UART_RX input, see Section 1.2.

Note:

To communicate with the UART at its maximum data rate using a standard PC, the PC requires an accelerated serial port adapter card.

Table 6.1 shows the possible UART settings for the CSR1013 WLCSP.

Parameter		Possible Values
Baud rate	Minimum	2400 baud ($\leq 2\%$ Error)
		9600 baud ($\leq 2\%$ Error)
	Maximum	3.69Mbaud ($\leq 0.1\%$ Error)
Parity		None, Odd or Even
Number of stop bits		1 or 2
Bits per byte		8

Table 6.1: Possible UART Settings

6.1.1.1 UART Configuration While in Deep Sleep

The maximum baud rate is 2400 baud during deep sleep.

6.2 I²C Interface

The I²C interface communicates to EEPROM, external peripherals or sensors. An external EEPROM connection can hold the program code externally to the CSR1013 WLCSP.

Figure 6.1 shows an example of an EEPROM connected to the I²C interface where I2C_SCL, I2C_SDA and PIO[2] are connected to the external EEPROM. The PIO[2] pin supplies the power to the EEPROM supply pin, e.g. VDD. At boot-up, if there is no valid ROM image in the CSR1013 WLCSP ROM area the CSR1013 WLCSP tries to boot from the I²C interface, see Figure 6.5. This involves reading the code from the external EEPROM and loading it into the internal CSR1013 WLCSP RAM.

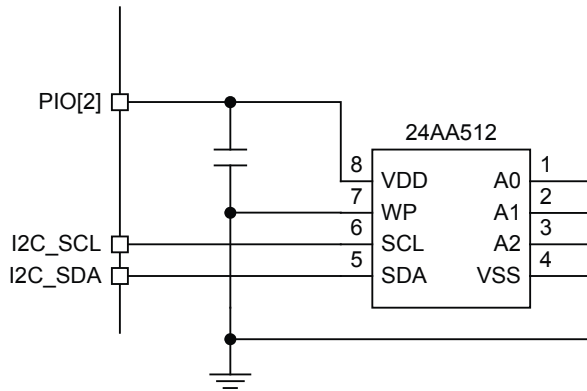


Figure 6.1: Example of an I²C Interface EEPROM Connection

Standard Mode 100 kHz

Figure 6.2 shows I²C standard mode 100 kHz timing diagram.

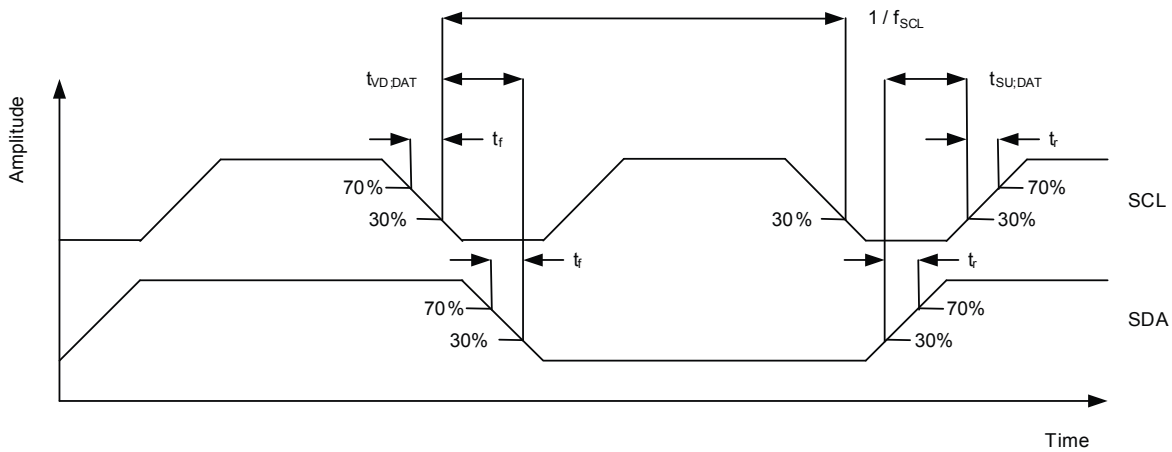


Figure 6.2: I²C Standard Mode 100 kHz Timing Diagram (Top Line: SCL, Bottom Line: SDA)

Table 6.2 lists I²C standard mode 100 kHz timing definition.

Parameter	Symbol	Min	Max	Unit
Clock Rate	f_{SCL}	-	100	kHz
SCL: Rise-time (30% to 70%)	t_r	-	50.3	ns
SCL: Fall-time (70% to 30%)	t_f	-	0.9	ns
SDA: Rise-time (30% to 70%)	t_r	-	55.3	ns
SDA: Fall-time (70% to 30%)	t_f	-	0.7	ns
Data set-up time	$t_{SU,DAT}$	2511	-	ns
Data valid time	$t_{VD,DAT}$	-	2.5	μ s

Table 6.2: I²C Standard Mode 100 kHz Timing Definition

Fast Mode 400 kHz

Figure 6.3 shows I²C fast mode 400 kHz timing diagram.

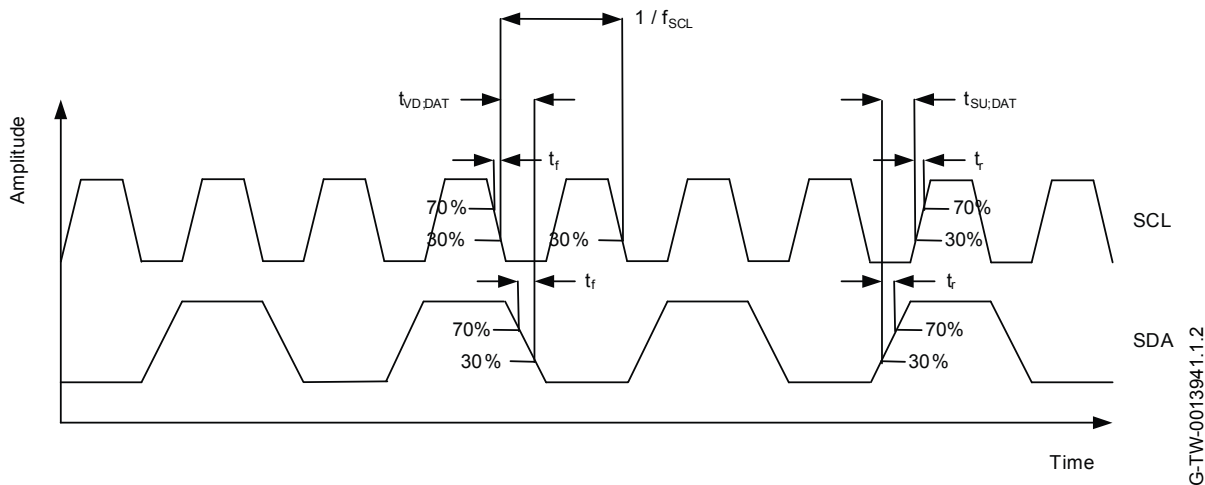


Figure 6.3: I²C Fast Mode 400 kHz Timing Diagram (Top Line: SCL, Bottom Line: SDA)

Table 6.3 lists I²C fast mode 400 kHz timing definition.

Parameter	Symbol	Min	Max	Unit
Clock Rate	f_{SCL}	-	400	kHz
SCL: Rise-time (30% to 70%)	t_r	41.4	50.6	ns
SCL: Fall-time (70% to 30%)	t_f	0.7	0.9	ns
SDA: Rise-time (30% to 70%)	t_r	46.0	55.9	ns
SDA: Fall-time (70% to 30%)	t_f	0.5	0.7	ns
Data set-up time	$t_{SU,DAT}$	573	-	ns
Data valid time	$t_{VD,DAT}$	-	0.56	μ s

Table 6.3: I²C Fast Mode 400 kHz Timing Definition

6.3 SPI Master Interface

The SPI master memory interface in the CSR1013 WLCSP is overlaid on the I²C interface and uses a further 3 PIOs for the extra pins, see Table 6.4.

SPI Flash Interface	Pin
Flash_VDD	PIO[2]
SF_DIN	PIO[3]
SF_CS#	PIO[4]
SF_CLK	I2C_SCL
SF_DOUT	I2C_SDA

Table 6.4: SPI Master Serial Flash Memory Interface

Note:

If an application using CSR1013 WLCSP is designed to boot from SPI serial flash, it is possible for the firmware to map the I²C interface to alternative PIOs.

Figure 6.4 shows simple SPI timing diagram.

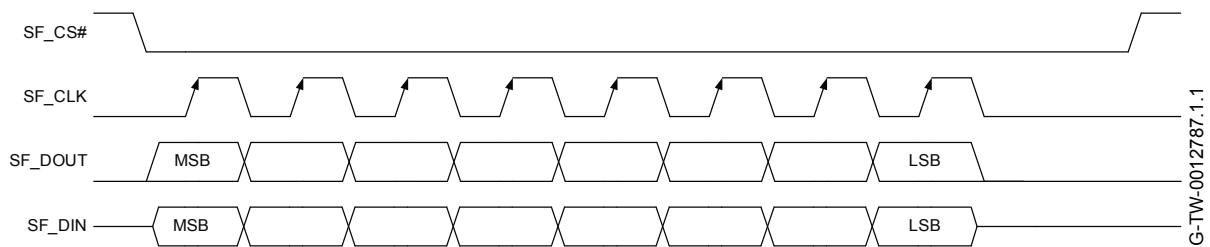
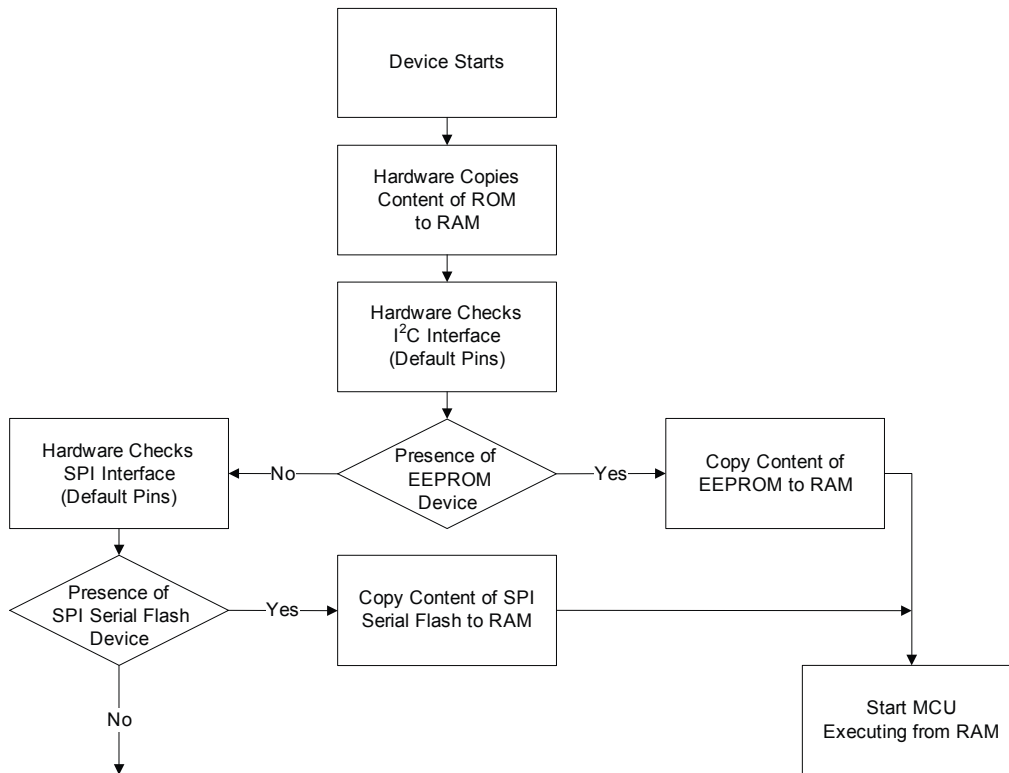


Figure 6.4: SPI Timing Diagram

The boot-up sequence for CSR1013 WLCSP is controlled by hardware and firmware. Figure 6.5 shows the sequence of loading RAM with content from RAM, EEPROM and SPI serial flash.



G-TW-0005552.3.2

Figure 6.5: Memory Boot-up Sequence

6.4 Programming and Debug Interface

Important Note:

The CSR1013 WLCSP debug SPI interface is available in SPI slave mode to enable an external MCU to program and control the CSR1013 WLCSP, generally via libraries or tools supplied by CSR. The protocol of this interface is proprietary. The 4 SPI debug lines directly support this function.

The SPI programs, configures and debugs the CSR1013 WLCSP. It is required in production. Ensure the 4 SPI signals are brought out to either test points or a header.

Take SPI_PIO#_SEL high to enable the SPI debug feature on PIO[8:5].

CSR1013 WLCSP uses a 16-bit data and 16-bit address programming and debug interface. Transactions occur when the internal processor is running or is stopped.

Data is written or read one word at a time. Alternatively, the auto-increment feature is available for block access.

6.4.1 Instruction Cycle

The CSR1013 WLCSP is the slave and receives commands on DEBUG_MOSI and outputs data on DEBUG_MISO. Table 6.5 shows the instruction cycle for a SPI transaction.

1	Reset the SPI interface	Hold DEBUG_CS# high for 2 DEBUG_CLK cycles
2	Write the command word	Take DEBUG_CS# low and clock in the 8-bit command
3	Write the address	Clock in the 16-bit address word
4	Write or read data words	Clock in or out 16-bit data word(s)
5	Termination	Take DEBUG_CS# high

Table 6.5: Instruction Cycle for a SPI Transaction

With the exception of reset, DEBUG_CS# must be held low during the transaction. Data on DEBUG_MOSI is clocked into the CSR1013 WLCSP on the rising edge of the clock line DEBUG_CLK. When reading, CSR1013 WLCSP replies to the master on DEBUG_MISO with the data changing on the falling edge of the DEBUG_CLK. The master provides the clock on DEBUG_CLK. The transaction is terminated by taking DEBUG_CS# high.

The auto increment operation on the CSR1013 WLCSP cuts down on the overhead of sending a command word and the address of a register for each read or write, especially when large amounts of data are to be transferred. The auto increment offers increased data transfer efficiency on the CSR1013 WLCSP. To invoke auto increment, DEBUG_CS# is kept low, which auto increments the address, while providing an extra 16 clock cycles for each extra word written or read.

6.4.2 Multi-slave Operation

Do not connect the CSR1013 WLCSP in a multi-slave arrangement by simple parallel connection of slave MISO lines. When CSR1013 WLCSP is deselected (DEBUG_CS# = 1), the DEBUG_MISO line does not float. Instead, CSR1013 WLCSP outputs 0 if the processor is running or 1 if it is stopped.

7 Power Control and Regulation

CSR1013 WLCSP contains 2 regulators:

- 1 switch-mode regulator, which generates the main supply rail from the battery
- 1 low-voltage linear regulator

Figure 7.1 shows the configuration for the power control and regulation with the CSR1013 WLCSP.

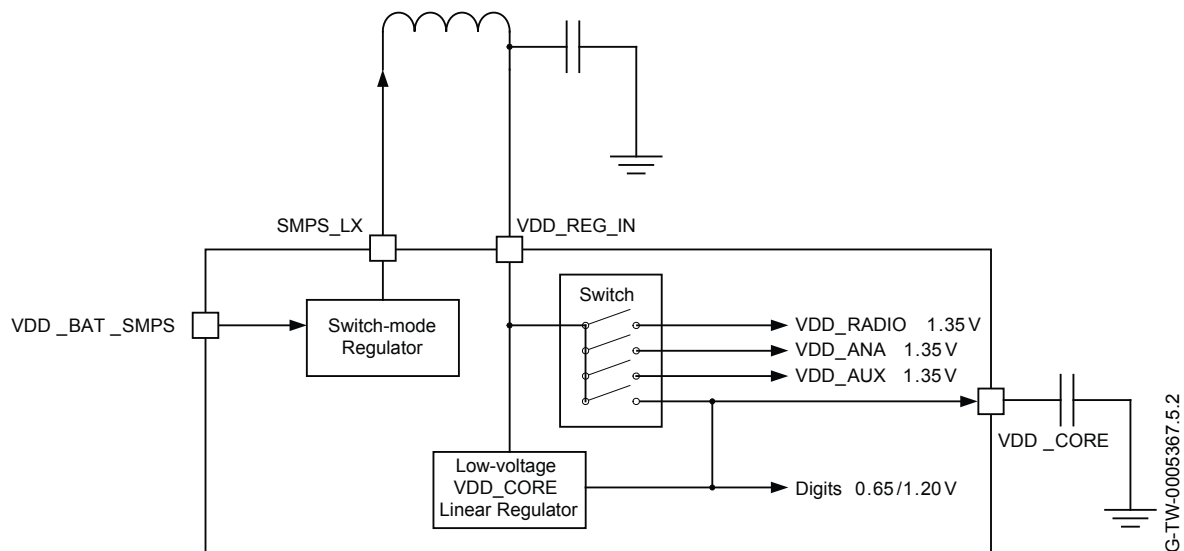


Figure 7.1: Voltage Regulator Configuration

7.1 Switch-mode Regulator

The switch-mode regulator generates the main rail from the battery supply, VDD_BAT_SMPS. The main rail supplies the lower regulated voltage to a further digital linear regulator and also to the analogue sections of the CSR1013 WLCSP.

The switch-mode regulator generates typically 1.35V.

7.2 Low-voltage VDD_CORE Linear Regulator

The integrated low-voltage VDD_CORE linear regulator powers the CSR1013 WLCSP digital circuits. The input voltage range is 0.65V to 1.35V. It can supply programmable voltages of 0.65V to 1.20V to the digital area of the CSR1013 WLCSP. The maximum output current for this regulator is 30mA.

Connect a minimum 470nF low ESR capacitor, e.g. MLC, to the VDD_CORE output pin. Software controls the output voltage.

Important Note:

This regulator is only for CSR internal use. Section 8 shows CSR's recommended circuit connection.

7.3 Reset

CSR1013 WLCSP is reset by:

- Power-on reset
- Software-configured watchdog timer

7.3.1 Digital Pin States on Reset

Table 7.1 shows the pin states of CSR1013 WLCSP on reset. PU and PD default to weak values unless specified otherwise.

Pin Name / Group	On Reset
I2C_SDA	Strong PU
I2C_SCL	Strong PU
PIO[11:0]	Weak PD
AIO[2:0]	Weak PU

Table 7.1: Pin States on Reset

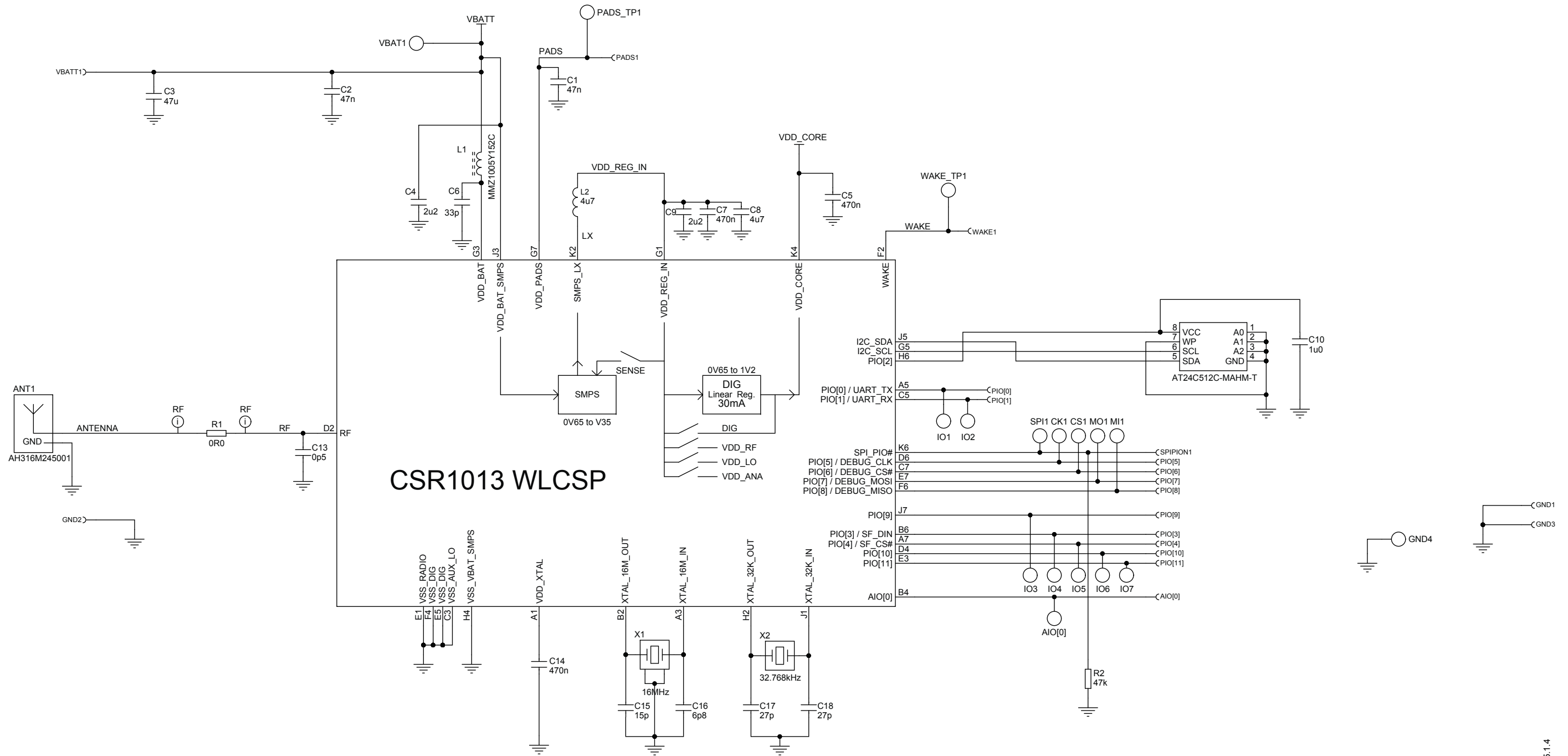
7.3.2 Power-on Reset

Table 7.2 shows how the power-on reset occurs.

Power-on Reset	Typ	Unit
Reset release on VDD_CORE rising	1.05	V
Reset assert on VDD_CORE falling	1.00	
Reset assert on VDD_CORE falling (Sleep mode)	0.60	
Hysteresis	50	mV

Table 7.2: Power-on Reset

8 Example Application Schematic



9 Electrical Characteristics

9.1 Absolute Maximum Ratings

Rating	Min	Max	Unit
Storage temperature	-40	85	°C
Battery (VDD_BAT) operation	1.8	4.4	V
I/O supply voltage	-0.4	4.4	V
Other terminal voltages ^(a)	VSS - 0.4	VDD + 0.4	V

^(a) VDD = Terminal Supply Domain

9.2 Recommended Operating Conditions

Operating Condition	Min	Typ	Max	Unit
Operating temperature range	-30	-	85	°C
Battery (VDD_BAT) operation ^{(a) (b)}	1.8	-	3.6	V
I/O supply voltage (VDD_PADS) ^(c)	1.2	-	3.6	V

^(a) CSR1013 WLCSP is reliable and qualifiable to 4.3V (idle, active and deep sleep modes) and 3.8V (all modes), but there are minor deviations in performance relative to published performance values for 1.8V to 3.6V. For layout guidelines for 4.3V operation, see *CSR1013 Hardware Design Review Template*.

^(b) For hibernate and dormant mode, see *Customer Advisory: Use of CSR101x at Operating Voltages Above 3.6V*.

^(c) Safe to 4.3V if VDD_BAT = 4.3V.

9.3 Input/Output Terminal Characteristics

9.3.1 Switch-mode Regulator

Switch-mode Regulator	Min	Typ	Max	Unit
Input voltage ^(a)	1.8	-	3.6	V
Output voltage ^(b)	-	1.35	-	V
Temperature coefficient	-200	-	200	ppm/°C
Normal Operation				
Output noise, frequency range 100Hz to 100kHz	-	-	0.4	mV rms
Settling time, settling to within 10% of final value	-	-	30	µs
Output current (I_{max})	-	-	50	mA
Quiescent current (excluding load, $I_{load} < 1mA$)	-	-	20	µA
Ultra Low-power Mode				
Output current (I_{max})	-	-	100	µA
Quiescent current	-	-	1	µA

^(a) CSR1013 WLCSP is reliable and qualifiable to 4.3V (idle, active and deep sleep modes) and 3.8V (all modes), but there are minor deviations in performance relative to published performance values for 1.8V to 3.6V. For layout guidelines for 4.3V operation, see *CSR1013 Hardware Design Review Template*.

^(b) During Run mode, see Section 4.1.

9.3.2 Low-voltage Linear Regulator

Normal Operation	Min	Typ	Max	Unit
Input voltage	0.65	-	1.35	V
Output voltage	0.65	-	1.20	V

Important Note:

This regulator is only for CSR internal use. Section 8 shows CSR's recommended circuit connection.

9.3.3 Digital Terminals

Input Voltage Levels	Min	Typ	Max	Unit
V_{IL} input logic level low	-0.4	-	0.3 x VDD_PADS	V
V_{IH} input logic level high	0.7 x VDD_PADS	-	VDD_PADS + 0.4	V
T_r/T_f	-	-	25	ns

Output Voltage Levels	Min	Typ	Max	Unit
V_{OL} output logic level low, $I_{OL} = 4.0\text{mA}$	-	-	0.4	V
V_{OH} output logic level high, $I_{OH} = -4.0\text{mA}$	$0.75 \times VDD_PADS$	-	-	V
T_r/T_f	-	-	5	ns

Input, Output and Tristate Currents ^(a)	Min	Typ	Max	Unit
I_{OL} output current low, V_{OL} max	-	8	10	mA
I_{OH} output current high, V_{OH} min	-	8	10	mA
With strong pull-up	-150	-40	-10	μA
I^2C with strong pull-up	-250	-	-	μA
With strong pull-down	10	40	150	μA
With weak pull-up	-5.0	-1.0	-0.33	μA
With weak pull-down	0.33	1.0	5.0	μA
C_I input capacitance	1.0	-	5.0	pF

^(a) Maximum current draw from VDD_PADS is less than 30mA depending on board design.

9.3.4 AIO

Input/Output Voltage Levels	Min	Typ	Max	Unit
Input voltage	0	-	VDD_AUX	V
Output voltage	0	-	VDD_AUX	V
Output drive strength	-	4	-	mA

9.3.4.1 Auxiliary ADC

Auxiliary ADC	Min	Typ	Max	Unit
Resolution	-	-	10	Bits
Input voltage range ^(a)	0	-	VDD_AUX	V
Accuracy	INL	-3	3	LSB
	DNL	-3	3	LSB

Auxiliary ADC	Min	Typ	Max	Unit
Offset	-1	-	1	LSB
Gain error	-0.8	-	0.8	%
Input bandwidth	-	100	-	kHz
Conversion time (measured at application)	-	46	-	µs
Sample rate ^(b)	-	-	21000	Samples/s
ADC block conversion current	-	410	-	µA

^(a) LSB size = VDD_AUX/1023

^(b) The auxiliary ADC is accessed through the firmware API. The sample rate given is achieved as part of this function.

9.3.4.2 Auxiliary DAC

Auxiliary DAC	Min	Typ	Max	Unit
Resolution	-	-	10	Bits
Supply voltage, VDD_ANA	1.30	1.35	1.40	V
Output voltage range	0	-	VDD_AUX	V
Full-scale output voltage	1.30	1.35	1.40	V
LSB size	0	1.32	2.64	mV
Offset	-1.32	0	1.32	mV
Integral non-linearity	-3	0	3	LSB
Settling time	-	-	250	ns

Important Note:

Access to the auxiliary DAC is firmware-dependent, for more information about its availability contact CSR.

9.4 Junction Temperature

Table 9.1 lists the junction temperature when the device is operating within recommended operating conditions.

Parameter	Min	Typ	Max	Unit
Junction temperature	-	-	125	°C

Table 9.1: Junction Temperature within Recommended Operating Conditions

9.5 ESD Protection

Apply ESD static handling precautions during manufacturing.

Table 9.2 shows the ESD handling maximum ratings.

Condition	Class	Max Rating
Charged Device Model Contact Discharge per JEDEC EIA/JESD22-C101	C2	1000V (all pins)

Table 9.2: ESD Handling Ratings

10 Current Consumption

Table 10.1 shows CSR1013 WLCSP total typical current consumption measured at the battery.

Mode	Description	Total Typical Current at 3.0V
Dormant	All functions are shut down. To wake them up, toggle the WAKE pin.	<900nA
Hibernate	VDD_PADS = OFF, REFCLK = OFF, SLEEPCLK = ON, VDD_BAT = ON	<1.9µA
Deep sleep	VDD_PADS = ON, REFCLK = OFF, SLEEPCLK = ON, VDD_BAT = ON, RAM = ON, digital circuits = ON, SMPS = ON (low-power mode), 2.2ms wake-up time	<5µA
Idle	VDD_PADS = ON, REFCLK = ON, SLEEPCLK = ON, VDD_BAT = ON, RAM = ON, digital circuits = ON, MCU = IDLE, <1µs wake-up time	~1mA
RX active	-	~20mA @ 3.0V peak current
TX active	-	~18mA @ 3.0V peak current

Table 10.1: Current Consumption

Note:

Current consumption measurements were made:

- At 20°C and with 3.0V VBAT.
- For the whole chip: including radio, microcontroller and necessary peripherals.
- Using SDK 2.4.3.

11 CSR Green Semiconductor Products and RoHS Compliance

CSR confirms that CSR Green semiconductor products comply with the following regulatory requirements:

- Restriction of Hazardous Substances directive guidelines in the EU RoHS Directive 2011/65/EU¹.
- EU REACH, Regulation (EC) No 1907/2006¹:
 - List of substances subject to authorisation (Annex XIV)
 - Restrictions on the manufacture, placing on the market and use of certain dangerous substances, preparations and articles (Annex XVII). This Annex now includes requirements that were contained within EU Directive, 76/769/EEC. There are many substance restrictions within this Annex, including, but not limited to, the control of use of Perfluorooctane sulfonates (PFOS).
 - When requested by customers, notification of substances identified on the Candidate List as Substances of Very High Concern (SVHC)¹.
- POP regulation (EC) No 850/2004¹
- EU Packaging and Packaging Waste, Directive 94/62/EC¹
- Montreal Protocol on substances that deplete the ozone layer.
- Conflict minerals, Section 1502, Dodd-Frank Wall Street Reform and Consumer Protection act, which affects columbite-tantalite (coltan / tantalum), cassiterite (tin), gold, wolframite (tungsten) or their derivatives. CSR is a fabless semiconductor company: all manufacturing is performed by key suppliers. CSR have mandated that the suppliers shall not use materials that are sourced from "conflict zone mines" but understand that this requires accurate data from the EICC programme. CSR shall provide a complete EICC / GeSI template upon request.

CSR has defined the "CSR Green" standard based on current regulatory and customer requirements including free from bromine, chlorine and antimony trioxide.

Products and shipment packaging are marked and labelled with applicable environmental marking symbols in accordance with relevant regulatory requirements.

This identifies the main environmental compliance regulatory restrictions CSR specify. For more information on the full "CSR Green" standard, contact product.compliance@csr.com.

¹ Including applicable amendments to EU law which are published in the EU Official Journal, or SVHC Candidate List updates published by the European Chemicals Agency (ECHA).

12 CSR1013 WLCSP Software Stack

CSR1013 WLCSP is supplied with Bluetooth v4.1 specification compliant stack firmware. Figure 12.1 shows that the CSR1013 WLCSP software architecture enables the Bluetooth processing and the application program to run on the internal RISC MCU.

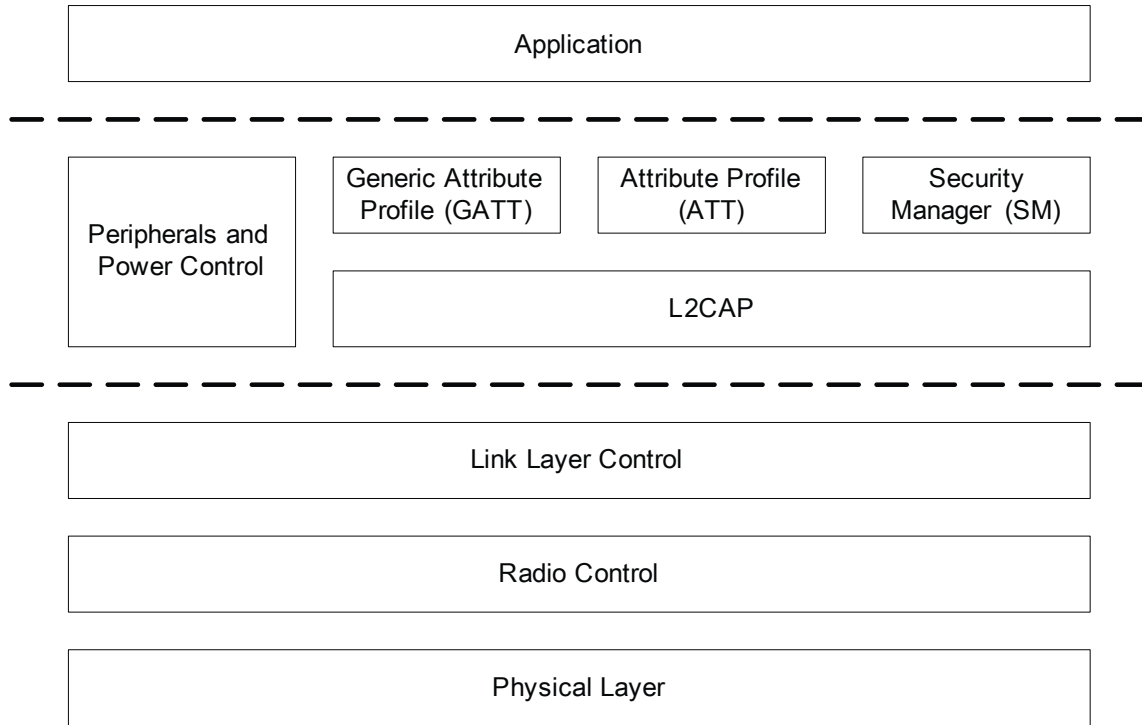


Figure 12.1: Software Architecture

G-TW-0005570.2.2

13 Tape and Reel Information

For tape and reel packing and labelling see *IC Packing and Labelling Specification*.

13.1 Tape Orientation

Figure 13.1 shows the CSR1013 WLCSP packing tape orientation.

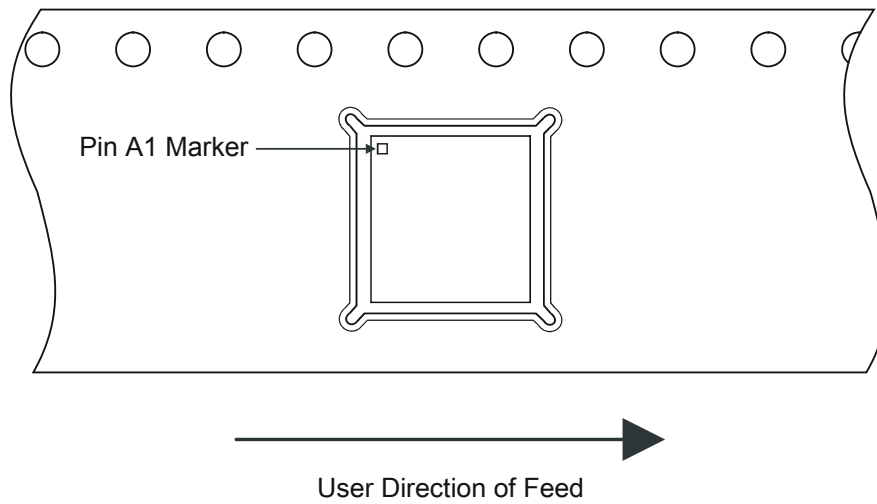
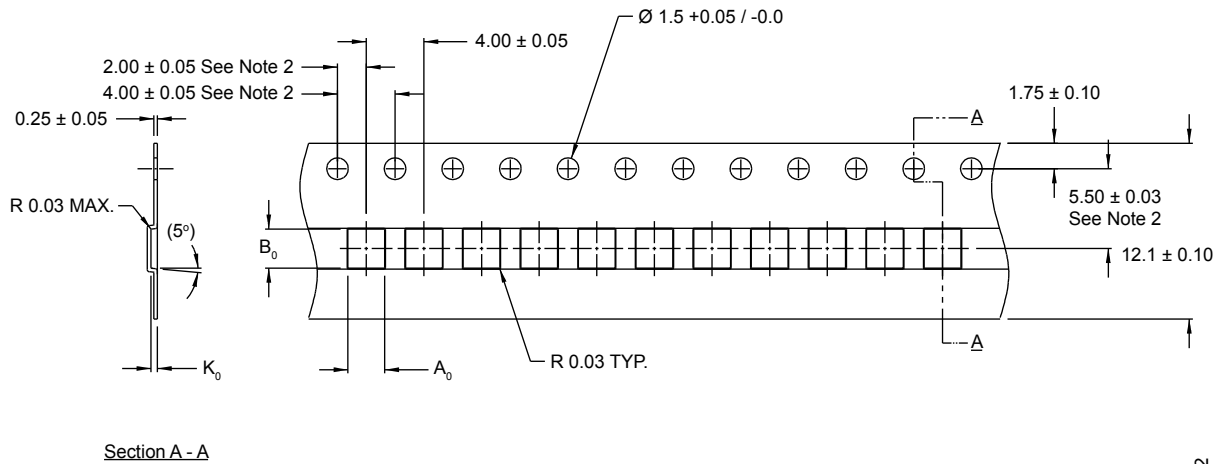


Figure 13.1: Tape Orientation

13.2 Tape Dimensions

Figure 13.2 shows the dimensions of the tape for the CSR1013 WLCSP.



G-TW-0014620.1.2

Figure 13.2: Tape Dimensions

A_0	B_0	K_0	Unit	Notes
2.55	2.70	0.45	mm	<ol style="list-style-type: none"> 10 sprocket hole pitch cumulative tolerance ± 0.1. Camber in compliance with EIA 763. Pocket position relative to sprocket hole measured as true position of pocket, not pocket hole. A_0 and B_0 are calculated on a plane at a distance "R" above the bottom of the pocket.

13.3 Reel Information

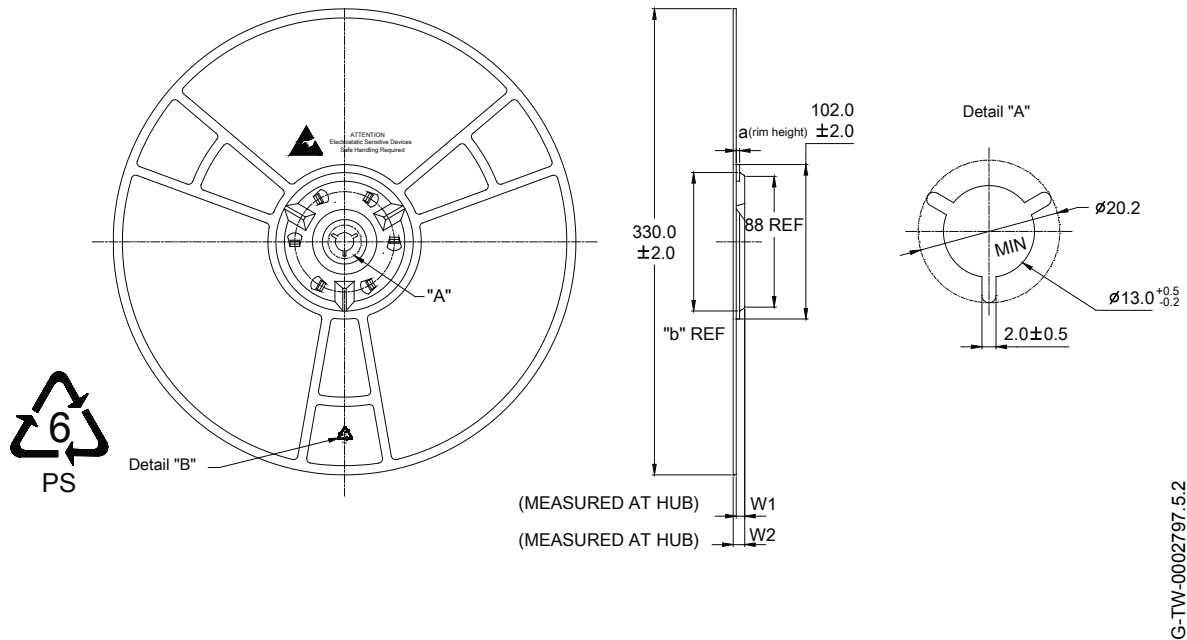


Figure 13.3: Reel Dimensions

Package Type	Nominal Hub Width (Tape Width)	a	b	W1	W2 Max	Units
2.43 x 2.56 x 0.35 mm UT-WLCSP	12	4.5	98.0	12.4 (2.0/-0.0)	18.4	mm

13.4 Moisture Sensitivity Level

CSR1013 WLCSP is qualified to moisture sensitivity level MSL1 in accordance with JEDEC J-STD-020.

14 Document References

Document	Reference, Date
<i>Core Specification of the Bluetooth System.</i>	Bluetooth Specification Version 4.1, 03 December 2013
<i>CSR1013 Hardware Design Review Template.</i>	CS-330976-DD
<i>CSR1013 WLCSP (3.3V Operation) Performance Specification .</i>	CS-332465-SP
<i>CSR1013 WLCSP (4.3V Operation) Performance Specification .</i>	CS-332466-SP
<i>Customer Advisory: Use of CSR101x at Operating Voltages Above 3.6V</i>	CS-306155-AN
<i>Electrostatic Discharge (ESD) Sensitivity Testing Human Body Model (HBM).</i>	JESD22-A114
<i>Environmental Compliance Statement for CSR Green Semiconductor Products.</i>	CB-001036-ST
<i>IC Packing and Labelling Specification.</i>	CS-112584-SP
<i>Moisture / Reflow Sensitivity Classification for Nonhermitic Solid State Surface Mount Devices.</i>	IPC / JEDEC J-STD-020
<i>Typical Solder Reflow Profile for Lead-free Devices.</i>	CS-116434-AN

Terms and Definitions

Term	Definition
AC	Alternating Current
ADC	Analogue to Digital Converter
AGC	Automatic Gain Control
AIO	Analogue Input/Output
ATT	ATTRIBUTE protocol
balun	balanced/unbalanced interface or device that changes a balanced output to an unbalanced input or vice versa
Bluetooth®	Set of technologies providing audio and data transfer over short-range radio connections
CSR	Cambridge Silicon Radio
CTE	Coefficient of Thermal Expansion
dBm	Decibels relative to 1 mW
DC	Direct Current
DNL	Differential Non Linearity (ADC accuracy parameter)
e.g.	<i>exempli gratia</i> , for example
EDR	Enhanced Data Rate
EEPROM	Electrically Erasable Programmable Read Only Memory
EIA	Electronic Industries Alliance
ESD	Electrostatic Discharge
ESR	Equivalent Series Resistance
GAP	Generic Access Profile
GATT	Generic ATTRIBUTE protocol
GSM	Global System for Mobile communications
HID	Human Interface Device
I ² C	Inter-Integrated Circuit Interface
I/O	Input/Output
IC	Integrated Circuit
IF	Intermediate Frequency
INL	Integral Non-Linearity (ADC accuracy parameter)
IQ	In-Phase and Quadrature
JEDEC	Joint Electron Device Engineering Council (now the JEDEC Solid State Technology Association)
KB	Kilobyte
L2CAP	Logical Link Control and Adaptation Protocol

Term	Definition
LC	An inductor (L) and capacitor (C) network
LED	Light-Emitting Diode
LNA	Low Noise Amplifier
LSB	Least Significant Bit (or Byte)
MAC	Medium Access Control
MCU	MicroController Unit
MISO	Master In Slave Out
MLC	MultiLayer Ceramic
MOSI	Master Out Slave In
NSMD	Non-Solder Mask Defined
OSP	Organic Solderability Preservative
PA	Power Amplifier
PC	Personal Computer
PCB	Printed Circuit Board
PD	Pull-Down
PIO	Parallel Input/Output
PIO	Programmable Input/Output, also known as general purpose I/O
plc	public limited company
ppm	parts per million
PU	Pull-Up
PWM	Pulse Width Modulation
RAM	Random Access Memory
RF	Radio Frequency
RISC	Reduced Instruction Set Computer
RoHS	Restriction of Hazardous Substances in Electrical and Electronic Equipment Directive (2002/95/EC)
ROM	Read Only Memory
RSSI	Received Signal Strength Indication
RX	Receive or Receiver
SIG	(Bluetooth) Special Interest Group
SMP	Security Manager Protocol
SMPS	Switch-Mode Power Supply
SPI	Serial Peripheral Interface

Term	Definition
TCXO	Temperature Compensated crystal Oscillator
TX	Transmit or Transmitter
UART	Universal Asynchronous Receiver Transmitter
UT-WLCSP	Ultra Thin Wafer Level Chip Scale Package
VCO	Voltage Controlled Oscillator
W-CDMA	Wideband Code Division Multiple Access