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Qualcomm

Efficient Video Perception through AI

Qualcomm Technologies, Inc.

Agenda

- The role of video in our lives
- What is video perception & what makes it challenging
- Our research toward efficient video perception
- Forward looking video perception research

A picture is worth a thousand words

Out of all the five senses, **vision**
is arguably the most important

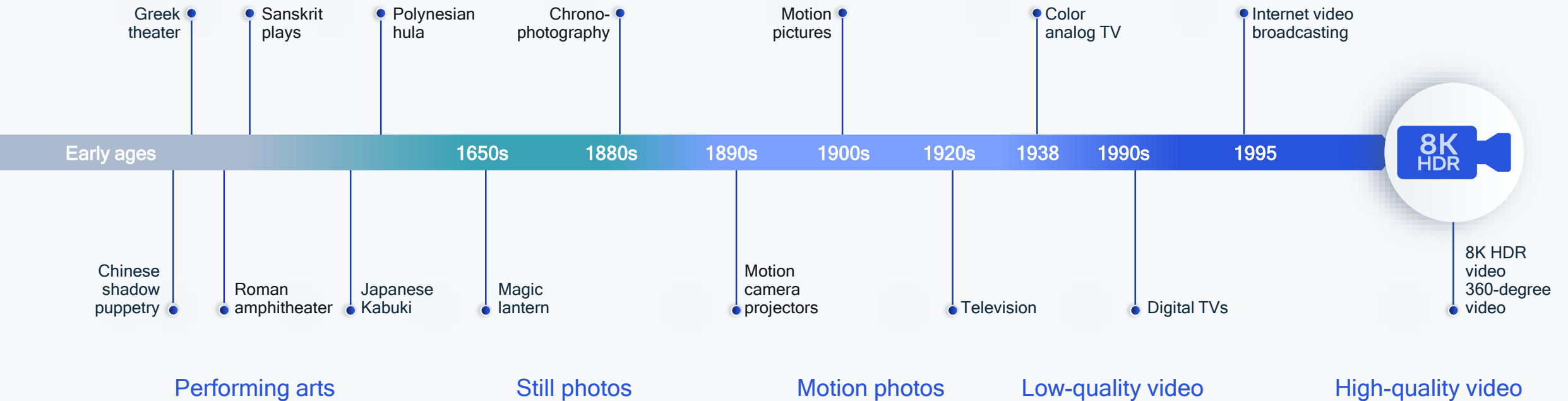


A minute of
video has
more than
1,000
pictures



How video came to be

From performing arts and still photos to high-quality video



The scale of video being created and consumed is massive

1M

Minutes of video crossing the internet per second

82%

Of all consumer internet traffic is online video

76

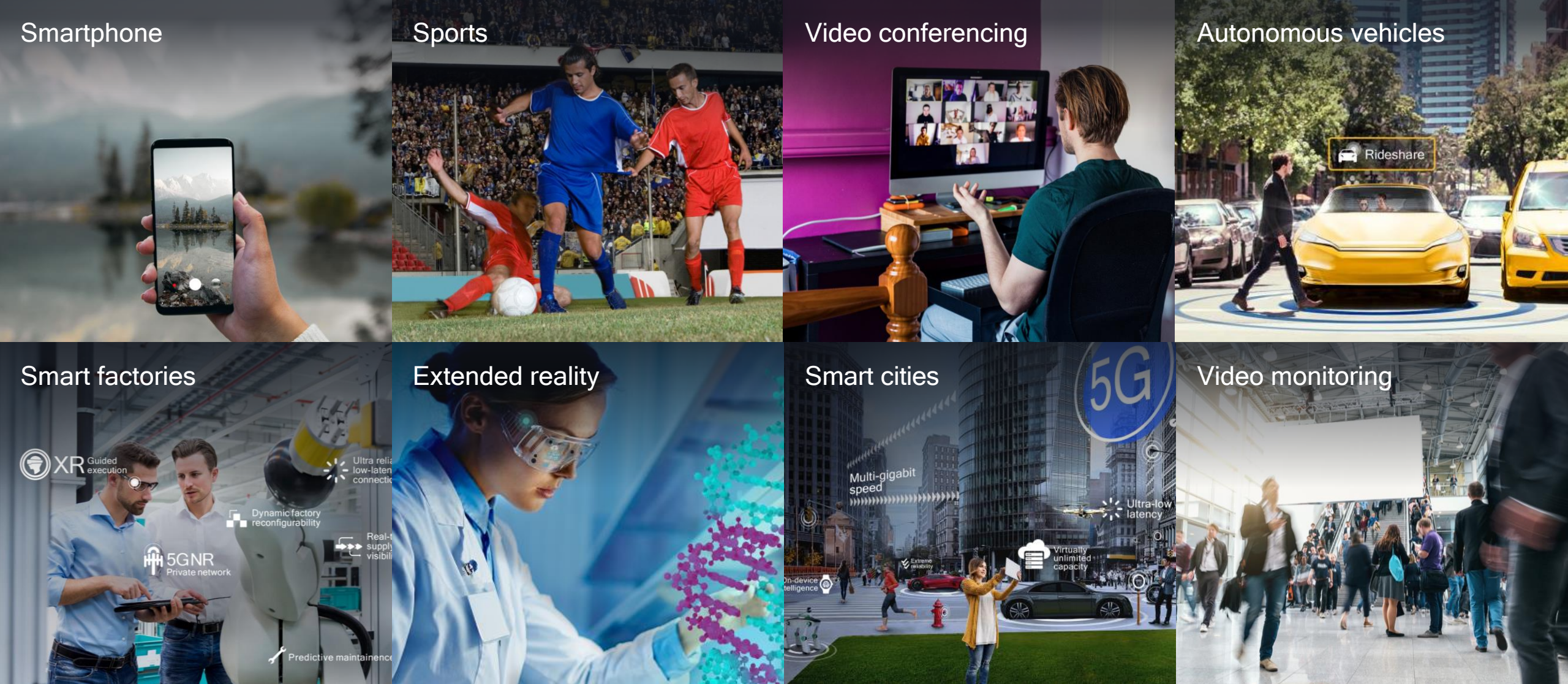
Minutes per day watching video on digital devices by US adults

8B

Average daily video views on Facebook

300

Hours of video are uploaded every minute to YouTube



Increasingly, video is all around us – providing entertainment, enhancing collaboration, and transforming industries



Video perception

Making systems
understand
video content



Making

Developing mathematical representations, models, algorithms, rules, and frameworks



Systems

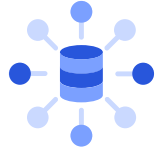
Any compute platform, including SoCs, CPUs, GPUs, TPUs, NPU, and DSPs



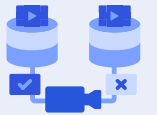
Understand

Recognizing patterns, identities, objects, scenes, context, relations, compositions, changes, motions, actions, activities, events, 3D structures, surfaces, lightings, text, emotions, sentiments, sounds, and more

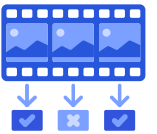
Data challenges



Diversity in visual data



Quality of data acquisition



Availability of annotated datasets

Video perception challenges



Implementation challenges

Volume of video data (training/testing)



Platform limitations



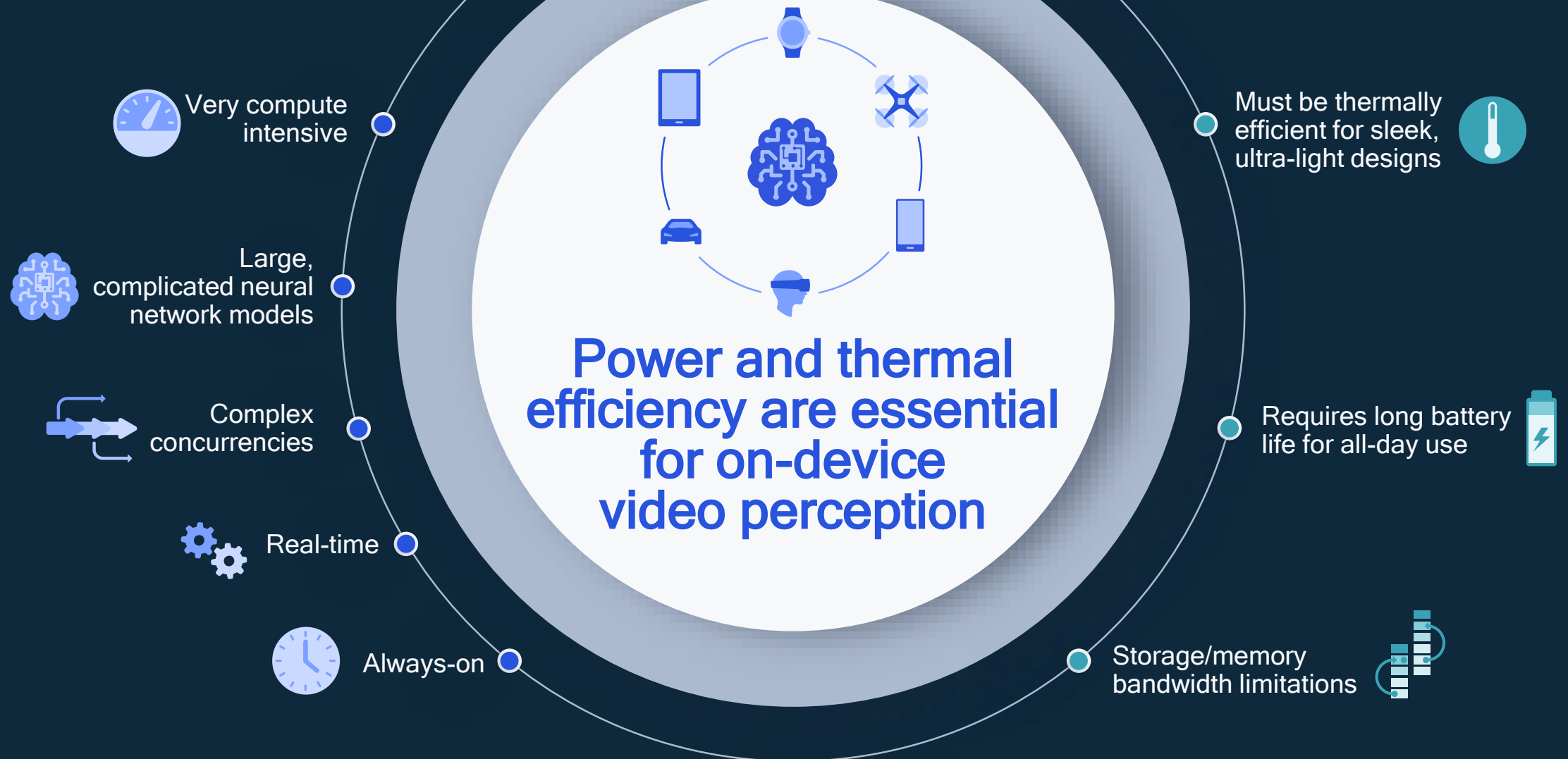
Task diversity



What makes video perception challenging?

The challenge of AI workloads

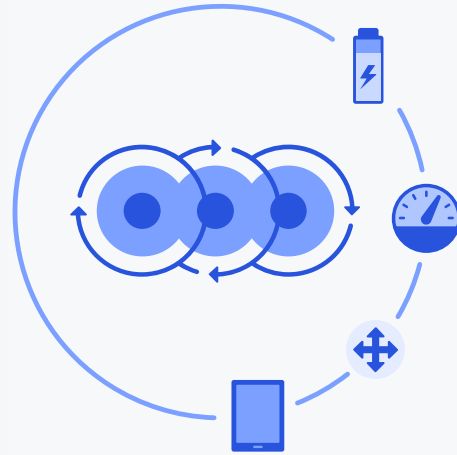
Constrained mobile environment





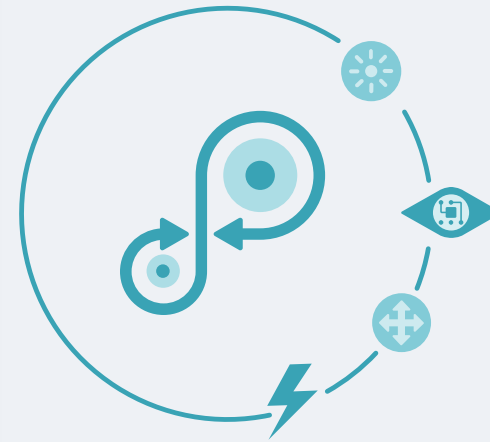
Making video perception ubiquitous

Solving additional
key challenges to
take video perception
from the research lab
to broad commercial
deployment



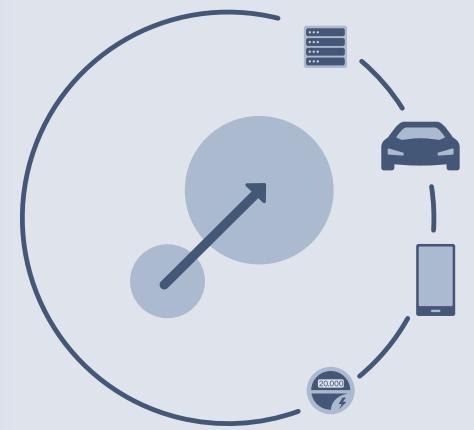
Robustness

Robust to data variations



Adaptability

Adaptable to different domains



Scalability

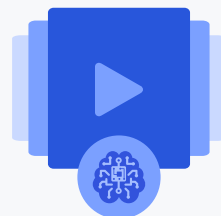
Scaling up and down,
from IoT to the data center



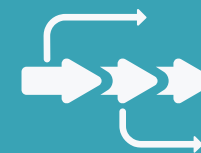
Leverage
**Temporal
redundancy**

By reusing what
is computed before

- Learning to skip regions
- Recycling features



**Key concepts
for efficient
video perception**



Make
**Early
decisions**

By dynamically changing
the network architecture
per input frame

- Early exiting
- Frame exiting

Efficiently running on-device video perception without sacrificing accuracy

Deep learning basics

Computable AI

Data driven learning

- Supervised, unsupervised, semi/self/weak supervised, adversarial

Neural network

- Convolutional neural networks
- Graph neural networks

Regression and classification tasks

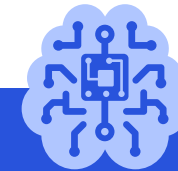
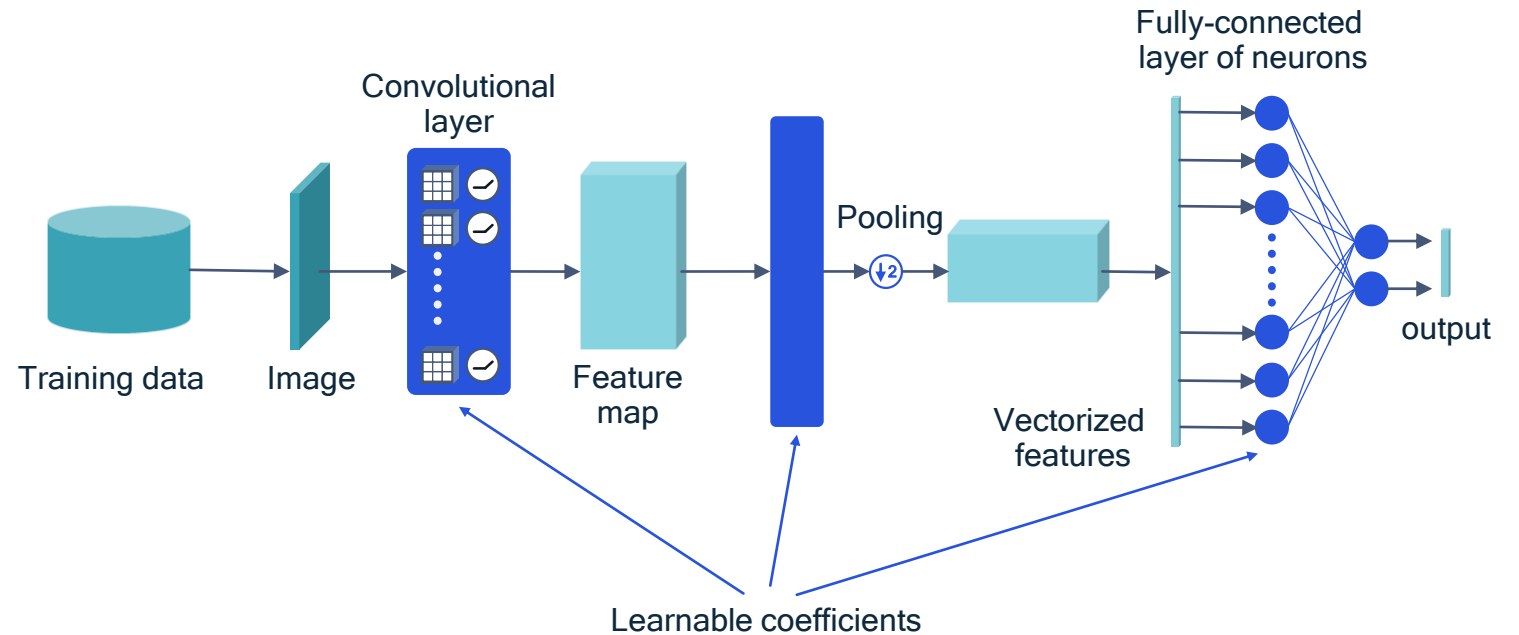
- Minimizing a loss function
- Back-propagation over differentiable layers

Convolutional layers (deep)

Non-linearity, pooling

Kernels, neurons

Feed-forward CNN



Inspired by the workings of the brain,
drawing from data

Learning to skip redundant computations

Video frames are heavily correlated

frame t



frame t+10



residual



“Skip-convolutions for efficient video processing” (submitted 2021)

The residual frame, the difference between two consecutive frames, contains little information in most regions

Limit the computation only to the regions where there are significant changes

Skip-convolution

A convolutional layer with a **skip gate** that masks out negligible residuals

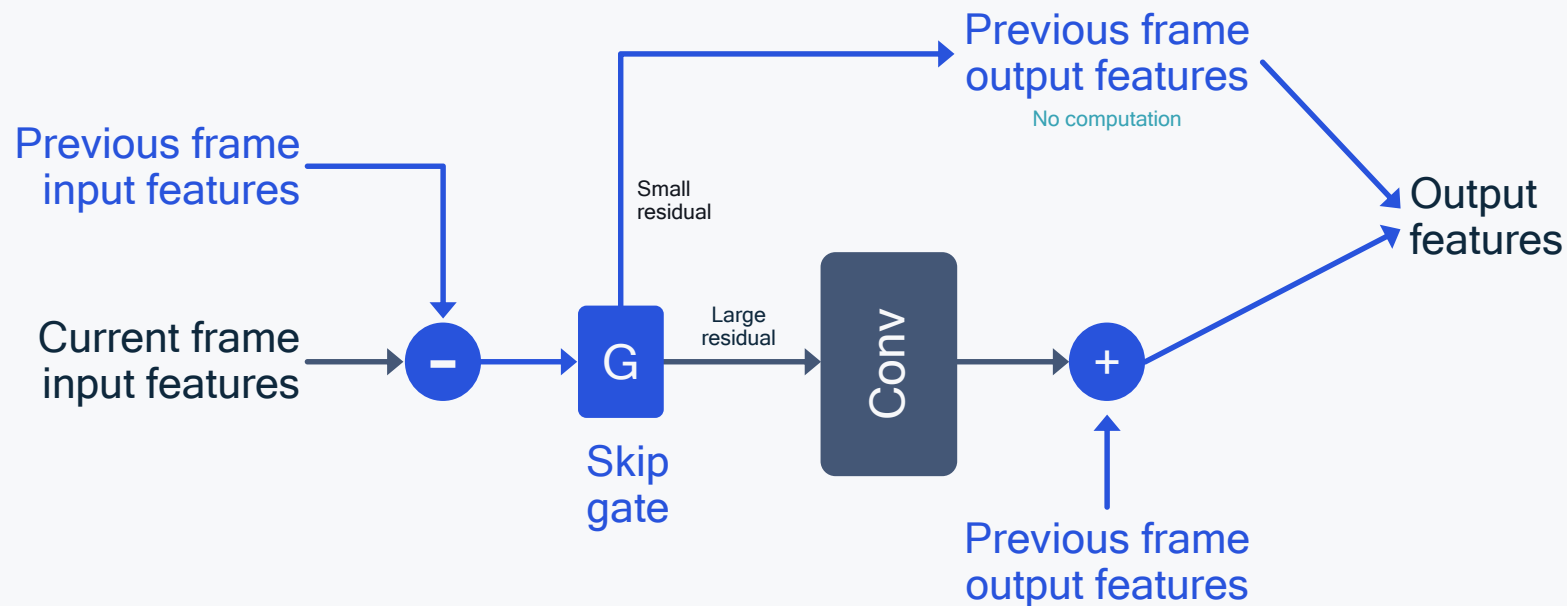
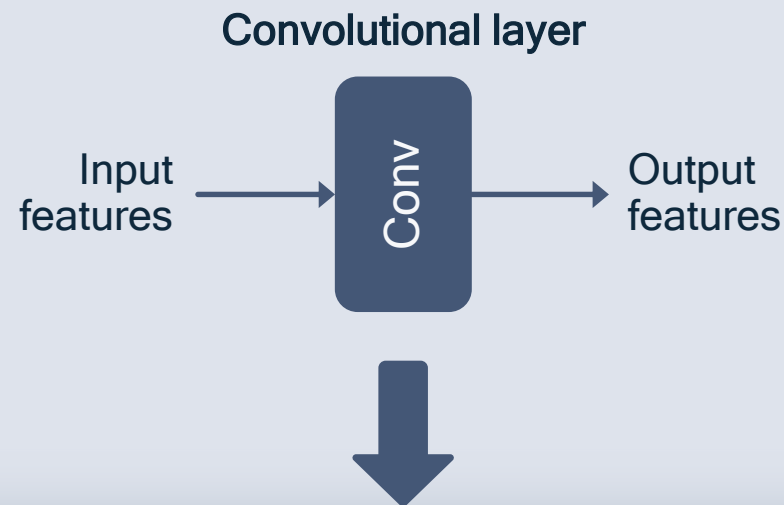
A convolution at a frame can be written as the previous frame's convolution plus the convolution of the residual

Computation is limited only to the regions where there are strong residuals

Reinforce residual's sparsity by removing negligible residuals

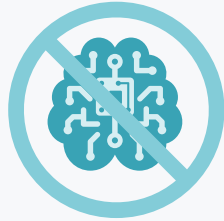
Can replace convolutional layers in any CNN with skip convolutions

"Skip-convolutions for efficient video processing"
(submitted 2021)



Determining the gate for a skip convolution

Can we learn it?



Non-trainable

Based on thresholding
the norm of the
convolved residual

Approximate the norm of output without computing it

Apply a sigmoid function on the
norm of the residual and the weight
of the layer kernel



Trainable

Based on a tiny gating
network that predicts
gate probabilities

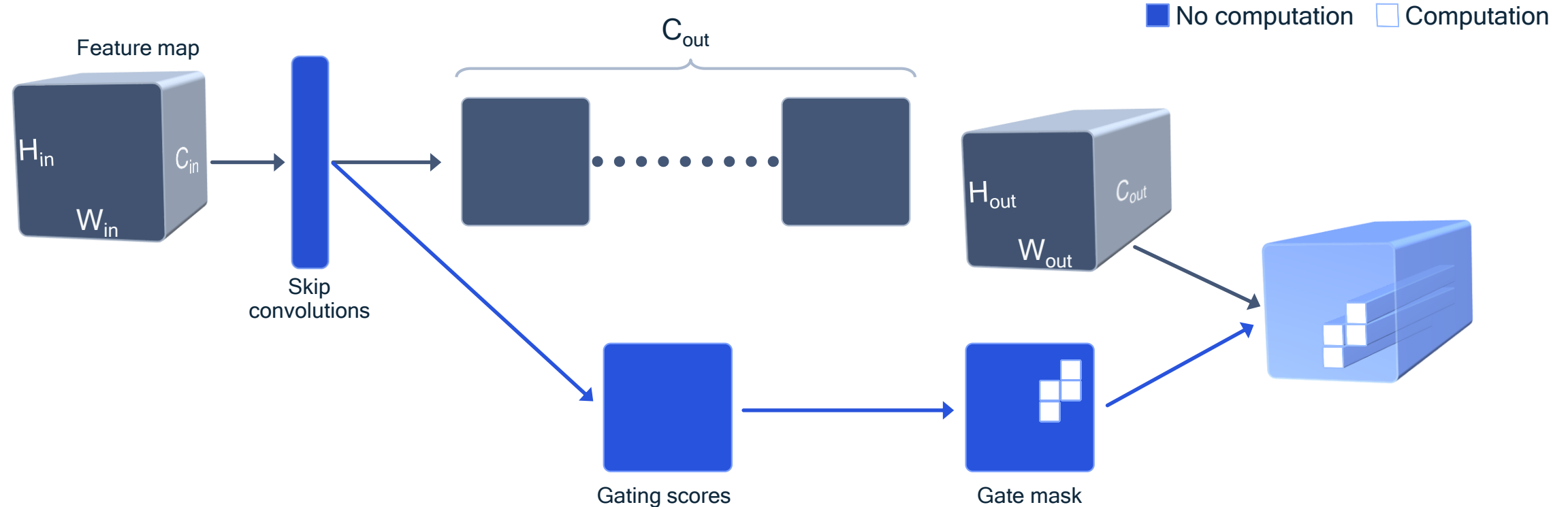
Implement as a convolution with a single output channel

Joint training to minimize
the classification loss and
average active gates

Apply a sigmoid
function to gating
network probabilities

Learned gate requires very low computational overhead

Gate network is an additional output channel



“Skip-convolutions for efficient video processing” (submitted 2021)

Hardware friendly implementation enforced by imposing structured sparsity into compute masks

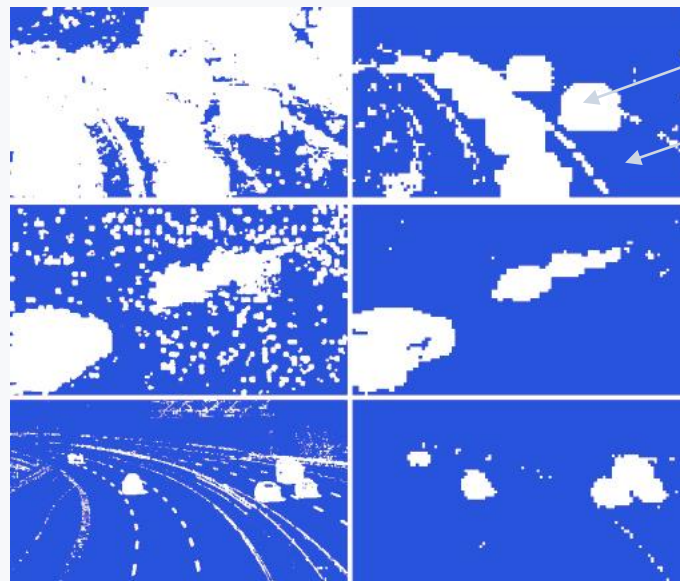
Block-wise structure by down/up sampling

Predicted gating masks reduce computations

Example masks show where computations can be skipped

Gating masks become more selective at deeper layers, concentrating on task specific regions

Larger block-wise structured gates are more selective when training with different sizes

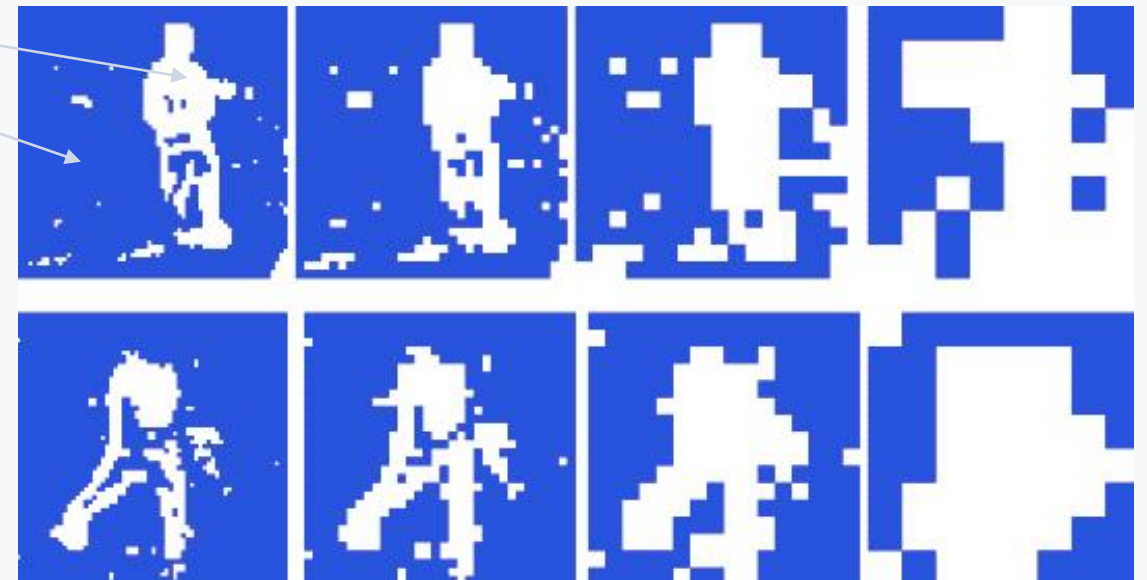


Layer 3

Layer 30

Gating masks for video object detection

Computation
No computation



1x1

2x2

4x4

8x8

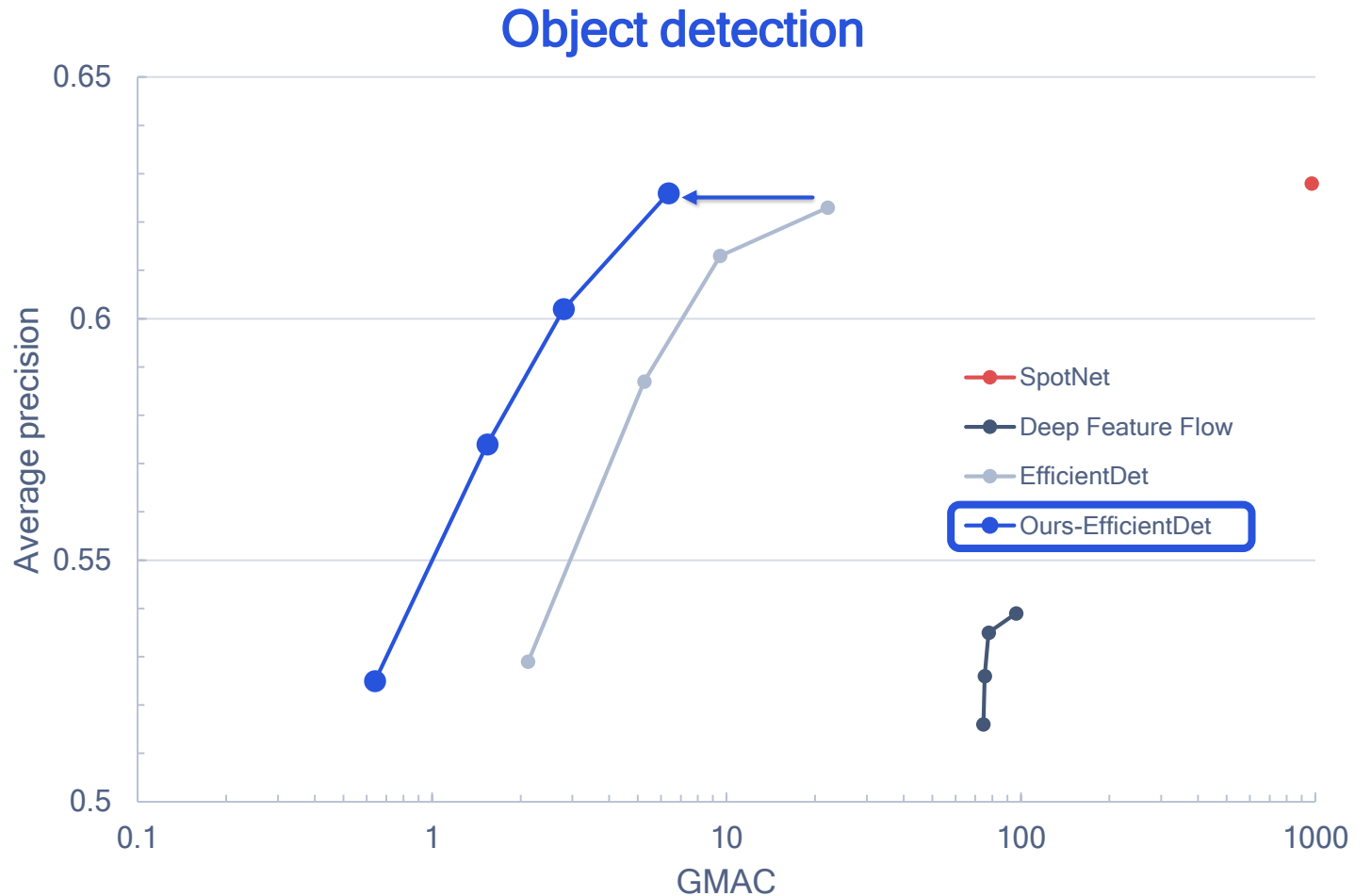
Gating masks for pose estimation

Learning to skip reduces compute and maintains accuracy

Results for object detection on video object detection dataset

3x-5x
speed-up over
state-of-the-art

"Skip-convolutions for efficient video processing"
(submitted 2021)

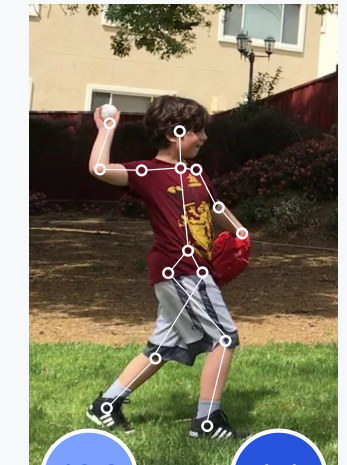
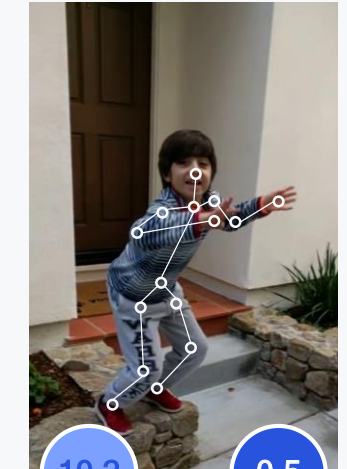
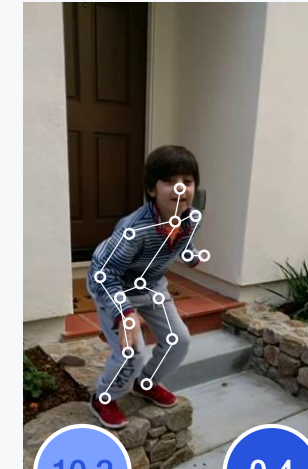


Learning to skip reduces compute for human pose estimation

Results for human pose estimation

● GMACs **without** skip convolutions

● GMACs **with** skip-convolutions

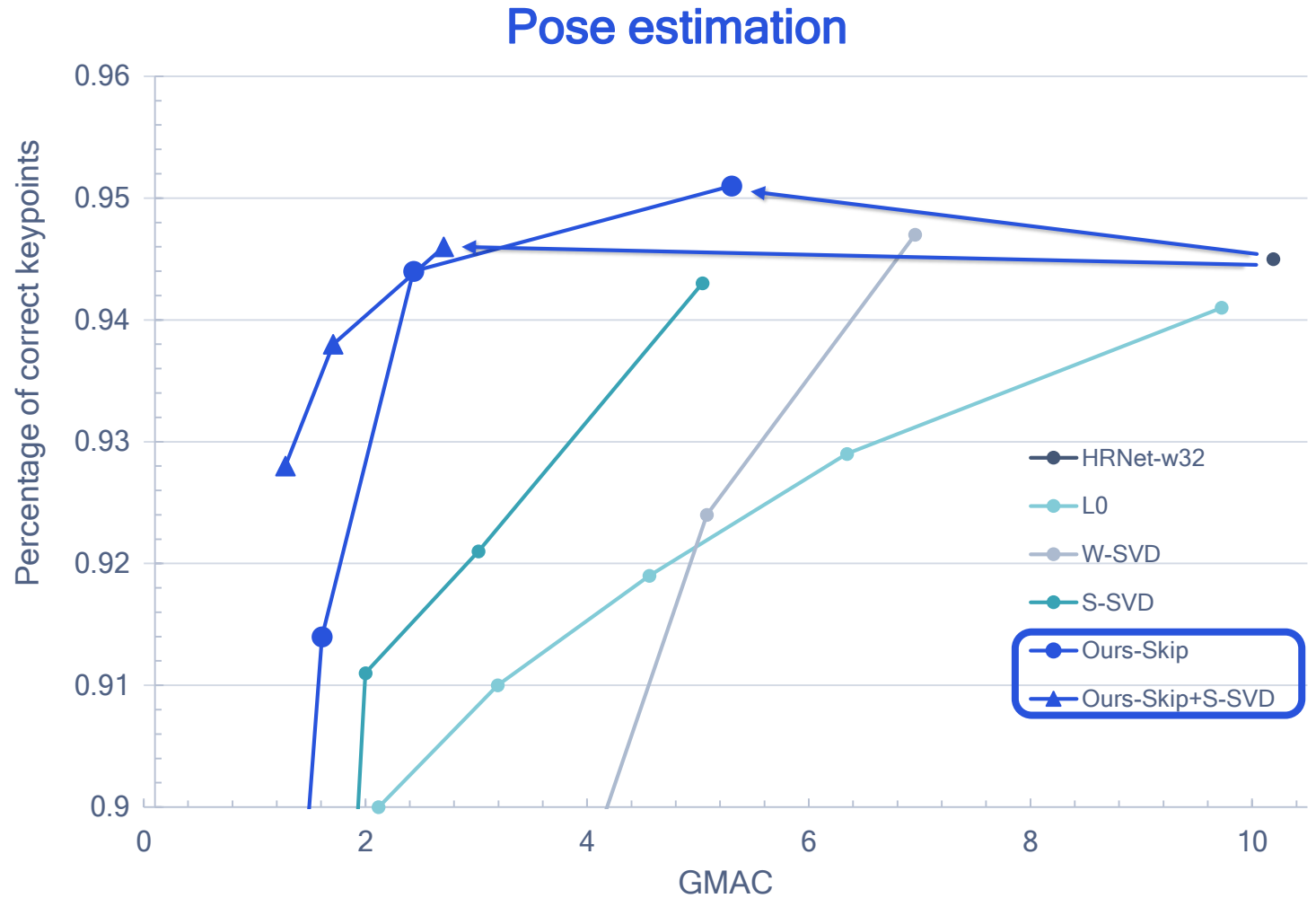


Learning to skip is complementary to model compression

Results for human pose estimation on video human action dataset

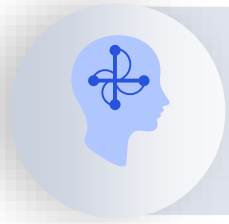
2.5x-8x
speed-up over
HRNet

"Skip-convolutions for efficient video processing"
(submitted 2021)



Recycling features saves compute

Instead of computing deep features repetitively, compute once and recycle



Deep features remain relatively stationary over time – they have lower spatial resolution



Compute deep features once and recycle – reuse from past frame



Shallow features are more responsive to smooth changes, encoding the temporally varying information

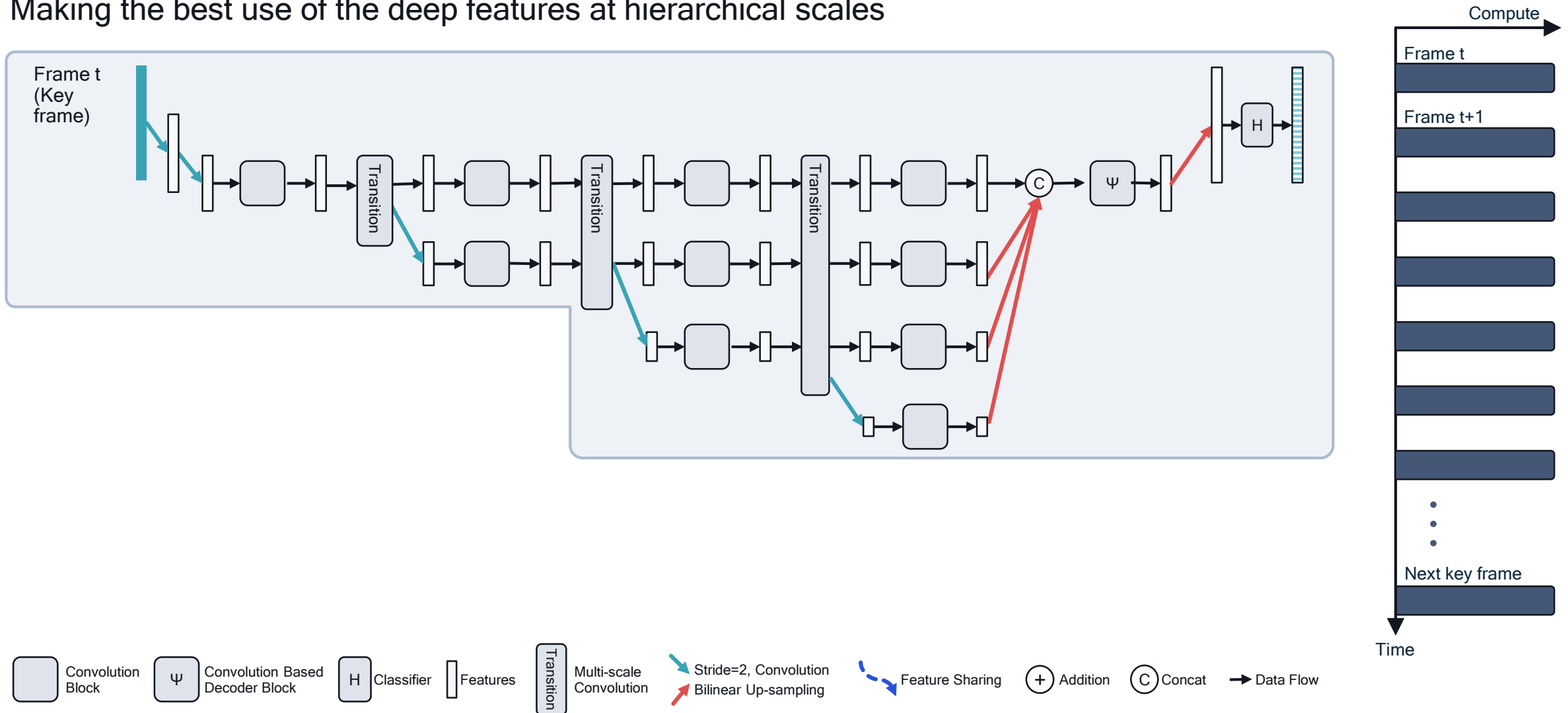


Compute shallow features for all frames

Applicable to any video neural network architectures including segmentation, optical flow, classification, and more

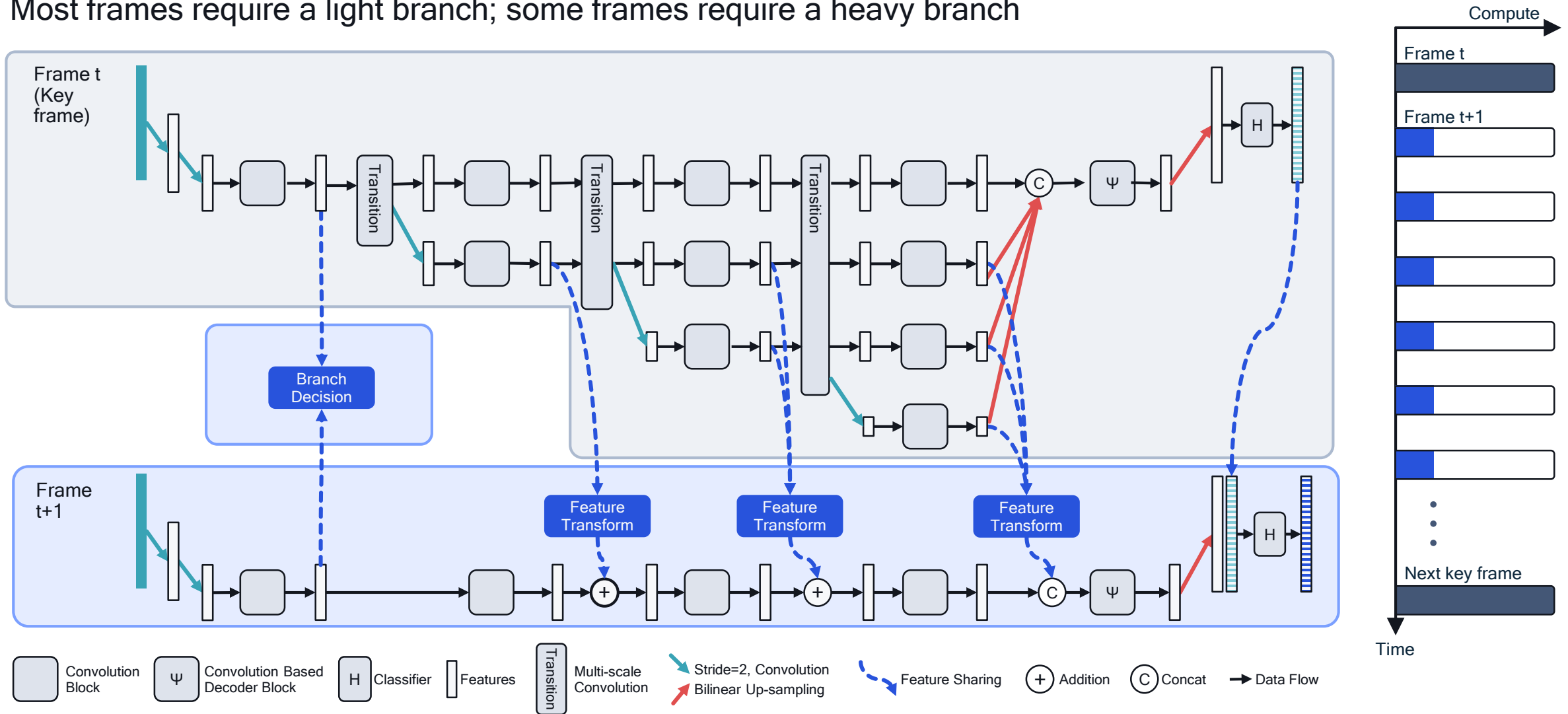
Example of a feature recycling network

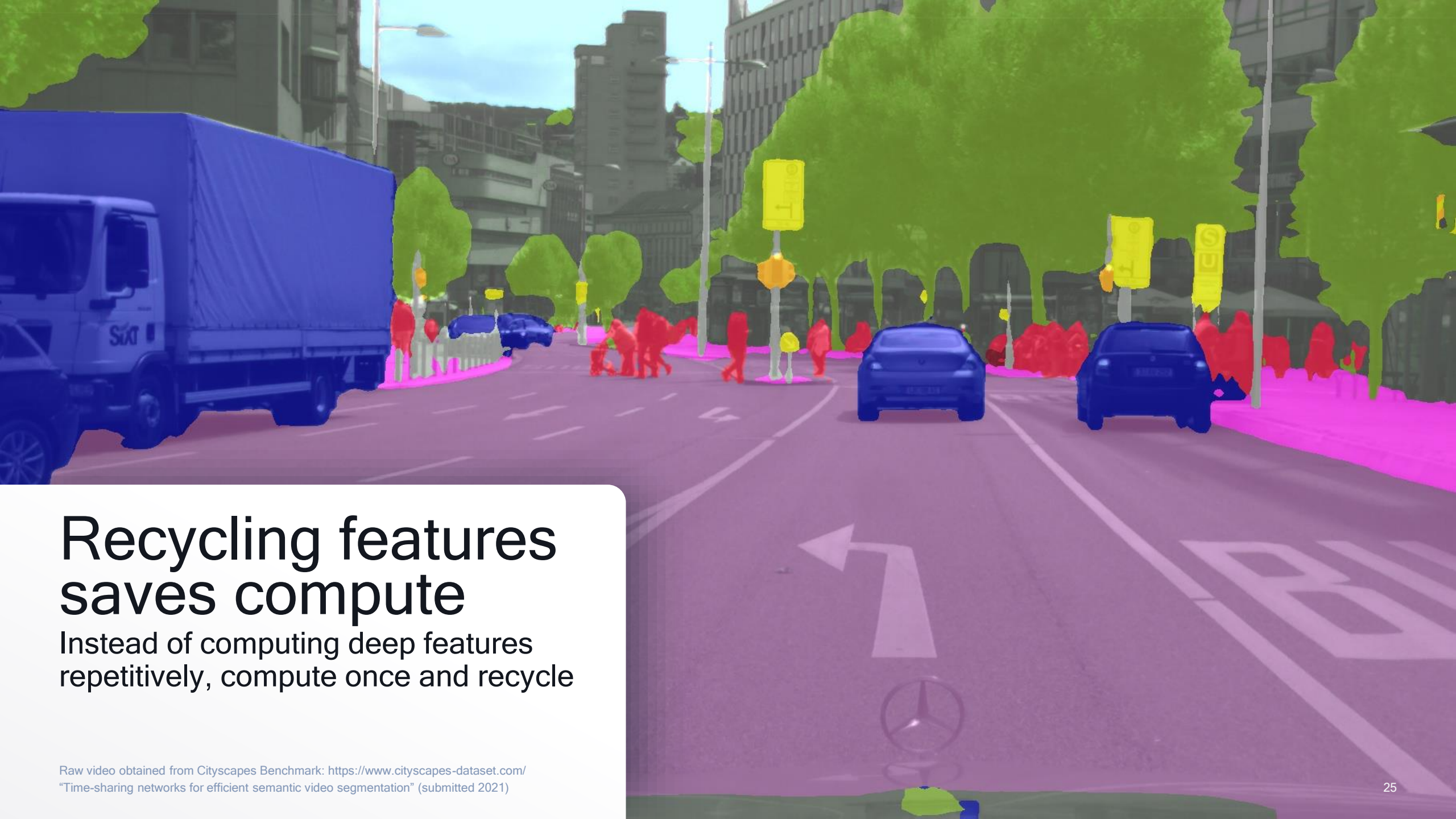
Making the best use of the deep features at hierarchical scales



Example of a feature recycling network

Most frames require a light branch; some frames require a heavy branch





Recycling features saves compute

Instead of computing deep features
repetitively, compute once and recycle



Feature recycling reduces compute and latency

Semantic segmentation example

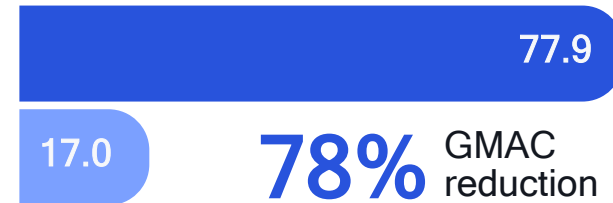
Input:
2048x1024 RGB video

Output:
2048x1024,
19 object classes

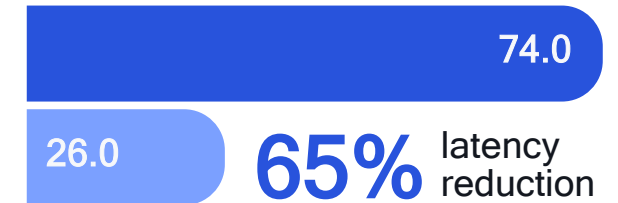
Runs on:
Qualcomm® Snapdragon™ 888
Mobile Platform

Model efficiency

GMACs

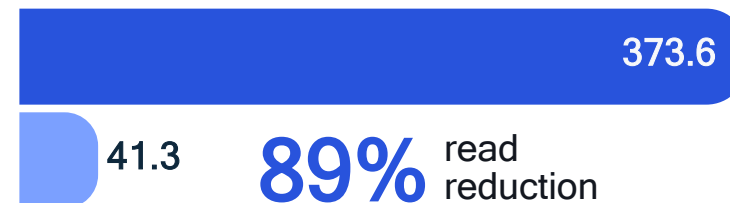


On-device latency (ms/frame)

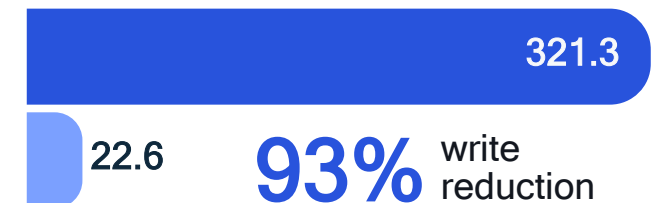


Memory traffic

MB read



MB write



Early exiting a neural network saves compute

Exploit the fact that not all input examples require models of the same complexity



**Complex
examples**



Very large, computationally intensive models are needed to correctly classify



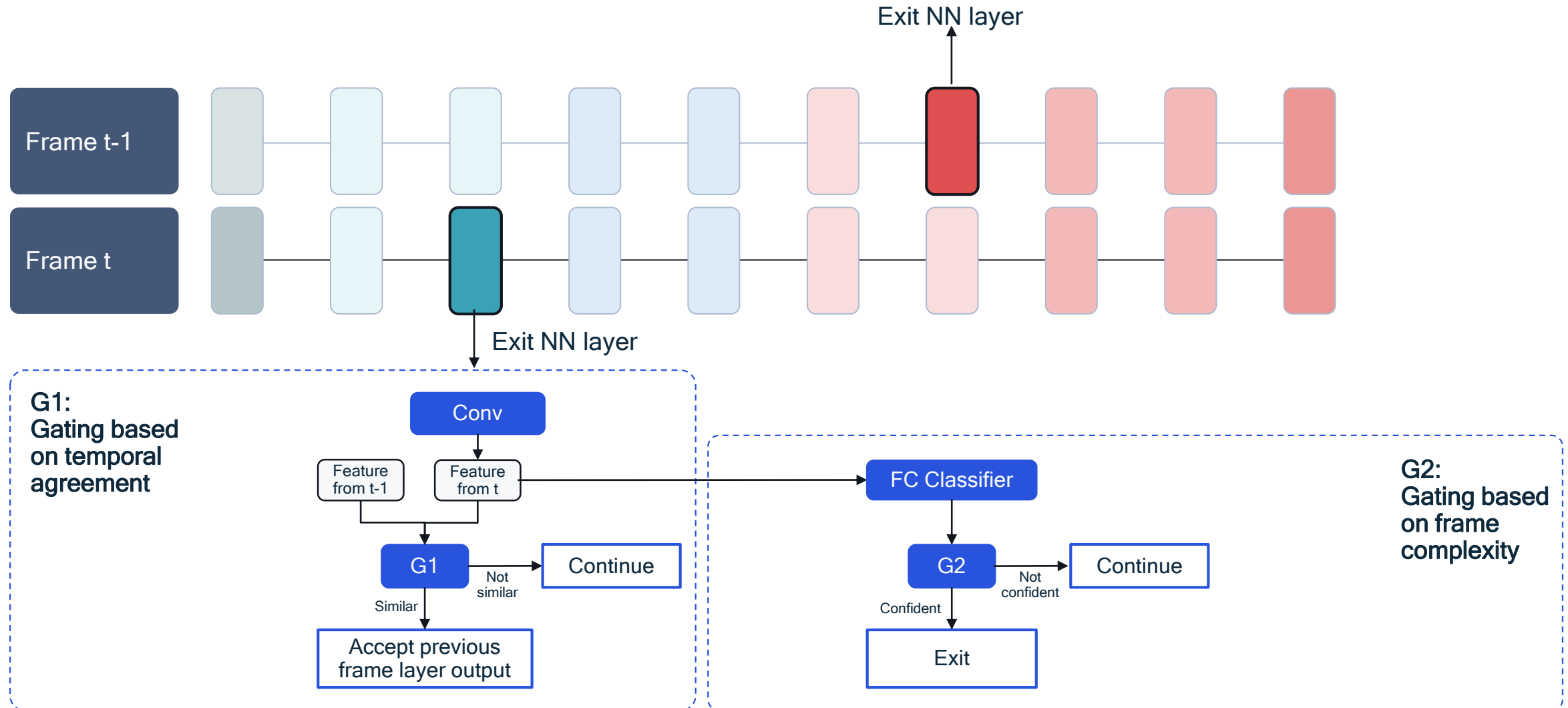
**Simple
examples**



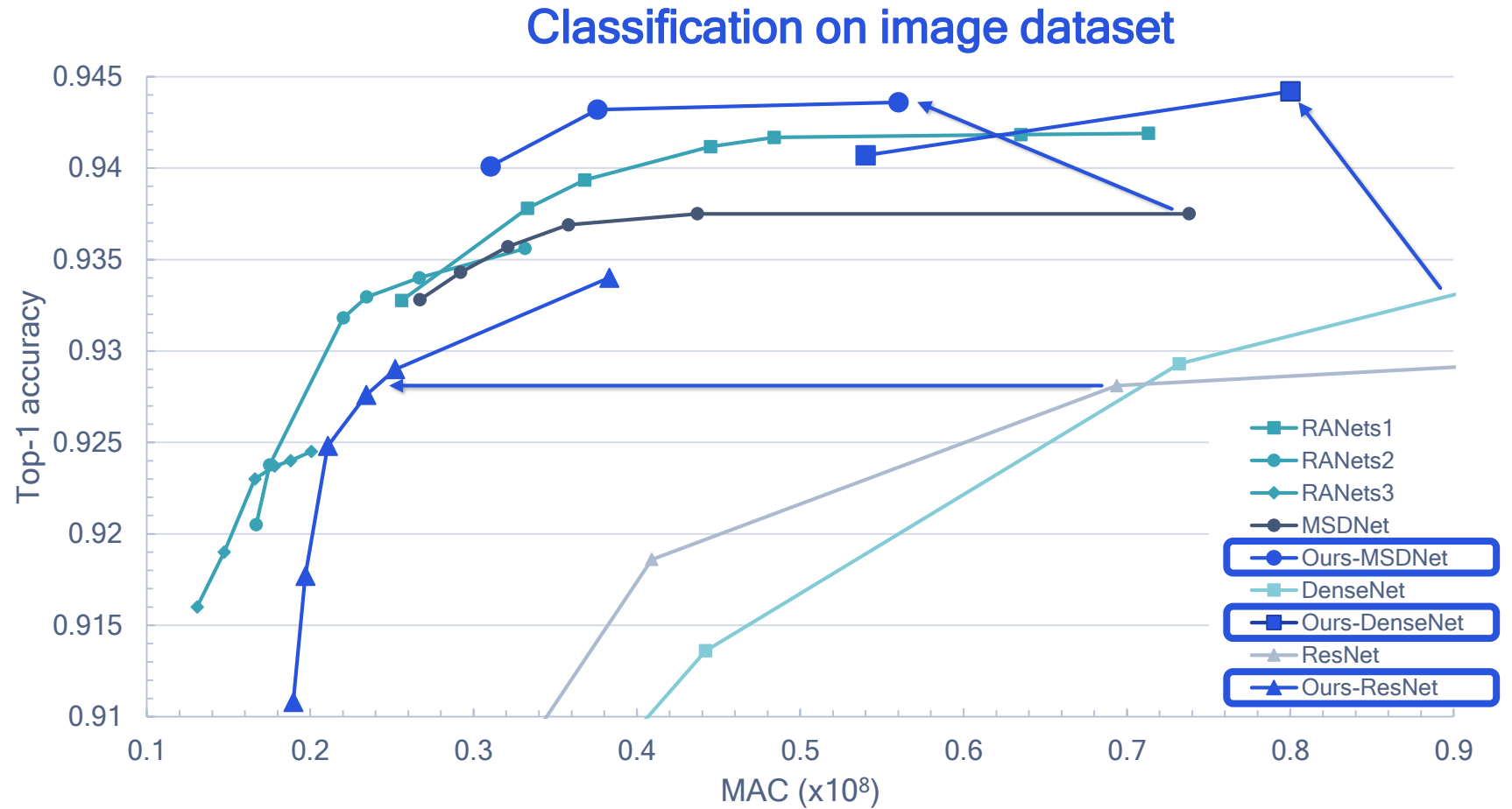
Very small and compact models can achieve very high accuracies, but they fail for complex examples

Ideally, our system should be composed of a cascade of classifiers throughout the network

Early exiting at the earliest possible NN layer for video



Early exiting
applies to most
neural network
backbones

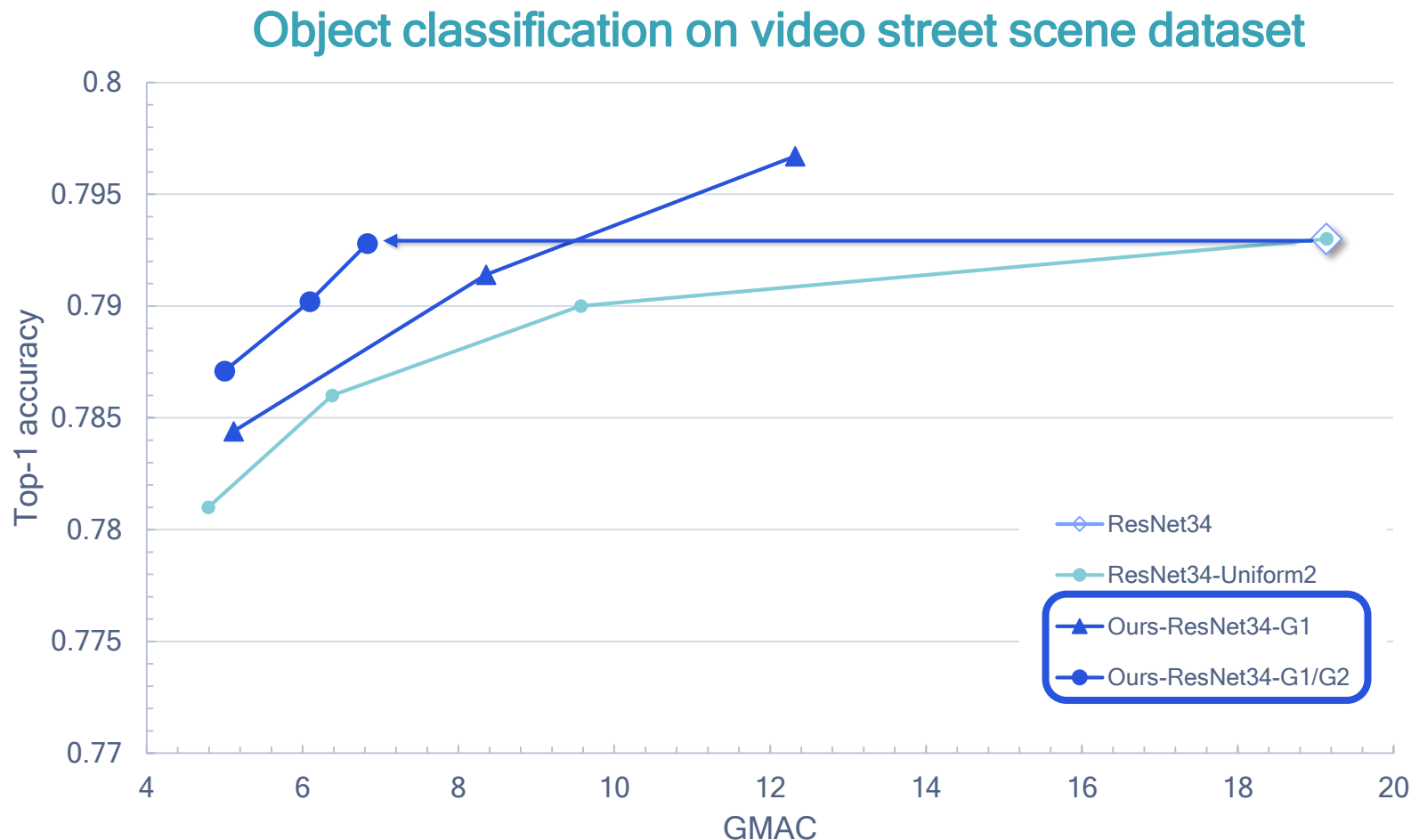


Early exiting reduces compute while maintaining accuracy

Early exiting for object classification

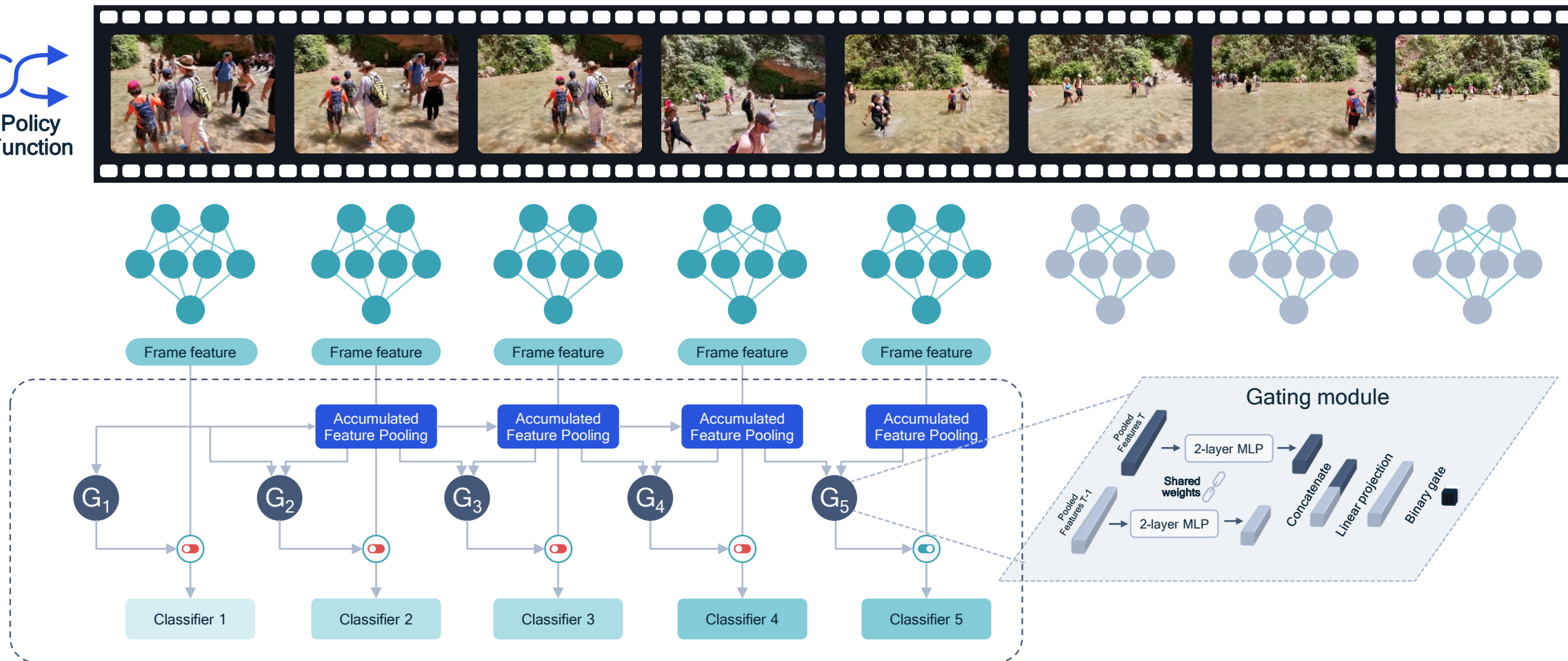
2.5x

less MACs while
maintaining
accuracy

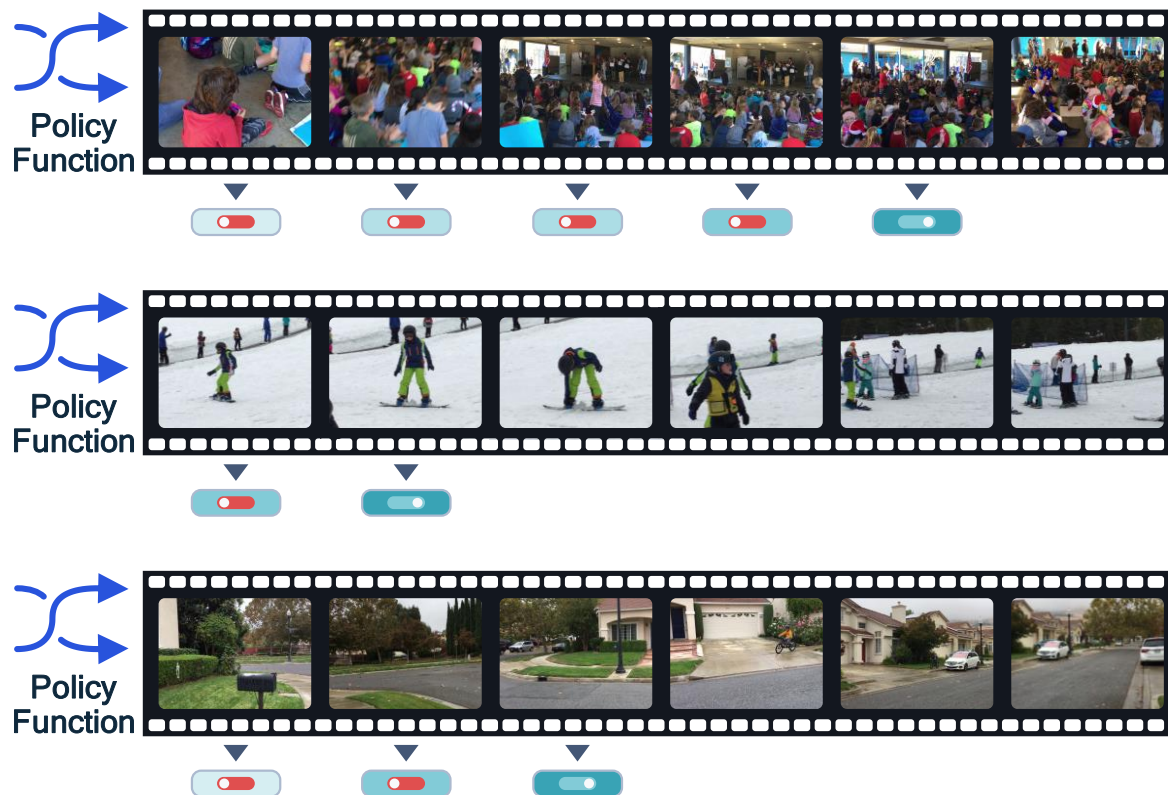


Frame exiting also applies to action recognition tasks

Policy Function



Frame exiting improves accuracy and reduces compute



Methods	Video activity dataset		Video action dataset	
	mAP (%)	GFLOPS	Top-1 (%)	GFLOPS
<i>Resnet</i>				
AdaFrame	71.5	79.0	—	—
LiteEval	72.7	95.1	61.0	99.0
ListenToLook	72.3	81.4	—	—
SCSampler	72.9	41.9	70.8	41.9
AR-Net	73.8	33.5	71.7	32.0
★ FrameExit	76.1	25.2	72.8	19.7
<i>EfficientNet</i>				
AR-Net	79.7	15.3	74.8	16.3
★ FrameExit	80.0	11.4	75.3	7.8

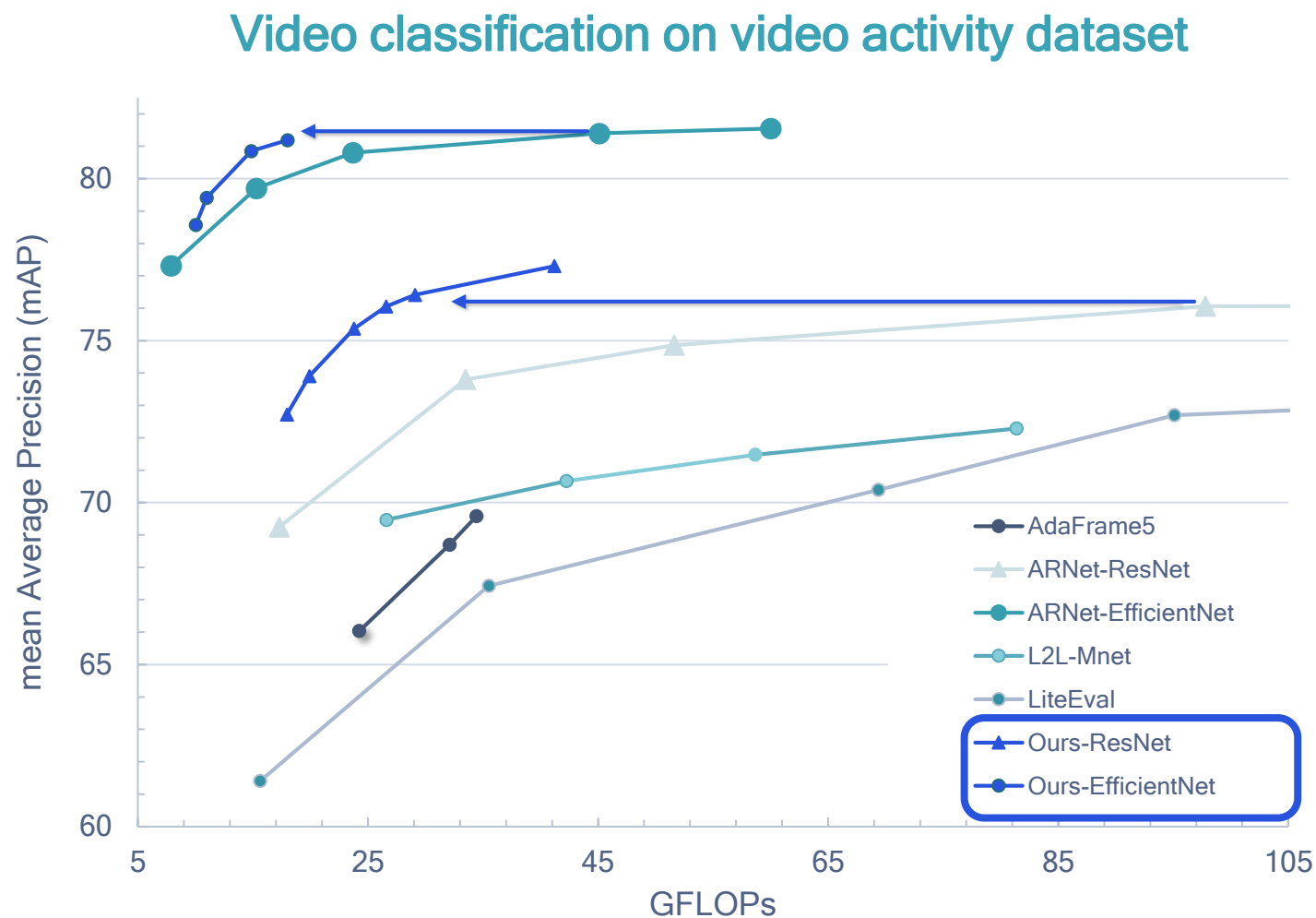
	mAP (%)	GFLOPS
<i>2d/3d Resnet</i>		
Video human action dataset		
Uniform-10	44.7	41.2
Random-10	43.6	41.2
3D-ResNet18	35.4	38.6*
HATNet	39.6	41.8*
★ FrameExit (Efficient)	45.7	8.6
★ FrameExit (Accurate)	49.2	18.7

By adding gates to the NN architecture, deeper layers concentrate on the difficult decisions while earlier layers solve all the easy issues

Frame exiting for video classification

1.3x-5x

less GFLOPs while
maintaining
accuracy



Advance existing conditional compute techniques

Learning to skip regions

Recycling features

Early exiting

Frame exiting



Future work in video perception

Develop efficient video neural network solutions

Unsupervised / semi-supervised learning

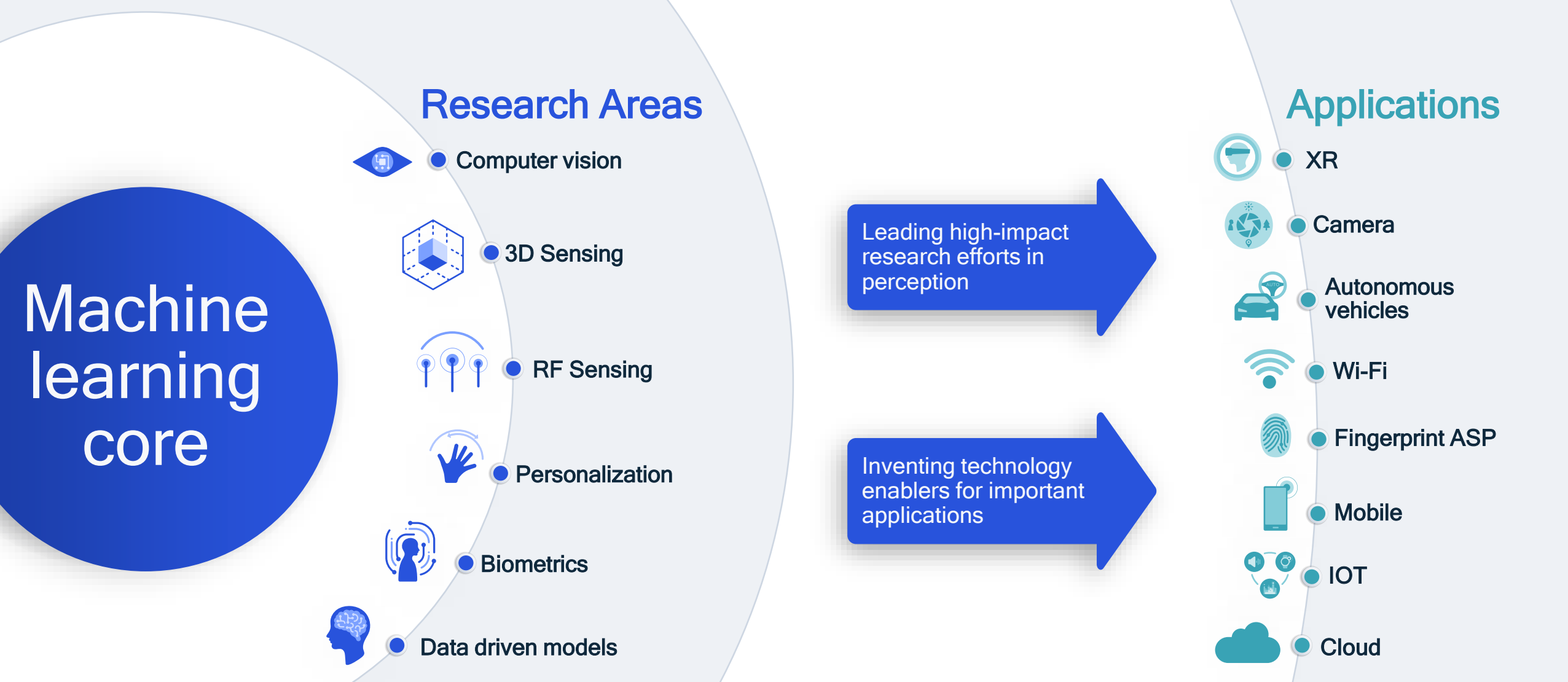
Efficient sparse convolutions

Personalization

Multi-task networks

Quantization aware training

Platform optimizations



Our perception research is much broader than video



Qualcomm

Video perception is crucial for understanding the world and making devices smarter

We are conducting leading research and development in video perception

We are making power efficient video perception possible without sacrificing accuracy

Questions?

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